



Allen-Bradley

ControlLogix Analog I/O Modules

**1756-IF16, -IF6CIS, -IF6I, -IF8, -IR6I,
-IT6I, -IT6I2, -OF4, -OF6CI, -OF6VI,
-OF8**

User Manual

**Rockwell
Automation**

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Introduction

This release of this document contains updated information. Changes are designated by change bars in margin, as shown.

New and Revised Information

Table Summary of Changes.1 lists the new and revised information included in this release of the ControlLogix digital I/O modules user manual.

Table Summary of Changes.1 New and Revised Information

In this section:	This information changed or was added:
Chapter 2	Triggering Event Tasks
Chapter 3	<ul style="list-style-type: none"> • Electronic Keying • 1756-IF6I module count information in integer mode
Module-specific chapters (i.e. Chapter 4 through Chapter 8)	Module block diagrams and input/output circuit diagrams
Chapter 5	Full description of ControlLogix Sourcing Current Loop Input Module (1756-IF6CIS)
Chapter 6	<ul style="list-style-type: none"> • Full description of ControlLogix Thermocouple Input Module (1756-IT6I2) • Wire Off Detection with the 1756-IR6I module
Appendix A	<ul style="list-style-type: none"> • Specifications for 1756-IF6CIS module • Specifications for 1756-IT6I2 module • Updated Open Circuit Detection specification for the 1756-IR6I module
Appendix C	Differences when using message instructions in RSLogix™ 5000, v 9 or earlier versus using RSLogix 5000, v10 or greater.
Appendix E	Additional specification information
Glossary	After Appendix C

Other changes have been made throughout this manual and, although not significant enough to warrant mention in the table above, they are marked by change bars.

Notes:

About This User Manual

What This Preface Contains This preface describes how to use this manual. The following table describes what this preface contains and its location.

For information about:	See page:
Who Should Use This Manual	Preface-1
Purpose of This Manual	Preface-1
Related Products and Documentation	Preface-3

Who Should Use This Manual

You must be able to program and operate a Rockwell Automation ControlLogix controller to efficiently use your analog I/O modules.

We assume that you know how to do this in this manual. If you do not, refer to the Logix5000 Controller documentation before you attempt to use this module. Table Preface.2 lists related documentation.

Purpose of This Manual

This manual describes how to install, configure, and troubleshoot your ControlLogix analog I/O module.

What This Manual Contains Table Preface.1 lists describes the sections contained in this manual.

Table Preface.1

Section:	Title:	Description:
Chapter 1	What Are ControlLogix Analog I/O Modules?	A general overview of the ControlLogix analog I/O modules and how they are used
Chapter 2	Analog I/O Operation Within the ControlLogix System	Description of how ControlLogix analog I/O modules work with in a ControlLogix system
Chapter 3	Using ControlLogix Analog I/O Module Features	Listing of the features that are common to all ControlLogix analog I/O modules
Chapter 4	Non-Isolated Analog Voltage/Current Input Modules (1756-IF16, -IF8)	Listing of the features that are specific to the 1756-IF16 and 1756-IF8 modules
Chapter 5	Sourcing Current Loop Input Module (1756-IF6CIS) and Isolated Analog Voltage/Current Input Module (1756-IF6I)	Listing of the features that are specific to the 1756-IF6CIS and 1756-IF6I modules
Chapter 6	Temperature Measuring Analog Modules (1756-IR6I, 1756-IT6I & 1756-IT6I2)	Listing of the features that are specific to the 1756-IR6I and 1756-IT6I modules
Chapter 7	Non-Isolated Analog Output Modules (1756-OF4 & 1756-OF8)	Listing of the features that are specific to the 1756-OF4 and 1756-OF8 modules.
Chapter 8	Isolated Analog Output Modules (1756-OF6CI & 1756-OF6VI)	Listing of the features that are specific to the 1756-OF6CI and 1756-OF6VI modules
Chapter 9	Installing ControlLogix I/O Modules	Step-by-step description of how to install and wire ControlLogix analog I/O modules
Chapter 10	Configuring ControlLogix Analog I/O Modules	Description of how to configure ControlLogix analog I/O modules with RSLogix 5000™
Chapter 11	Calibrating the ControlLogix Analog I/O Modules	Description of how to calibrate ControlLogix analog I/O modules with RSLogix 5000
Chapter 12	Troubleshooting Your ControlLogix Analog I/O Module	Description of how to use LED status indicators and RSLogix 5000 to troubleshoot any problems with your ControlLogix analog I/O modules
Appendix A	Specifications	Listing of all modules' specifications
Appendix B	Tag Definitions	Description of how to use the RSLogix 5000 tag editor to change a module's configuration
Appendix C	Using Ladder Logic To Perform Run Time Services and Reconfiguration	Description of uses for ladder logic in your ControlLogix analog I/O module applications
Appendix D	Power Supply Sizing Chart	Information necessary to check the power your ControlLogix chassis is using.

Related Products and Documentation

The following table lists related ControlLogix products and documentation:

Table Preface.2
Related Documentation

Catalog number:	Document title:	Publication number:
1756-A4, -A7, -A10, -A13	ControlLogix Chassis Installation Instructions	1756-IN080
1756-PA72/B, -PB72/B	ControlLogix Power Supply Installation Instructions	1756-5.67
1756-PA75, -PB75	ControlLogix Power Supply Installation Instructions	1756-5.78
1756-Series	ControlLogix Module Installation Instructions (Each module has separate installation document.)	Multiple 1756-IN numbers
1756-Series	ControlLogix Digital I/O Modules User Manual	1756-UM058
1756-CNB, -CNBR	ControlLogix ControlNet™ Interface Module User Manual	1756-6.5.3
1756-DNB	ControlLogix DeviceNet Interface Module User Manual	1756-6.5.19
1756-DHRIO	ControlLogix Data Highway Plus Communication Interface Module User Manual	1756-UM514
1756-ENET	ControlLogix Ethernet Communication Interface Module User Manual	1756-UM051
1756-ENBT	ControlLogix EtherNet/IP™ Bridge Module User Manual	1756-UM050
1756-IF4FXOF2F	ControlLogix High Speed Analog I/O Module User Manual	1756-UM005
1756-Lx	ControlLogix Selection Guide	1756-SG001
1756-Lx	ControlLogix System User Manual	1756-UM001
1756-Lx, 1769-Lx, 1789-Lx, 1794-Lx, PowerFlex 700S	Logix5000 Controllers Quick Reference	1756-QR107
1756-Lx, 1769-Lx, 1789-Lx, 1794-Lx, PowerFlex 700S	Logix5000 Controllers Common Procedures Programming Manual	1756-PM001
1756-Lx, 1769-Lx, 1789-Lx, 1794-Lx, PowerFlex 700S	Logix5000 Controllers Motion Instruction Set Reference Manual	1756-RM007
1756-Lx, 1769-Lx, 1789-Lx, 1794-Lx, PowerFlex 700S	Logix5000 Controllers General Instructions Reference Manual	1756-RM003
Allen-Bradly I/O catalog numbers	I/O Products System Overview	CIG-S0001

For more information on these products, contact your local Rockwell Automation distributor or sales office.

The documentation listed in Table Preface.2 is available at the following locations:

- <http://www.ab.com/manuals/cl>
- <http://www.theautomationbookstore.com>

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Appendix F**Using 1492 Wiring Systems with
Your Analog I/O Module****Glossary****Index**

What Are ControlLogix Analog I/O Modules?

What This Chapter Contains This chapter describes the ControlLogix analog modules and what you must know and do before you begin to use them.

For information about:	See page:
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Using an I/O Module in the ControlLogix System	1-3
Features of the ControlLogix Analog I/O Modules	1-4
Using Module Identification and Status Information	1-5
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Removal and Insertion Under Power	1-6

What are ControlLogix Analog I/O Modules?

ControlLogix analog I/O modules are interface modules that convert analog signals to digital values for inputs and convert digital values to analog signals for outputs. Controllers can then use these signals for control purposes.

Using the producer/consumer network model, ControlLogix analog I/O modules produce information when needed while providing additional system functions.

Table 1.1 lists the features available on ControlLogix analog I/O modules that allow greater system applicability.

Table 1.1 ControlLogix Analog I/O Module Features

Feature:	Description:
Removal and insertion under power (RIUP)	This system feature allows you to remove and insert modules and RTB while power is applied. For more information on RIUP, see page 1-6.
Producer/consumer communications model	These communications are an intelligent data exchange between modules and other system devices in which each module produces data without having been polled.
Rolling timestamp of data	15-bit module-specific rolling timestamp with millisecond resolution which indicates when data was sampled/applied. This timestamp may be used to calculate the interval between channel or field side updates
Multiple data formats	Analog I/O modules offer the option of IEEE 32-bit floating point or 16-bit integer data formats.
Module resolution	Analog input modules use 16-bit resolution, and analog output modules offer 13 to 16-bit output resolution, depending on the module type, to detect data changes.
On-board features	Features such as scaling to engineering units, alarming and under/overrange detection increase the modules' complexity and effectiveness.
Calibration	ControlLogix analog I/O module ships from the factory with factory calibration. You can recalibrate the module calibration on a channel-by-channel or module-wide basis to increase accuracy in customer-specific applications, if necessary.
Coordinated System Time (CST) timestamp of data	64-bit system clock (i.e. Coordinated System Time [CST]) places a timestamp on the transfer of data between the module and its owner-controller within the local chassis
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	<p>Full agency certification for in any application that requires approval of the agencies listed.</p> <p>Agency certification varies depending on catalog number. To see a complete listing of the certifications associated with each catalog number, see Appendix A.</p>

Using an I/O Module in the ControlLogix System

ControlLogix modules mount in a ControlLogix chassis and use a Removable Terminal Block (RTB) or a Bulletin 1492 Interface Module⁽¹⁾ cable that connects to an IFM to connect all field-side wiring. Before you install and use your module you should have already:

- installed and grounded a 1756 chassis and power supply⁽²⁾. To install these products, refer to the publications listed in Table Preface.2 on page Preface-3.
- ordered and received an RTB or IFM and its components for your application.

IMPORTANT

RTBs and IFMs are not included with your module purchase.

Table 1.2 Types of ControlLogix Analog I/O

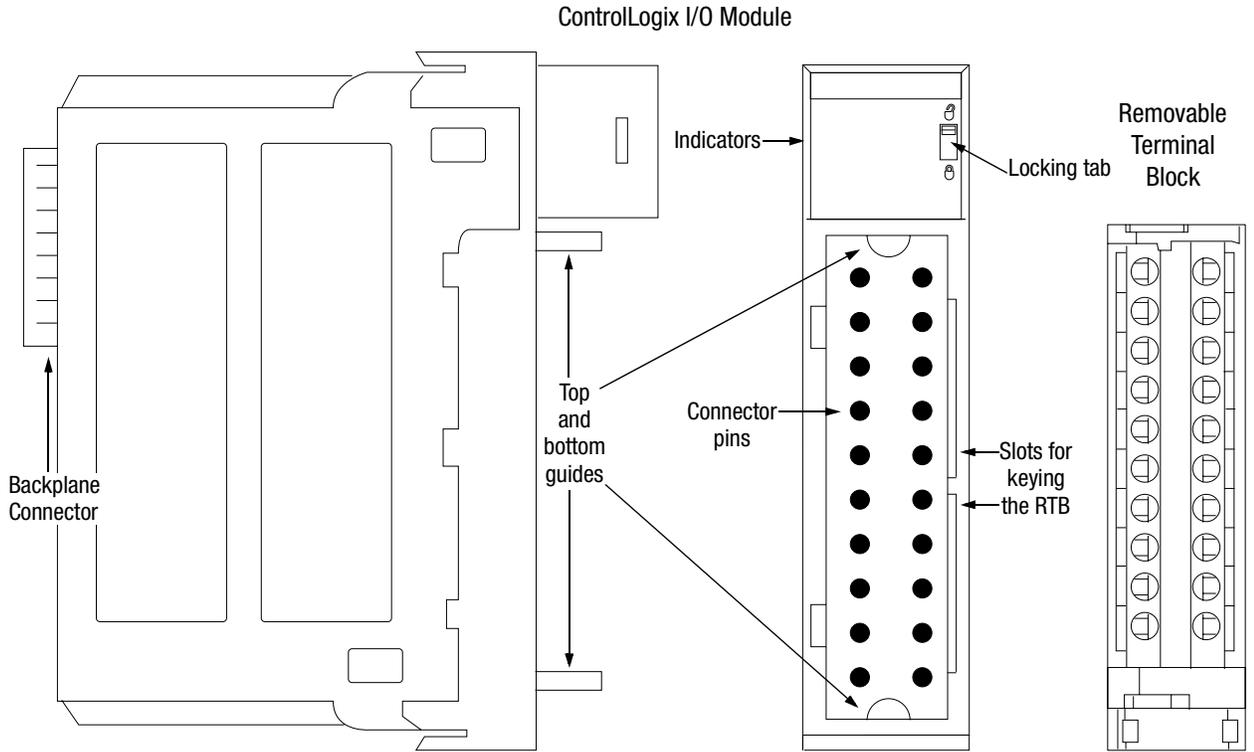
Catalog Number:	Description:	RTB Used:	Module Specific Information in Section:
1756-IF16	16-point non-isolated analog current/voltage input module	36 pin	Chapter 4
1756-IF8	8-point non-isolated analog current/voltage input module	36 pin	
1756-IF6CIS	6-point sourcing current loop input module	20 pin	Chapter 5
1756-IF6I	6-point isolated analog current/voltage input module	20 pin	
1756-IR6I	6-point isolated RTD input module	20 pin	Chapter 6
1756-IT6I	6-point isolated Thermocouple/mV input module	20 pin	
1756-IT6I2	6-point isolated Enhanced Thermocouple/mV input module	20 pin	
1756-OF4	4-point non-isolated analog current/voltage output module	20 pin	Chapter 7
1756-OF8	8-point non-isolated analog current/voltage output module	20 pin	
1756-OF6CI	6-point isolated analog current output module	20 pin	Chapter 8
1756-OF6VI	6-point isolated analog voltage output module	20 pin	

⁽¹⁾ The Bulletin 1492 IFM may not be used in any application that requires agency certification of the ControlLogix system. Use of the IFM violates the UL, CSA and FM certifications of a ControlLogix digital I/O module. Also, to see what IFMs are used with each ControlLogix analog I/O module, see Appendix F.

⁽²⁾ In addition to standard ControlLogix power supplies, ControlLogix Redundant Power Supplies are also available for your application. For more information on these supplies see the ControlLogix Selection Guide, publication 1756-SG001 or contact your local Rockwell Automation distributor or sales representative.

Features of the ControlLogix Analog I/O Modules

Figure 1.1



40200-M

Table 1.3 lists descriptions of the physical features shown in Figure 1.1.

Table 1.3 Physical Features on the ControlLogix Digital I/O Modules

Physical Feature:	Description:
Backplane connector	The backplane connector interface for the ControlLogix system connects the module to the ControlBus backplane.
Connector pins	Input/output, power and grounding connections are made to the module through these pins with the use of an RTB or IFM.
Locking tab	The locking tab anchors the RTB or IFM cable on the module, maintaining wiring connections.
Slots for keying	Mechanically keys the RTB to prevent inadvertently making the wrong wire connections to your module.
Status indicators	Indicators display the status of communication, module health and input/output devices. Use these indicators to help in troubleshooting.
Top and bottom guides	Guides provide assistance in seating the RTB or IFM cable onto the module.

Using Module Identification and Status Information

Each ControlLogix I/O module maintains specific identification information that separates it from all other modules. This information assists you in tracking all the components of your system.

For example, you can track module identification information to be aware of exactly what modules are located in any ControlLogix rack at any time. While retrieving module identity, you can also retrieve the module's status.

Each module maintains the following information:

Table 1.4 Module Identification and Status Information

Module Identification:	Description:
Product Type	Module's product type, such as Digital I/O or Analog I/O module
Catalog Code	Module's catalog number
Major Revision	Module's major revision number
Minor Revision	Module's minor revision number
Status	Module's status. Returns the following information: <ul style="list-style-type: none"> • Controller ownership (if any) • Whether module has been configured • Device Specific Status, such as: <ul style="list-style-type: none"> • Self-Test • Flash update in progress • Communications fault • Not owned (outputs in program mode) • Internal fault (need flash update) • Run mode • Program mode (output mods only) • Minor recoverable fault • Minor unrecoverable fault • Major recoverable fault • Major unrecoverable fault
Vendor ID	Module manufacturer vendor, for example Allen-Bradley
Serial Number	Module serial number
Length of ASCII Text String	Number of characters in module's text string
ASCII Text String	Number of characters in module's text string

IMPORTANT

You must perform a WHO service to retrieve this information.

Preventing Electrostatic Discharge

This module is sensitive to electrostatic discharge.

ATTENTION



This equipment is sensitive to electrostatic discharge, which can cause internal damage and affect normal operation. Follow these guidelines when you handle this equipment:

- Touch a grounded object to discharge potential static.
 - Wear an approved grounding wriststrap.
 - Do not touch connectors or pins on component boards.
 - Do not touch circuit components inside the equipment.
 - If available, use a static-safe workstation.
 - When not in use, store the equipment in appropriate static-safe packaging.
-

Removal and Insertion Under Power

These modules are designed to be installed or removed while chassis power is applied.

WARNING



When you insert or remove the module while backplane power is on, an electrical arc can occur. This could cause an explosion in hazardous location installations.

Be sure that power is removed or the area is nonhazardous before proceeding. Repeated electrical arcing causes excessive wear to contacts on both the module and its mating connector. Worn contacts may create electrical resistance that can affect module operation.

Chapter Summary and What's Next

In this chapter you read about what ControlLogix analog I/O modules are. Chapter 2 describes Analog I/O Operation Within the ControlLogix System.

Analog I/O Operation Within the ControlLogix System

What This Chapter Contains This chapter describes how analog I/O modules work within the ControlLogix system.

For information about:	See page:
Ownership and Connections	2-1
Using RSNetWorx™ and RSLogix 5000	2-2
Direct Connections	2-3
Input Module Operation	2-3
Input Modules in a Local Chassis	2-4
Real Time Sample (RTS)	2-4
Requested Packet Interval (RPI)	2-5
Input Modules in a Remote Chassis	2-7
Output Module Operation	2-9
Output Modules in a Local Chassis	2-9
Output Modules in a Remote Chassis	2-10
Listen-Only Mode	2-12
Multiple Owners of Input Modules	2-13
Configuration Changes in an Input Module with Multiple Owners	2-14

Ownership and Connections

Every I/O module in the ControlLogix system must be owned by a ControlLogix controller to be useful. This owner-controller stores configuration data for every module that it owns and can be located locally or remotely, relative to the I/O module's position. The owner sends the I/O module configuration data to define the module's behavior and begin operation within the control system. Each ControlLogix I/O module must continuously maintain communication with its owner to operate normally.

Typically, each module in the system will have only 1 owner. Input modules can have more than 1 owner. Output modules, however, are limited to a single owner. For more information on the increased flexibility provided by multiple owners and the ramifications of using multiple owners, see page 2-13.

Using RSNetWorx™ and RSLogix 5000

The I/O configuration portion of RSLogix5000 generates the configuration data for each I/O module in the control system, whether the module is located in a local or remote chassis. A remote chassis, also known as networked, contains the I/O module but not the module's owner-controller. Remote chassis can be connected to the controller via a scheduled ControlNet or EtherNet/IP network.

Configuration data is transferred to the controller during the program download and subsequently transferred to the appropriate I/O modules.

I/O modules in the local chassis, and modules in a remote chassis this connected via the EtherNet/IP network, are ready to run as soon as the configuration data has been downloaded. However, you must run RSNetWorx for ControlNet to enable I/O modules in a scheduled ControlNet chassis.

Running RSNetWorx transfers configuration data to I/O modules on scheduled ControlNet and establishes a Network Update Time (NUT) for ControlNet that is compliant with the desired communications options specified for each module during configuration.

Anytime a controller references an I/O module in a scheduled ControlNet chassis, you must run RSNetWorx to configure ControlNet. Follow these general guidelines when configuring I/O modules:

1. Configure all I/O modules for a given controller using RSLogix 5000 and download that information to the controller.
2. If the I/O configuration data references a module in a remote chassis connected by scheduled ControlNet, run RSNetWorx.

IMPORTANT

You **must** run RSNetWorx whenever a new module is added to a scheduled ControlNet chassis. When a module is permanently removed from a remote chassis, we recommend that RSNetWorx be run to optimize the allocation of network bandwidth.

Direct Connections

A **direct connection** is a real-time data transfer link between the controller and the device that occupies the slot that the configuration data references. ControlLogix analog I/O modules use direct connections only.

When module configuration data is downloaded to an owner-controller, the controller attempts to establish a direct connection to each of the modules the data references.

If a controller has configuration data referencing a slot in the control system, the controller periodically checks for the presence of a device there. When a device's presence is first detected, the controller automatically sends the configuration data and one of the following events occurs:

- If the data is appropriate to the module found in the slot, a connection is made and operation begins.
- If the configuration data is not appropriate, the data is rejected and an error message displays in the software. In this case, the configuration data can be inappropriate for any of a number of reasons.

For example, a module's configuration data may be appropriate except for a mismatch in electronic keying that prevents normal operation.

The controller maintains and monitors its connection with a module. Any break in the connection, such as removal of the module from the chassis while under power, causes the controller to set fault status bits in the data area associated with the module. You can use ladder logic to monitor this data area and detect module failures.

Input Module Operation

In traditional I/O systems, controllers poll input modules to obtain their input status. In the ControlLogix system, however, the owner-controller does not poll analog input modules after a connection is established. The modules multicast their data periodically. Multicast frequency depends on the options chosen during configuration and where in the control system that input module physically resides.

An input module's communication, or multicasting, behavior varies depending upon whether it operates in the local chassis or in a remote chassis, based on the network type. The following sections detail the differences in data transfers between these set-ups.

Input Modules in a Local Chassis

When a module resides in the same chassis as the owner-controller, the following two configuration parameters will affect how and when the input module multicasts data:

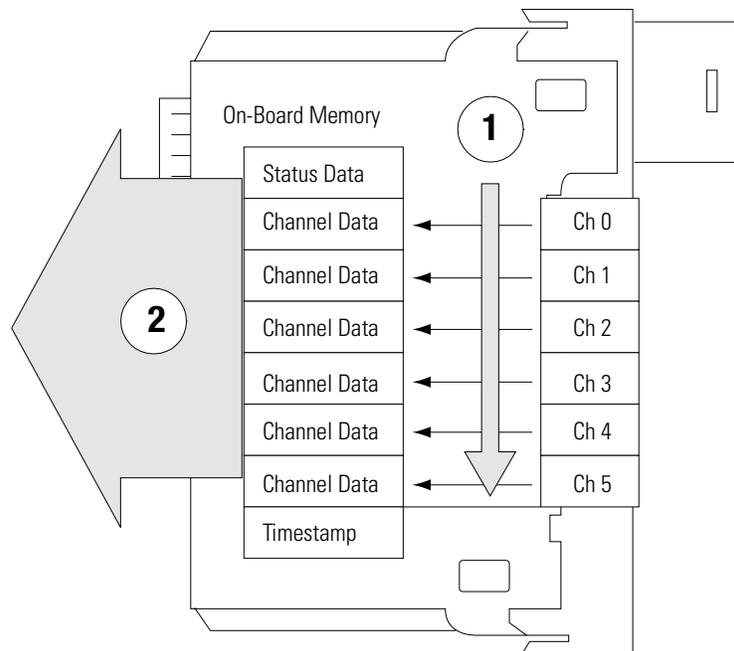
- Real Time Sample (RTS)
- Requested Packet Interval (RPI)

Real Time Sample (RTS)

This configurable parameter instructs the module to perform the following operations:

1. **Scan all** of its input channels and store the data into on-board memory
2. Multicast the updated channel data (as well as other status data) to the backplane of the local chassis

Figure 2.1



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IMPORTANT

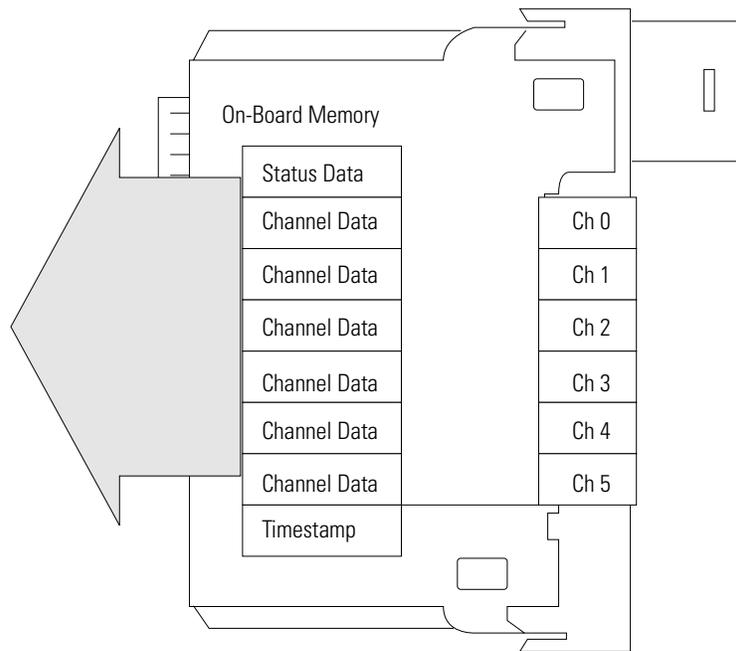
The RTS value is set during the initial configuration using RSLogix 5000. This value can be adjusted anytime.

Requested Packet Interval (RPI)

This configurable parameter also instructs the module to multicast its channel and status data to the local chassis backplane.

The RPI instructs the module to multicast the **current contents** of its on-board memory when the RPI expires, (i.e. the module does not update its channels prior to the multicast).

Figure 2.2



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IMPORTANT

The RPI value is set during the initial module configuration using RSLogix 5000. This value can be adjusted when the controller is in Program mode.

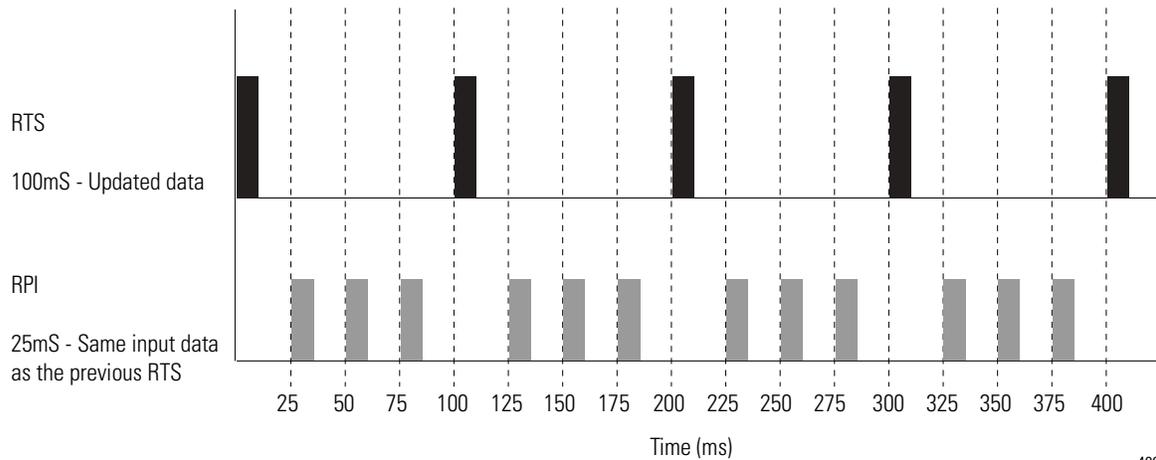
It is important to note that the module will reset the RPI timer each time an RTS is performed. This operation dictates how and when the owner-controller in the local chassis will receive updated channel data, depending on the values given to these parameters.

If the RTS value is less than or equal to the RPI, each multicast of data from the module will have updated channel information. In effect, the module is only multicasting at the RTS rate.

If the RTS value is greater than the RPI, the module multicasts at both the RTS rate and the RPI rate. Their respective values will dictate how often the owner-controller will receive data and how many multicasts from the module contain updated channel data.

In the example below, the RTS value is 100mS and the RPI value is 25mS. Only every fourth multicast from the module will contain updated channel data.

Figure 2.3



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Triggering Event Tasks

When configured to do so, ControlLogix analog input modules can trigger an event task. The event task offers ControlLogix controller users a task that executes a section of logic immediately when an event (i.e. receipt of new data) occurs.

Your ControlLogix analog I/O module can trigger event tasks every RTS, after the module has sampled and multicast its data. Events tasks are useful for synchronizing process variable (PV) samples and proportional integral derivative (PID) calculations.

IMPORTANT

ControlLogix analog I/O modules can trigger event tasks at every RTS but not at the RPI. For example, in Figure 2.3 above, an event task can only be triggered every 100ms.

Input Modules in a Remote Chassis

If an input module resides in a remote chassis, the role of the RPI and the module's RTS behavior change slightly with respect to getting data to the owner-controller, depending on what network type you are using to connect to the modules.

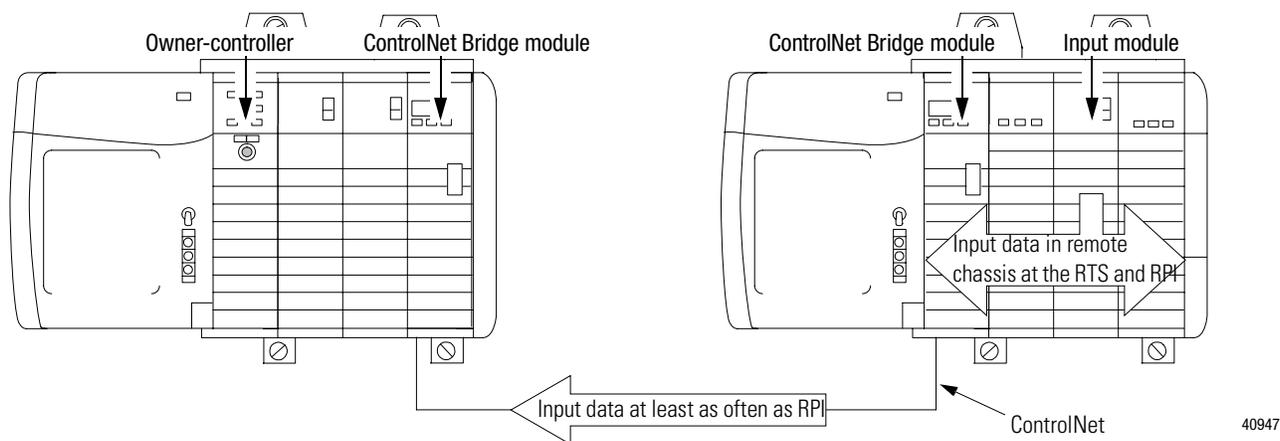
Remote Input Modules Connected Via ControlNet

When remote analog I/O modules are connected to the owner-controller via a scheduled ControlNet network, the RPI and RTS intervals still define when the module will multicast data **within its own chassis** (as described in the previous section). However, only the value of the RPI determines how often the owner-controller will receive it over the network.

When an RPI value is specified for an input module in a remote chassis connected by a scheduled ControlNet network, in addition to instructing the module to multicast data within its own chassis, the RPI also “reserves” a spot in the stream of data flowing across the ControlNet network.

The timing of this “reserved” spot may or may not coincide with the exact value of the RPI, but the control system guarantees that the owner-controller receives data **at least as often** as the specified RPI.

Figure 2.4 Input Module in Remote Chassis with RPI Reserving Spot in Flow of Data



The “reserved” spot on the network and the module's RTS are asynchronous to each other. This means there are Best and Worst Case scenarios as to when the owner-controller will receive updated channel data from the module in a networked chassis.

Best Case RTS Scenario

In the Best Case scenario, the module performs an RTS multicast with updated channel data just before the “reserved” network slot is made available. In this case, the remotely-located owner-controller receives the data almost immediately.

Worst Case RTS Scenario

In the Worst Case scenario, the module performs an RTS multicast just after the “reserved” network slot has passed. In this case, the owner-controller will not receive data until the next scheduled network slot.

TIP

Because it is the RPI and NOT the RTS which dictates when the module’s data will be sent over the network, we recommend the RPI value be set LESS THAN OR EQUAL TO the RTS to make sure that updated channel data is received by the owner-controller with each receipt of data.

Remote Input Modules Connected Via EtherNet/IP

When remote analog input modules are connected to the owner-controller via an EtherNet/IP network, data is transferred to the owner-controller in the following way:

- At the RTS or RPI (whichever is faster), the module multicasts data within its own chassis.
- The 1756-ENBT module in the remote chassis immediately sends the module’s data over the network to the owner-controller as long as it has not sent data within a timeframe that is 1/4 the value of the analog input module’s RPI.

For example, if an analog input module uses an RPI = 100ms, the 1756-ENBT module will only send module data immediately on receiving it if another data packet was not sent within the last 25ms.

Output Module Operation

The RPI parameter governs exactly when an analog output module receives data from the owner-controller and when the output module echoes data. An owner-controller sends data to an analog output module **only at the period specified in the RPI**. Data is NOT sent to the module at the end of the controller's program scan.

When an analog output module receives **new data** from an owner-controller (i.e. every RPI), the module automatically multicasts or "echoes" a data value that corresponds to the analog signal present at the output terminals to the rest of the control system. This feature, called **Output Data Echo**, occurs whether the output module is local or remote.

For more information on data echo, see the feature description in each module-specific chapter.

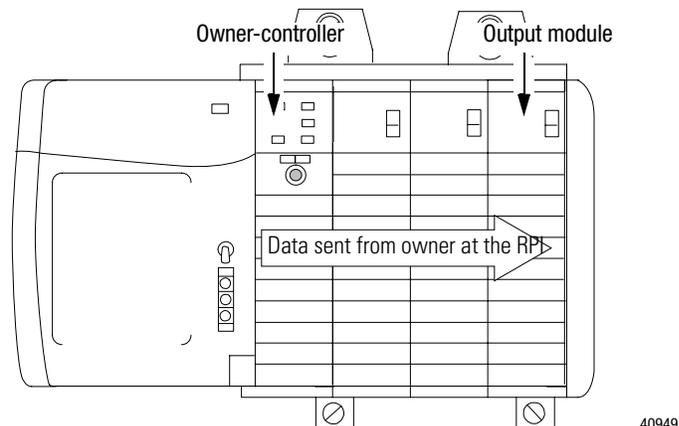
Depending on the value of the RPI, with respect to the length of the controller program scan, the output module can receive and "echo" data multiple times during one program scan.

When the RPI is less than the program scan length, the controller effectively allows the module's output channels to change values multiple times during a single program scan because the output module is not dependent on reaching the end of the program to send data.

Output Modules in a Local Chassis

When specifying an RPI value for an analog output module, you instruct the controller when to broadcast the output data to the module. If the module resides in the same chassis as the owner-controller, the module receives the data almost immediately after the controller sends it.

Figure 2.5



Output Modules in a Remote Chassis

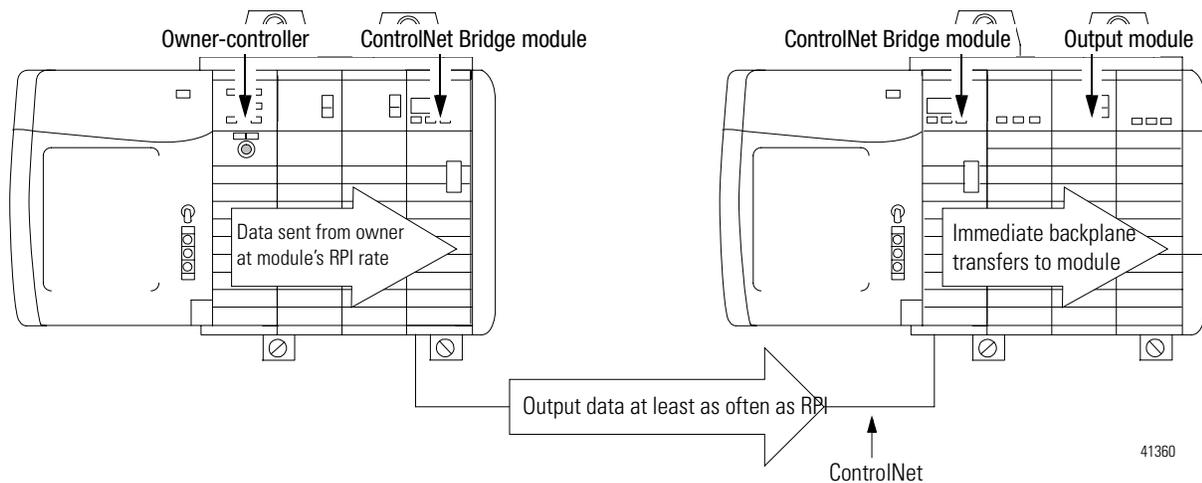
If an output module resides in a remote chassis, the role of the RPI changes slightly with respect to getting data from the owner-controller, depending on what network type you are using to connect to the modules.

Remote Output Modules Connected Via ControlNet

When remote analog output modules are connected to the owner-controller via a scheduled ControlNet network, in addition to instructing the controller to multicast the output data within its own chassis, the RPI also “reserves” a spot in the stream of data flowing across the ControlNet network.

The timing of this “reserved” spot may or may not coincide with the exact value of the RPI, but the control system will guarantee that the output module will receive data **at least as often** as the specified RPI.

Figure 2.6 Output Module in Remote Chassis with RPI Reserving a Spot in Flow of Data



The “reserved” spot on the network and when the controller sends the output data are asynchronous to each other. This means there are Best and Worst Case scenarios as to when the module will receive the output data from the controller in a networked chassis.

Best Case RPI Scenario

In the Best Case scenario, the controller sends the output data just BEFORE the “reserved” network slot is available. In this case, the remotely located output module receives the data almost immediately.

Worst Case RPI Scenario

In the Worst Case scenario, the controller sends the data just AFTER the “reserved” network slot has passed. In this case, the module does not receive the data until the next scheduled network slot.

IMPORTANT

These Best and Worst Case scenarios indicate the time required for output data to transfer from the controller to the module **once the controller has produced it.**

The scenarios do not take into account when the module will receive NEW data (updated by the user program) from the controller. That is a function of the length of the user program and its asynchronous relationship with the RPI.

Remote Output Modules Connected Via EtherNet/IP

When remote analog output modules are connected to the owner-controller via an EtherNet/IP network, the controller multicasts data in the following way:

- At the RPI, the owner-controller multicasts data within its own chassis.
- The 1756-ENBT module in the local chassis immediately sends the data over the network to the analog output module as long as it has not sent data within a timeframe that is 1/4 the value of the analog module’s RPI.

Listen-Only Mode

Any controller in the system can **listen** to the data from any I/O module (e.g. input data or “echoed” output data) even if the controller does not own the module. In other words, the controller does not have to own a module’s configuration data to listen to it.

During the I/O configuration process, you can specify one of several ‘Listen-Only’ modes in the Communication Format field. For more information on Communications Format, see page 10-6.

Choosing a ‘Listen-Only’ mode option allows the controller and module to establish communications without the controller sending any configuration data. In this instance, another controller owns the module being listened to.

IMPORTANT

Controllers using the Listen-Only mode continue to receive data multicast from the I/O module as long as a connection between an owner-controller and I/O module is maintained.

If the connection between all owner-controllers and the module is broken, the module stops multicasting data and connections to all ‘Listening controllers’ are also broken.

Multiple Owners of Input Modules

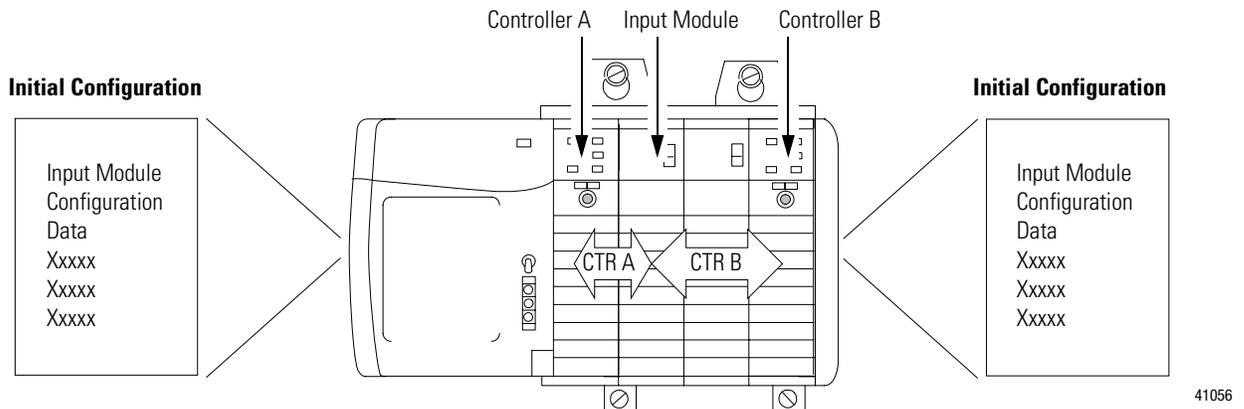
Because ‘Listening controllers’ lose their connections to modules when communications with the owner stop, the ControlLogix system will allow you to define more than one owner for input modules.

IMPORTANT

Only input modules can have multiple owners. If multiple owners are connected to the same input module, they **must maintain identical configuration** for that module.

In the example below, Controller A and Controller B have both been configured to be the owner of the input module.

Figure 2.7 Multiple Owners with Identical Configuration Data



When multiple controllers are configured to own the same input module, the following events occur:

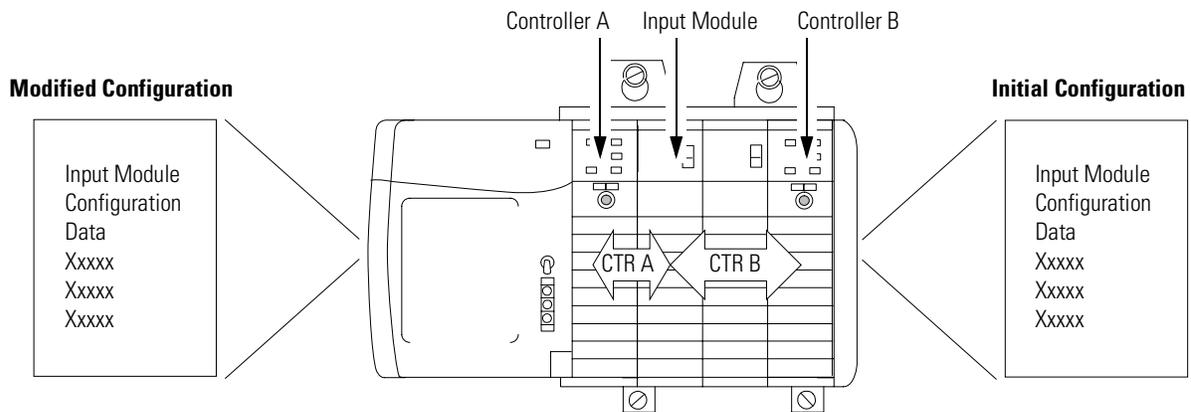
- When the controllers begin downloading configuration data, both try to establish a connection with the input module.
- Whichever controller’s data arrives first establishes a connection.
- When the second controller’s data arrives, the module compares it to its current configuration data (the data received and accepted from the first controller).
 - If the configuration data sent by the second controller matches the configuration data sent by the first controller the connection is also accepted.
 - If any parameter of the second configuration data is different from the first, the module rejects the connection; RSLogix 5000 alerts you to the rejected connection through an error message.

The advantage of multiple owners over a ‘Listen-only’ connection is that now either of the controllers can lose the connection to the module and the module will continue to operate and multicast data to the system because of the connection maintained by the other owner-controller.

Configuration Changes in an Input Module with Multiple Owners

You must be careful when changing an input module's configuration data in a multiple owner scenario. When the configuration data is changed in one of the owners, for example, Controller A, and sent to the module, that configuration data is accepted as the new configuration for the module. Controller B continues to listen, unaware that any changes have been made in the module's behavior.

Figure 2.8 Multiple Owners with Changed Configuration Data



Controller B is unaware that changes were made by Controller A.

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IMPORTANT

A pop-up screen in RSLogix 5000 alerts you to the possibility of a multiple owner situation and allows you to inhibit the connection before changing the module's configuration. When changing configuration for a module with multiple owners, we recommend the connection be inhibited.

To prevent other owners from receiving potentially erroneous data, as described above, the following steps **must be followed** when changing a module's configuration in a multiple owner scenario while online:

1. For each owner-controller, inhibit the controller's connection to the module, either in the software on the Connection tab or the pop-up screen warning of the multiple owner condition.
2. Make the appropriate configuration data changes in the software. For detailed information on using RSLogix 5000 to change configuration, see Chapter 10.
3. Repeat steps 1 and 2 for all owner-controllers, making the **exact same changes** in all controllers.
4. Disable the Inhibit box in each owner's configuration.

Chapter Summary and What's Next

In this chapter, you learned about Analog I/O Operation Within the ControlLogix System.

Chapter 3 describes Using ControlLogix Analog I/O Module Features.

Notes:

Using ControlLogix Analog I/O Module Features

What This Chapter Contains This chapter describes features that are common to all ControlLogix analog I/O modules.

For information about:	See page:
Determining Input Module Compatibility	3-1
Determining Output Module Compatibility	3-1
Features Common to All Analog I/O Modules	3-2
Understanding the Relationship Between Module Resolution, Scaling and Data Format	3-11

Determining Input Module Compatibility

ControlLogix analog input modules convert an analog signal of either volts, millivolts, milliamps or ohms that is connected to the module's screw terminals into a digital value.

The digital value which represents the magnitude of the analog signal is then transmitted on the backplane to either a controller or other control entities.

For more information on compatibility of other Rockwell Automation products to ControlLogix analog input modules, see the I/O Products Systems Overview, publication CIG-SO001.

Determining Output Module Compatibility

ControlLogix output modules convert a digital value that is delivered to the module via the backplane into an analog signal of -10.5 to +10.5 volts or 0 to 21 milliamps.

The digital value represents the magnitude of the desired analog signal. The module converts the digital value into an analog signal and provides this signal on the module's screw terminals.

For more information on compatibility of other Rockwell Automation products to ControlLogix analog output modules, see the I/O Products Systems Overview, publication CIG-SO001.

Features Common to All Analog I/O Modules

Table 3.1 lists the features that are common to all ControlLogix analog I/O modules. The features are described later in this section.

Table 3.1

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Removal and Insertion Under Power (RIUP)

All ControlLogix I/O modules may be inserted and removed from the chassis while power is applied. This feature allows greater availability of the overall control system because, while the module is being removed or inserted, there is no additional disruption to the rest of the controlled process.

Module Fault Reporting

ControlLogix analog I/O modules provide both hardware and software indication when a module fault has occurred. Each module has an LED fault indicator and RSLogix 5000 will graphically display this fault and include a fault message describing the nature of the fault. This feature allows you to determine how your module has been affected and what action should be taken to resume normal operation.

For more information on module fault reporting as it relates to specific modules, see the chapter describing that module, either chapter 4, 5, 6, 7 or 8.

Fully Software Configurable

The RSLogix 5000 software uses a custom, easily understood interface to write configuration. All module features are enabled or disabled through the I/O configuration portion of the software.

You can also use the software to interrogate any module in the system to retrieve:

- serial number
- revision information
- catalog number
- vendor identification
- error/fault information
- diagnostic counters.

By eliminating such tasks as setting hardware switches and jumpers, the software makes module configuration easier and more reliable.

Electronic Keying

Instead of plastic mechanical backplane keys, electronic keying allows the ControlLogix system to control what modules belong in the various slots of a configured system.

During module configuration, you must choose one of the following keying options for your I/O module:

- Exact Match
- Compatible Match
- Disable Keying

When the controller attempts to connect to and configure an I/O module (e.g. after program download), the module compares the following parameters before allowing the connection and configuration to be accepted:

- Vendor
- Product Type
- Catalog Number
- Major Revision - Change that affects the module's function or RSLogix 5000 interface
- Minor Revision - Change that does not affect the module's function or RSLogix 5000 interface (e.g. bug fixes)

The comparison is made between the keying information present in the I/O module and the keying information in the controller's program. This feature can prevent the inadvertent operation of a control system with the wrong module in the wrong slot. For example, if you select Exact Match and a module with revision 2.2 is placed in a location configured for a module with revision 2.4, the controller does not make a connection to the new module because of the mismatched revisions.

Table 3.2 describes the keying options available with your ControlLogix analog I/O module.

Table 3.2

Keying option:	Definiton:
Exact Match	All of the parameters listed above must match or the inserted module will reject a connection to the controller.
Compatible Match	<p>The Compatible Match mode allows an I/O module to determine whether it can emulate the module defined in the configuration sent from the controller.</p> <p>With ControlLogix analog I/O modules, the module can emulate older revisions. The module will accept the configuration if the configuration's major.minor revision is less than or equal to the physical module's revision.</p> <p>For example, if the configuration contains a major.minor revision of 1.7, the module inserted into the slot must have a firmware revision of 1.7 or higher for a connection to be made. When a module is inserted with a major.minor revision that is less than the revision for which the slot is configured (i.e. the module has a revision of 1.6 and the slot is configured for a module with revision 1.8), no connection is made between the controller and the I/O module.</p>
	<div style="display: flex; align-items: flex-start;"> <div style="background-color: black; color: white; padding: 5px; margin-right: 10px;">TIP</div> <div> <p>We recommend using Compatible Match whenever possible. Remember, though, with major revision changes, the module only works to the level of the configuration. At the time of this printing, the ControlLogix analog I/O modules all used a major revision of 1.⁽¹⁾</p> <p>However, if a new major revision for a ControlLogix analog I/O module is released, consider this example. If a slot is configured for a module with major.minor revision of 1.7 and you insert a module with a major.minor revision of 2.3, the module works at the 1.7 level, with respect to module functions that are related to RSLogix 5000 such as interface changes. However, bug fixes that are affected by the module's firmware, would work at the 2.3 revision level.</p> <p>If possible, we suggest you make sure configuration is updated to match the revision levels of all I/O modules. Failure to do so may not prevent the application from working but may defeat the purpose of upgrading your modules' revision levels.</p> </div> </div>
Disable Keying	<p>The inserted module attempts to accept a connection to the controller regardless of its type.</p> <div style="display: flex; align-items: flex-start;"> <div style="background-color: black; color: white; padding: 5px; margin-right: 10px;">ATTENTION</div> <div style="text-align: center;">  </div> <div style="margin-left: 10px;"> <p>Be extremely cautious when using the disable keying option; if used incorrectly, this option can lead to personal injury or death, property damage or economic loss.</p> </div> </div> <p>If keying is disabled, a controller makes a connection with most modules of the same type as that used in the slot configuration. For example, if a slot is configured for a 1756-IF16 (16-point non-isolated analog current/voltage input module), and a 1756-IF8 (8-point non-isolated analog current/voltage input module) is inserted into the slot, the controller may establish a connection because keying is disabled.</p> <p>Even if keying is disabled, a controller will not establish a connection if the slot is configured for one module type (e.g. input module) and a module of another type (e.g. output module) is inserted in the slot.</p>

⁽¹⁾ Minor revisions are incremented by single counts such that minor level 10 (i.e. major.minor revision level = 1.10) follows minor revision level 9 (i.e. 1.9).

Access to System Clock for Timestamping Functions

Controllers within the ControlLogix chassis maintain a system clock. This clock is also known as the Coordinated System Time (CST). You can configure your analog I/O modules to access this clock and timestamp input data or output echo data when the module multicasts to the system. You decide how to timestamp data when you choose a Communications Format. For more information on choosing a Communications Format, see page 10-6.

This feature allows for accurate calculations between events to help you identify the sequence of events in either fault conditions or in the course of normal I/O operations. The system clock can be used between multiple modules in the same chassis.

Rolling Timestamp

Each module maintains a rolling timestamp that is unrelated to the CST. The rolling timestamp is a continuously running 15 bit timer that counts in milliseconds.

For input modules, whenever a module scans its channels, it also records the value of the rolling timestamp at that time. The user program can then use the last two rolling timestamp values and calculate the interval between receipt of data or the time when new data has been received.

For output modules, the rolling timestamp value is only updated when new values are applied to the Digital to Analog Converter (DAC).

Producer/Consumer Model

By using the Producer/Consumer model, ControlLogix I/O modules can produce data without having been polled by a controller first. The modules produce the data and any owner or listen-only controller device can decide to consume it.

For example, an input module produces data and any number of processors can consume the data at the same time. This eliminates the need for one processor to send the data to another processor. For a more detailed explanation of this process, see Chapter 2, Analog I/O Operation Within the ControlLogix System.

Status Indicator Information

Each ControlLogix analog I/O module has status indicators on the front of the module that allows you to check the module health and operational status of a module.

Table 3.3 describes what status each status indicator represents:

Table 3.3

Status:	Description:
Calibration status	display indicates when your module is in the calibration mode
Module status	display indicates the module's communication status

For examples of LED indicators on ControlLogix analog I/O modules, see Chapter 12, Troubleshooting Your ControlLogix Analog I/O Module.

Full Class I Division 2 Compliance

All ControlLogix analog I/O modules maintain CSA Class I Division 2 system certification. This allows the ControlLogix system to be placed in an environment other than only a 100% hazard free.

IMPORTANT

Modules should not be pulled under power, nor should a powered RTB be removed, when a hazardous environment is present.

UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification

Any ControlLogix analog I/O modules that have obtained various agency certifications are marked as such. Ultimately, all analog modules will have these agency approvals and be marked accordingly.

Field Calibration

ControlLogix analog I/O modules allow you to calibrate on a channel-by-channel or module-wide basis. RSLogix 5000 provides a software interface to perform calibration.

To see how to calibrate your module, see Chapter 11, *Calibrating the ControlLogix Analog I/O Modules*.

Sensor Offset

You can add this offset directly to the input or output during calibration calculation. The purpose of this feature is to allow you to compensate for any sensor offset errors which may exist, such offset errors are common in thermocouple sensors.

To see how to set the sensor offset, see page 10-10.

Latching of Alarms

The latching feature allows analog I/O modules to latch an alarm in the set position once it has been triggered, even if the condition causing the alarm to occur disappears.

Data Format

During initial configuration of any ControlLogix analog I/O module, you must choose a Communications Format. The format chosen determines the data format of data exchanged between the owner-controller and the I/O module. For more information on choosing a Communications Format, see page 10-6.

Your analog module multicasts data in the formats listed in Table 3.4.

Table 3.4

Format type:	Description:
Integer	<p>This mode uses a 16-bit signed format and allows faster sampling rates while using less memory in the controller but also limits the availability of features on your module.</p> <p>The faster sampling rates and lower memory usage vary according to module and application type. For more information on the specific sampling rates, see the Module Filter section in the module-specific chapters. Memory usage can be up to 50% less than in floating point.</p>
Floating point	This mode uses a 32 bit IEEE floating point format.

Your choice of data format may restrict the features available with an I/O module. For example, if you use an integer data format with the 1756-OF6CI module, the Clamping feature is not available for use. For specific listings of what features are available and not available see the individual chapters for each catalog number.

TIP

We recommend that you use the floating point data format in most applications. Floating point is simpler to use and offer all module features. All ControlLogix analog I/O module default to floating point when initialled configured.

You should only use the integer data format if your application requires faster sampling rates than offered in in floating point or if you application memory is extremely limited.

For a more detailed explanation of Data Formats, as they relate to module resolution and scaling, see the next section.

Module Inhibiting

Module inhibiting allows you to indefinitely suspend a connection between an owner-controller and an analog I/O module. This process can occur in either of the following ways:

- You write configuration for an I/O module but inhibit the module to prevent it from communicating with the owner-controller. In this case, the owner does not establish a connection and configuration is not sent to the module until the connection is uninhibited.
- In your application, a controller already owns a module, has downloaded configuration to the module and is currently exchanging data over the connection between the devices. In this case, you can inhibit the module and the owner-controller behaves as if the connection to the module does not exist.

IMPORTANT

Whenever you inhibit an output module, it enters the program mode and all outputs change to the state configured for the program mode. For example, if an output module is configured so that the state of the outputs go to zero (0) during program mode, whenever that module is inhibited, the outputs will go to zero (0).

The following examples are instances where you may need to use module inhibiting:

- Multiple controllers own the same analog input module. A change is required in the module's configuration; however, the change must be made to the program in all controllers. In this case, you can:
 - a. Inhibit the module.
 - b. Change configuration in all controllers.
 - c. Uninhibit the module.
- You want to FLASH upgrade an analog I/O module. We recommend you:
 - a. Inhibit the module.
 - b. Perform the upgrade.
 - c. Uninhibit the module.
- You are using a program that includes a module that you do not physically possess yet, but you do not want the controller to continually look for a module that does not exist yet. In this case, you can inhibit the module in your program until it physically resides in the proper slot.

Understanding the Relationship Between Module Resolution, Scaling and Data Format

The following three concepts are closely related and must be explained in conjunction with each other:

- Module Resolution
- Scaling
- Data Format as Related to Resolution and Scaling

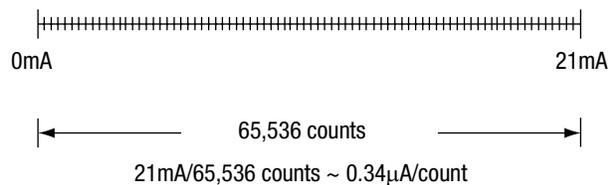
Module Resolution

Resolution is the smallest amount of change that the module can detect. Analog input modules are capable of 16 bit resolution. Output modules are capable of 13-16 bit resolution, depending on the module type.

The 16 bits represent 65,536 counts. This total is fixed but the value of each count is determined by the operational range you choose for your module.

For example, if you are using the 1756-IF6I module, your module's available current range equals 21mA. Divide your range by the number of counts to figure out the value of each count. In this case, one count is approximately 0.34 μ A.

Figure 3.1 Module Resolution



IMPORTANT

A module's resolution is fixed. It will not change regardless of what data format you choose or how you decide to scale your module in floating point mode.

Resolution is based on the module hardware and the range selected. If you use a sensor with limited range, you do not change the module resolution.

Table 3.5 lists the resolution for each module's range.

Table 3.5 Current Values Represented in Engineering Units

Module:	Range:	Number of significant bits:	Resolution:
1756-IF16 and 1756-IF8	+/- 10.25V	16 bits	320 μ V/count
	0V - 10.25V		160 μ V/count
	0V - 5.125V		80 μ V/count
	0mA - 20.5mA		0.32 μ A/count
1756-IF6CIS	0mA - 21mA	16 bits	0.34 μ A/count
1756-IF6I	+/- 10.5V	16 bits	343 μ V/count
	0V - 10.5V		171 μ V/count
	0V - 5.25V		86 μ V/count
	0mA - 21mA		0.34 μ A/count
1756-IR6I	1 Ω - 487 Ω	16 bits	7.7m Ω /count
	2 Ω - 1000 Ω		15m Ω /count
	4 Ω - 2000 Ω		30m Ω /count
	8 Ω - 4020 Ω		60m Ω /count
1756-IT6I and 1756-IT6I2	-12mV - 30mV	16 bits	0.7 μ V/count
	-12mV - 78mV		1.4 μ V/count
1756-OF4 and 1756-OF8	+/- 10.4V	16 bits	320 μ V/count
	0mA - 21mA	15 bits	0.65 μ A/count
1756-OF6VI	+/- 10.5V	14 bits	1.3mV
1756-OF6CI	0mA - 21mA	13 bits	2.7 μ A

IMPORTANT

Because these modules must allow for possible calibration inaccuracies, resolution values represent the available Analog to Digital or Digital to Analog counts over the specified range.

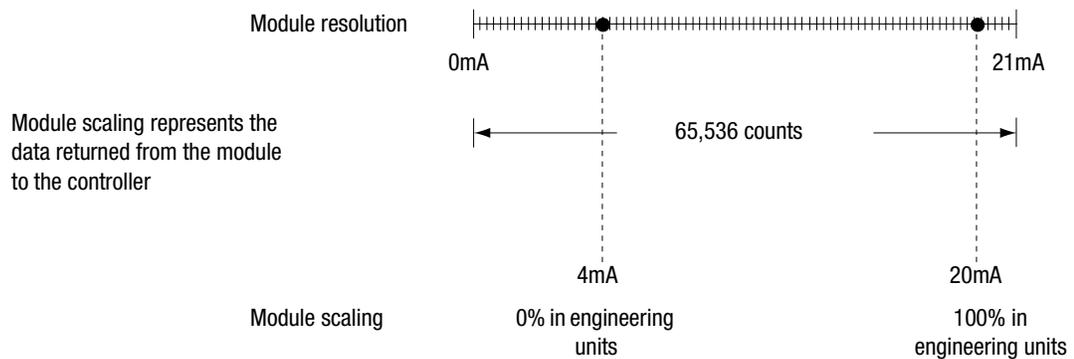
Scaling

With scaling, you change a quantity from one notation to another. For ControlLogix analog I/O modules, scaling is **only available with the floating point data format**.

When you scale a channel, you must choose two points along the module's operating range and apply low and high values to those points. For example, if you are using the 1756-IF6I module in current mode, the module maintains a 0mA to 21mA range capability. But your application may use a 4mA to 20mA transmitter. You can scale the module to represent 4mA as the low signal and 20mA as the high signal.

Scaling allows you to configure the module to return data to the controller so that 4mA returns a value of 0% in engineering units and 20mA returns a value of 100% in engineering units.

Figure 3.2 Module Resolution Compared to Module Scaling



IMPORTANT

In choosing two points for the low and high value of your application, you do not limit the range of the module. The module's range and its resolution remain constant regardless of how you scale it for your application.

The module may operate with values beyond the 4mA to 20mA range. If an input signal beyond the low and high signals is present at the module (e.g. 3mA), that data will be represented in terms of the engineering units set during scaling. Table 3.5 shows example values that may appear based on the example mentioned above.

Table 3.6 Current Values Represented in Engineering Units

Current:	Engineering units value:
3mA	-6.25%
4mA	0%
12mA	50%
20mA	100%
21mA	106.25%

Data Format as Related to Resolution and Scaling

You can choose one of the following data formats for your application:

- Integer mode
- Floating point mode

Integer mode

This mode provides the most basic representation of analog data. When a module multicasts data in the integer mode, the low and high signals of the input range are fixed.

IMPORTANT

Scaling is not available in integer mode. The low signal of your application range equals -32,768 counts while the high signal equals 32,767 counts.

In integer mode, input modules generate digital signal values that correspond to a range from -32,768 to 32,767 counts.

Table 3.7 lists the conversions of a generated digital signal to the number of counts.

Table 3.7 Input Signal to User Count Conversion

Input module:	Available range:	Low signal and user counts:	High signal and user counts:
1756-IF16/IF8	+/- 10V	-10.25V -32768 counts	10.25V 32767 counts
	0V - 10V	0V -32768 counts	10.25V 32767 counts
	0V - 5V	0V -32768 counts	5.125V 32767 counts
	0mA - 20mA	0mA -32768 counts	20.58mA 32767 counts
1756-IF6CIS	0mA - 20mA	0mA -32768 counts	21.09376mA 32767 counts
1756-IF6I	+/- 10V	-10.54688V -32768 counts	10.54688V 32767 counts
	0V - 10V	0V -32768 counts	10.54688V 32767 counts
	0V - 5V	0V -32768 counts	5.27344V 32767 counts
	0mA - 20mA	0mA -32768 counts	21.09376mA 32767 counts
1756-IR6I	1 Ω - 487 Ω	0.859068653 Ω -32768 counts	507.862 Ω 32767 counts
	2 Ω - 1000 Ω	2 Ω -32768 counts	1016.502 Ω 32767 counts
	4 Ω - 2000 Ω	4 Ω -32768 counts	2033.780 Ω 32767 counts
	8 Ω - 4020 Ω	8 Ω -32768 counts	4068.392 Ω 32767 counts
1756-IT6I and 1756-IT6I2	-12mV - 30mV	-15.80323mV -32768 counts	31.396mV 32767 counts
	-12mV - 78mV	-15.15836mV -32768 counts	79.241mV 32767 counts

Output modules allow you to generate an analog signal at the screw terminals that correspond to a range from -32,768 to 32,767 counts.

Table 3.8 lists the conversions a generated digital signal to the number of counts.

Table 3.8 Output Signal to User Count Conversion

Output module:	Available range:	Low signal and user counts:	High signal and user counts:
1756-OF4/OF8	0mA - 20mA	0mA	21.2916mA
		-32768 counts	32767 counts
	+/- 10V	-10.4336V	10.4336V
		-32768 counts	32767 counts
1756-OF6CI	0mA - 20mA	0mA	21.074mA
		-32768 counts	32767 counts
1756-OF6VI	+/- 10V	-10.517V	10.517V
		-32768 counts	32767 counts

Floating point mode

This data type mode allows you to change the data representation of the selected module. Although the full range of the module does not change, you can **scale** your module to represent I/O data in terms specific for your application.

For example, if you are using the 1756-IF6I module in floating point mode and choose an input range of 0mA to 20mA, the module can use signals within the range of 0mA to 21mA but you can scale the module to represent data between 4mA to 20mA as the low and high signals in engineering units as shown in Figure 3.1 on page 3-11.

For an example of how to define data representation in engineering units through RSLogix 5000, see page 10-10.

Difference Between Integer and Floating Point

The key difference between choosing integer mode or floating point mode is that integer is fixed between -32,768 and 32,767 counts and floating point mode provides scaling to represent I/O data in specific engineering units for your application. Module resolution remains constant between the formats at 0.34 μ A/count.

For example, Table 3.9 shows the difference in the data returned from the 1756-IF6I module to the controller between data formats. In this case, the module uses the 0mA-20mA input range with 0mA scaled to 0% and 20mA scaled to 100%, as shown in Figure 3.1 on page 3-11.

Table 3.9 Difference Between Data Formats in Applications Using the 1756-IF6I Module and An Input Range of 0mA to 20mA

Signal value:	Fixed number of counts in integer mode:	Data representation in floating point mode (Engineering units):
0mA	-32768 counts	-25%
4mA	-20341 counts	0%
12mA	4514 counts	50%
20mA	29369 counts	100%
21.09376mA	32767 counts	106.25%

Chapter Summary and What's Next

In this chapter you learned about using features common to all ControlLogix analog I/O modules

Move to Chapter 4 to learn about non-isolated analog input modules.

Notes:

Non-Isolated Analog Voltage/Current Input Modules (1756-IF16, -IF8)

What This Chapter Contains This chapter describes features specific to ControlLogix non-isolated analog voltage/current input modules.

For information about:	See page:
Choosing a Wiring Method	4-2
Choosing a Data Format	4-4
Features Specific to Non-Isolated Analog Input Modules	4-5
Using Module Block and Input Circuit Diagrams	4-12
Wiring the 1756-IF16 Module	4-15
Wiring the 1756-IF8 Module	4-19
1756-IF16 Module Fault and Status Reporting	4-23
1756-IF8 Module Fault and Status Reporting	4-30

In addition to the features described in this chapter, the non-isolated analog voltage/current input modules support all features described in Chapter 3. Table 4.1 lists additional features that your non-isolated analog voltage/current input modules support.

Table 4.1 Additional Features Supported by the Non-Isolated Analog Input Modules

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Choosing a Wiring Method

The 1756-IF16 and 1756-IF8 modules support the following three wiring methods:

- Single-Ended Wiring Method
- Differential Wiring Method
- High Speed Mode Differential Wiring Method

After determining which wiring method you will use on your module, you must inform the system of that choice when you choose a Communications Format. For more information on choosing a Communications Format, see page 10-6.

For examples of each wiring format on the 1756-IF16 module, see the examples beginning on page 4-15. For examples of each wiring format on the 1756-IF8 module, see the examples beginning on page 4-19.

Single-Ended Wiring Method

Single-ended wiring compares one side of the signal input to signal ground. This difference is used by the module in generating digital data for the controller.

When using the single-ended wiring method, all input devices are tied to a common ground. In addition to the common ground, the use of single-ended wiring maximizes the number of usable channels on the module (8 channels for 1756-IF8 module & 16 channels for the 1756-IF16).

Differential Wiring Method

The differential wiring method is recommended for applications in which it is advantageous or required to have separate signal pairs or a common ground is not available. Differential wiring is recommended for environments where improved noise immunity is needed.

IMPORTANT

This wiring method allows use of only half a module's channels. For example, you can only use 8 channels on the 1756-IF16 module and 4 channels on the 1756-IF8 module.

High Speed Mode Differential Wiring Method

You can configure the 1756-IF16 and 1756-IF8 modules for a high speed mode that will give you the fastest data updates possible. When using the high speed mode, remember the following conditions:

- This mode uses the differential wiring method
- This mode only allows use of 1 out of every 4 channels on the module

Update times for applications using the high speed mode can be found in Table 4.5 on page 4-6.

Choosing a Data Format

Data format determines the format of the data returned from the module to the owner-controller and the features that are available to your application. You choose a data format when you choose a Communications Format. For more information on Communications Format, see page 10-6.

You can choose one of the two following data formats:

- Integer mode
- Floating point mode

Table 4.2 shows which features are available in each format.

Table 4.2 Features Available in Each Data Format

Data format:	Features available:	Features not available:
Integer mode	Multiple input ranges Module filter Real time sampling	Process alarms Digital filtering Rate alarms Scaling
Floating point mode	All features	See below

IMPORTANT

When using the **1756-IF16** module in **single-ended** mode (i.e. 16 channel mode) with floating point data format, **process alarms and rate alarms** are **not available**.

This condition exists only when the 1756-IF16 is wired for single-ended mode. The 1756-IF8 is not affected.

Features Specific to Non-Isolated Analog Input Modules

Table 4.3 lists features that are specific to the 1756-IF16 and 1756-IF8 modules. The features are described later in this section.

Table 4.3

Feature:	Page of description:
Multiple Input Ranges	4-5
Module Filter	4-6
Real Time Sampling	4-7
Underrange/Overrange Detection	4-7
Digital Filter	4-8
Process Alarms	4-9
Rate Alarm	4-10
Wire Off Detection	4-10

Multiple Input Ranges

You can select from a series of operational ranges for **each channel** on your module. The range designates the minimum and maximum signals that are detectable by the module.

Table 4.4 Possible Input Ranges

Module:	Possible ranges:
1756-IF16 and 1756-IF8	-10 to 10V 0 to 5V 0 to 10V 0 to 20mA

For an example of how to choose an input range for your module, see page 10-10.

Module Filter

The module filter is a built-in feature of the Analog-to-Digital convertor which attenuates the input signal beginning at the specified frequency. This feature is applied on a module-wide basis.

The module attenuates the selected frequency by approximately -3dB or 0.707 of the applied amplitude. This selected frequency is also called the bandwidth of the module.

An input signal with frequencies above the selected frequency will be attenuated more while frequencies below the selection will receive no attenuation.

In addition to frequency rejection, a by-product of the filter selection is the minimum sample rate (RTS) that is available. For example, in floating point mode, the 1000Hz selection will not attenuate any frequencies less than 1000Hz but will allow sampling of all 16 channels within 18ms. But the 10Hz selection attenuates all frequencies above 10Hz and only allow sampling all 16 channels within 488ms.

IMPORTANT

60Hz is the default setting for the module filter. This setting provides approximately 3dB of filtering of a 60Hz input.

Use Table 4.5 to choose a module filter setting.

Table 4.5 Notch Filter Selections with Associated Performance Data

Module Filter Setting (-3dB) ^{(1) (2)}	Wiring Mode	10Hz	50Hz/60Hz (Default)	100Hz	250Hz	1000Hz
Minimum Sample Time (RTS)	Single-Ended	488ms	88ms	56ms	28ms	16ms
Integer Mode	Differential	244ms	44ms	28ms	14ms	8ms
	High Speed Differential	122ms	22ms	14ms	7ms	5ms
Minimum Sample Time (RTS)	Single-Ended	488ms	88ms	56ms	28ms	18ms
Floating Point Mode	Differential	244ms	44ms	28ms	14ms	11ms
	High Speed Differential	122ms	22ms	14ms	7ms	6ms
Effective Resolution		16 bits	16 bits	16 bits	14 bits	12 bits

⁽¹⁾ For optimal 50/60Hz noise rejection (>80dB), choose the 10Hz filter.

⁽²⁾ Worst case settling time to 100% of a step change is double the RTS sample times

To see how to choose a Module Filter, see page 10-10.

Real Time Sampling

This parameter instructs the module how often to scan its input channels and obtain all available data. After the channels are scanned, the module multicasts that data. This feature is applied on a module-wide basis.

During module configuration, you specify a Real Time Sampling (RTS) period and a Requested Packet Interval (RPI) period. Both of these features instruct the module to multicast data, but only the RTS feature instructs the module to scan its channels before multicasting.

For more information on Real Time Sampling, see page 2-4. For an example of how to set the RTS rate, see page 10-10.

Underrange/Overrange Detection

This feature detects when the non-isolated input module is operating beyond limits set by the input range. For example, If you are using the 1756-IF16 module in the 0V-10V input range and the module voltage increases to 11V, the Overrange detection detects this condition.

Use the following table to see the input ranges of non-isolated input modules and the lowest/highest signal available in each range before the module detects an underrange/overrange condition:

Table 4.6 Low and High Signal Limits on Non-Isolated Input Modules

Input module:	Available range:	Lowest signal in range:	Highest signal in range:
1756-IF16 and 1756-IF8	+/- 10V	-10.25V	10.25V
	0V-10V	0V	10.25V
	0V-5V	0V	5.125V
	0mA-20mA	0mA	20.58mA

Digital Filter

The digital filter smooths input data noise transients for all channels on the module. This feature is applied on a **per channel** basis.

The digital filter value specifies the time constant for a digital first order lag filter on the input. It is specified in units of milliseconds. A value of 0 disables the filter.

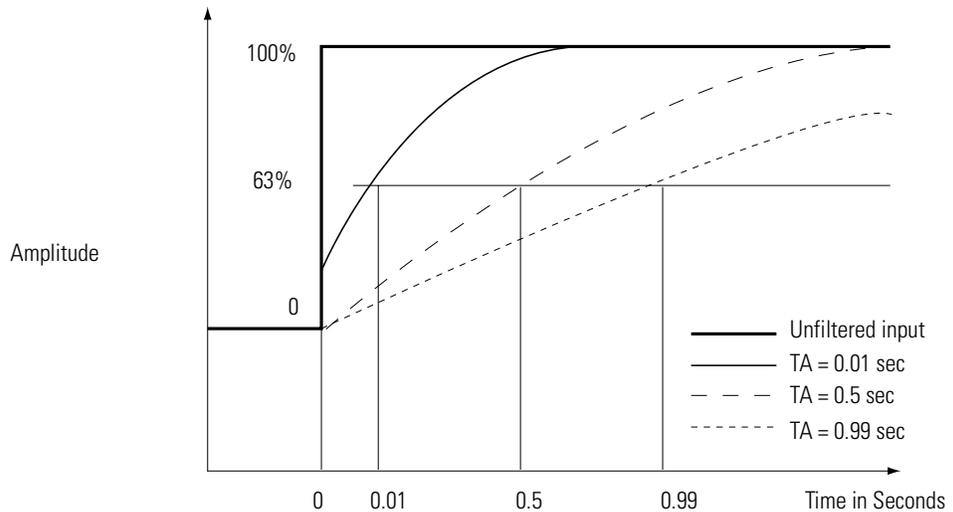
The digital filter equation is a classic first order lag equation.

$$Y_n = Y_{n-1} + \frac{[\Delta t]}{\Delta t + TA} (X_n - Y_{n-1})$$

- Y_n = present output, filtered peak voltage (PV)
- Y_{n-1} = previous output, filtered PV
- Δt = module channel update time (seconds)
- TA = digital filter time constant (seconds)
- X_n = present input, unfiltered PV

Using a step input change to illustrate the filter response, as shown in Figure 4.1, you can see that when the digital filter time constant elapses, 63.2% of the total response is reached. Each additional time constant achieves 63.2% of the remaining response.

Figure 4.1



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To see how to set the Digital Filter, see page 10-10.

Process Alarms

Process alarms alert you when the module has exceeded configured high or low limits for **each channel**. You can latch process alarms. These are set at four user configurable alarm trigger points:

- High high
- High
- Low
- Low low

IMPORTANT

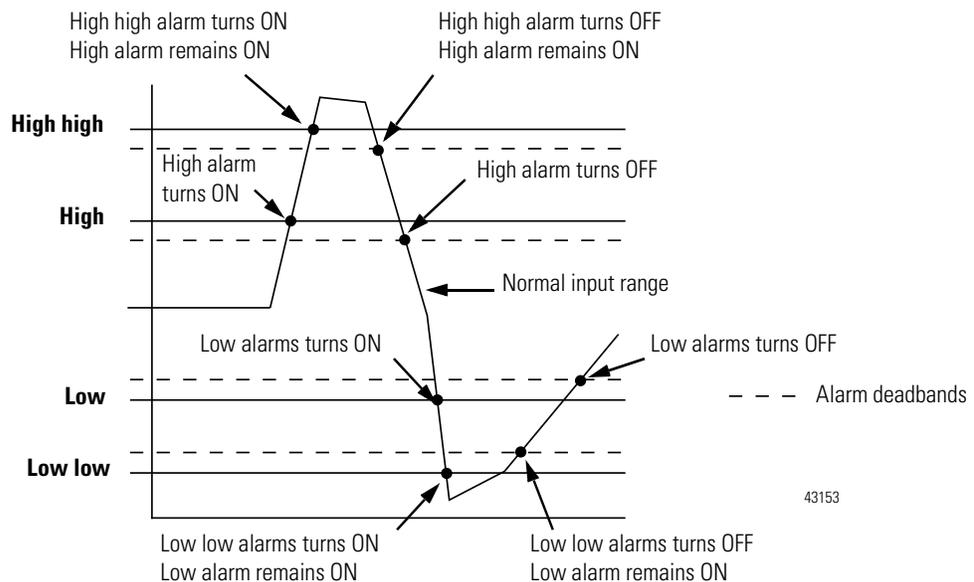
Process alarms are not available in integer mode or in applications using 1756-IF16 module in the single-ended, floating point mode. The values for each limit are entered in scaled engineering units.

Alarm Deadband

You may configure an **Alarm Deadband** to work with the process alarms. The deadband allows the process alarm status bit to remain set, despite the alarm condition disappearing, as long as the input data remains within the deadband of the process alarm.

Figure 4.2 shows input data that sets each of the four alarms at some point during module operation. In this example, Latching is disabled; therefore, each alarms turns OFF when the condition that caused it to set ceases to exist.

Figure 4.2



To see how to set Process Alarms, see page 10-10.

Rate Alarm

The rate alarm triggers if the rate of change between input samples for **each channel** exceeds the specified trigger point for that channel.

IMPORTANT

Rate alarms are not available in integer mode or in applications using 1756-IF16 module in the single-ended, floating point mode. The values for each limit are entered in scaled engineering units.

For example, if you set the 1756-IF16 (with normal scaling in Volts) to a rate alarm of 1.0 V/S, the rate alarm will only trigger if the difference between measured input samples changes at a rate > 1.0 V/S.

If the module's RTS is 100 ms (i.e. sampling new input data every 100ms) and at time 0, the module measures 5.0 volts and at time 100ms measures 5.08 V, the rate of change is $(5.08V - 5.0V) / (100mS) = 0.8$ V/S. The rate alarm would not set as the change is less than the trigger point of 1.0V/s.

If the next sample taken is 4.9V, the rate of change is $(4.9V - 5.08V) / (100mS) = -1.8V/S$. The absolute value of this result is $> 1.0V/S$, so the rate alarm will set. Absolute value is applied because rate alarm checks for the magnitude of the rate of change being beyond the trigger point, whether a positive or negative excursion.

To see how to set the Rate Alarm, see page 10-10.

Wire Off Detection

The 1756-IF16 and 1756-IF8 modules will alert you when a **signal wire only** has been disconnected from one of its channels or the RTB has been removed from the module. When a wire off condition occurs for this module, two events occur:

- Input data for that channel changes to a specific scaled value
- A fault bit is set in the owner-controller which may indicate the presence of a wire off condition

Because the 1756-IF16 and 1756-IF8 modules can be applied in voltage or current applications, differences exist as to how a wire off condition is detected in each application.

Table 4.7 lists the differences that occur when a wire off condition occurs in various applications.

Table 4.7

When the Wire Off condition occurs in this application:	The following events occur:
Single-Ended Voltage Applications	<ul style="list-style-type: none"> • Input data for odd numbered channels changes to the scaled value associated with the underrange signal value of the selected operational range in floating point mode (minimum possible scaled value) or -32,767 counts in integer mode • The ChxUnderrange (x=channel number) tag is set to 1 • Input data for even numbered channels changes to the scaled value associated with the overrange signal value of the selected operational range in floating point mode (maximum possible scaled value) or 32,767 counts in integer mode • The ChxOvrerrange (x=channel number) tag⁽¹⁾ is set to 1
Single-Ended Current	<ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the underrange signal value of the selected operational range in floating point mode (minimum possible scaled value) or -32,768 counts in integer mode • The ChxUnderrange (x=channel number) tag is set to 1
Differential Voltage	<ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the overrange signal value of the selected operational range in floating point mode (maximum possible scaled value) or 32,768 counts in integer mode • The ChxOvrerrange (x=channel number) tag is set to 1
Differential Current Applications	<ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the underrange signal value of the selected operational range in floating point mode (minimum possible scaled value) or -32,768 counts in integer mode • The ChxUnderrange (x=channel number) tag is set to 1 <p>In current applications, if wire off detection occurs for one of the following reasons:</p> <ul style="list-style-type: none"> • because the RTB has been disconnected from the module • both the signal wire and the jumper wire have been disconnected <p>the module reacts with the same conditions as described in differential voltage applications.</p>

⁽¹⁾ For more information about tags in the tag editor, see Appendix B.

Using Module Block and Input Circuit Diagrams

This section shows the 1756-IF16 and 1756-IF8 modules' block diagrams and input circuit diagrams.

Module Block Diagrams

Figure 4.3 1756-IF16 Module Block Diagram

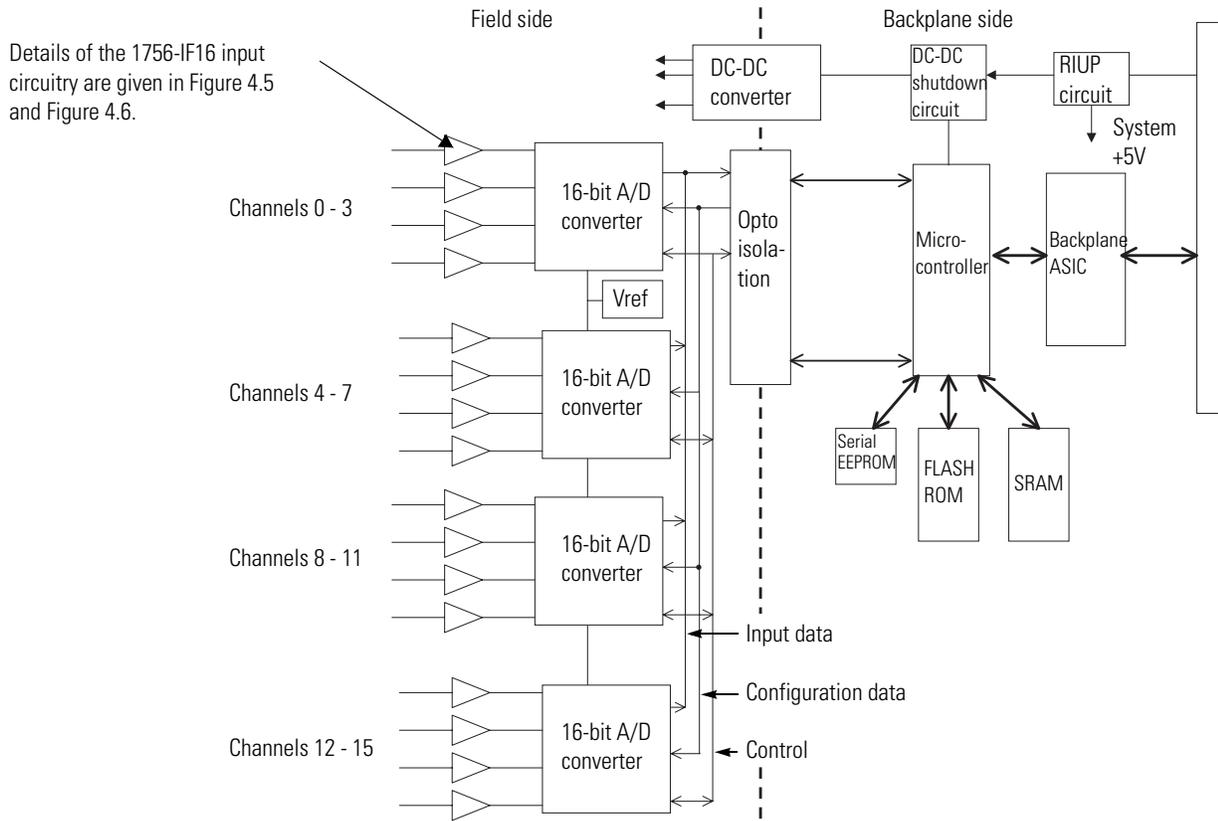
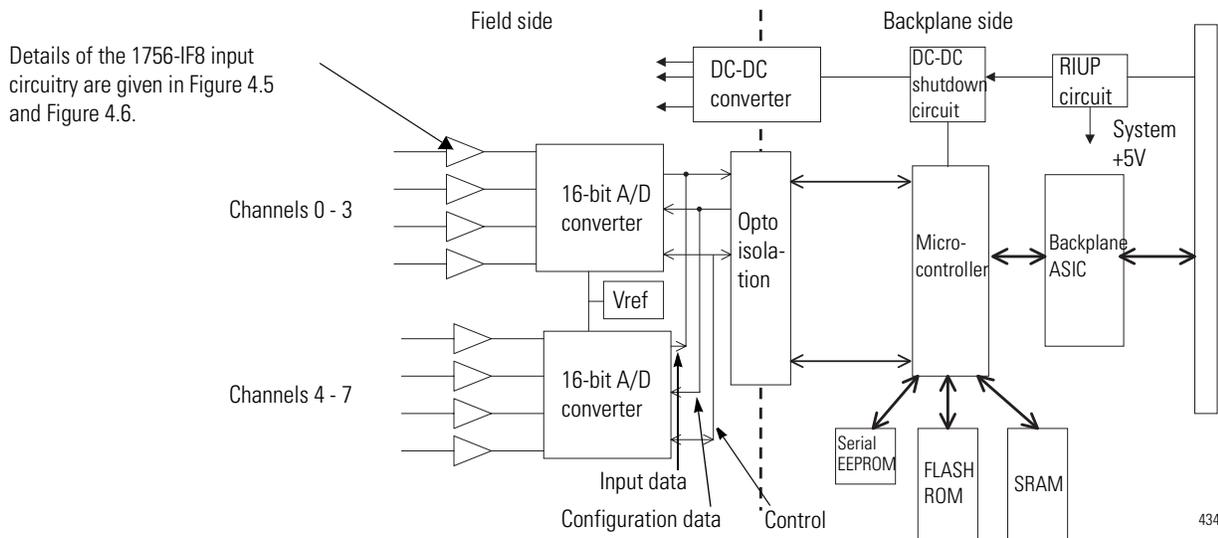


Figure 4.4 1756-IF8 Module Block Diagram



Field Side Circuit Diagrams

The field side circuit diagrams are the same for both the 1756-IF16 and 1756-IF8 modules.

Figure 4.5 1756-IF16 and 1756-IF8 Voltage Input Circuit

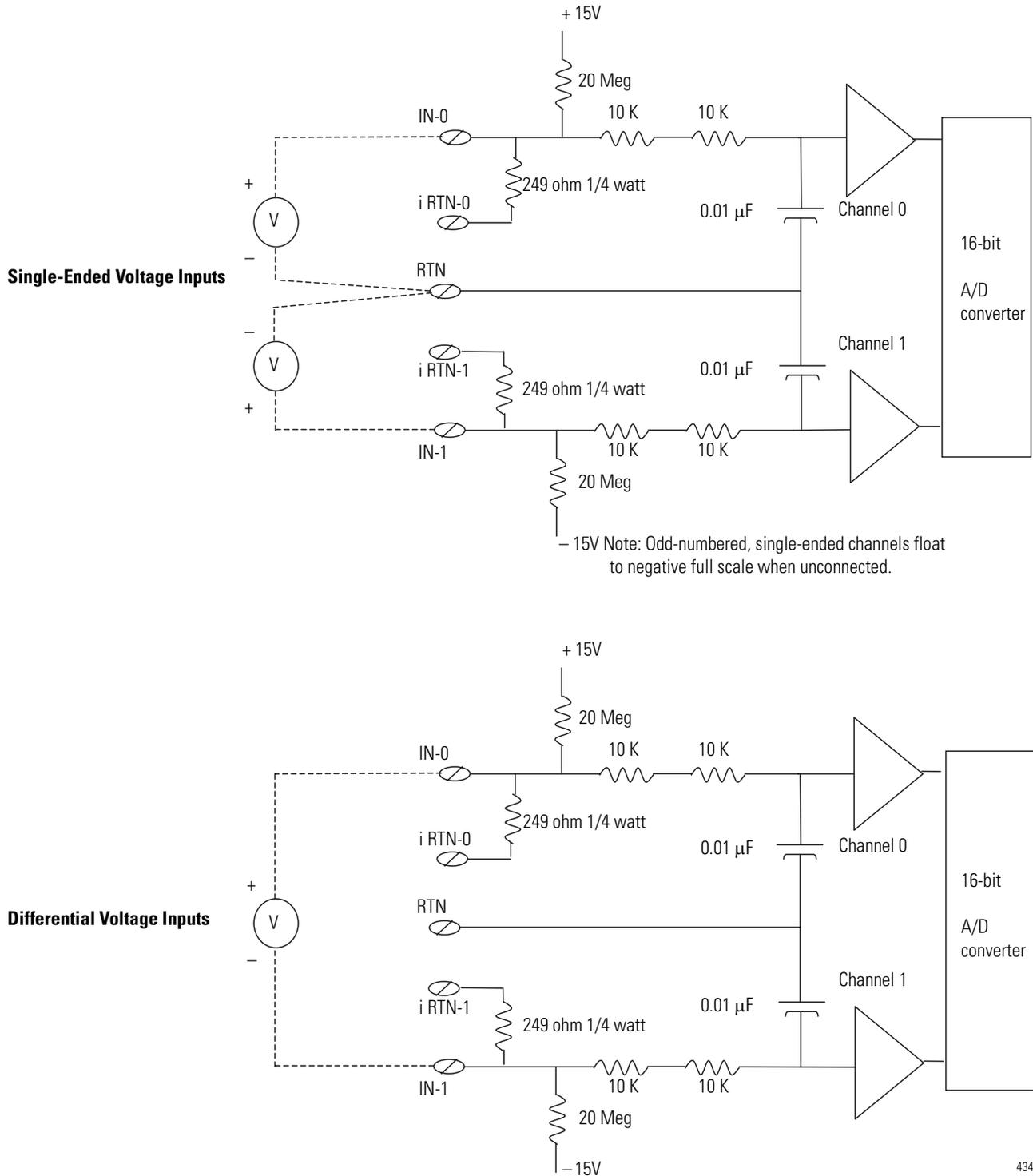
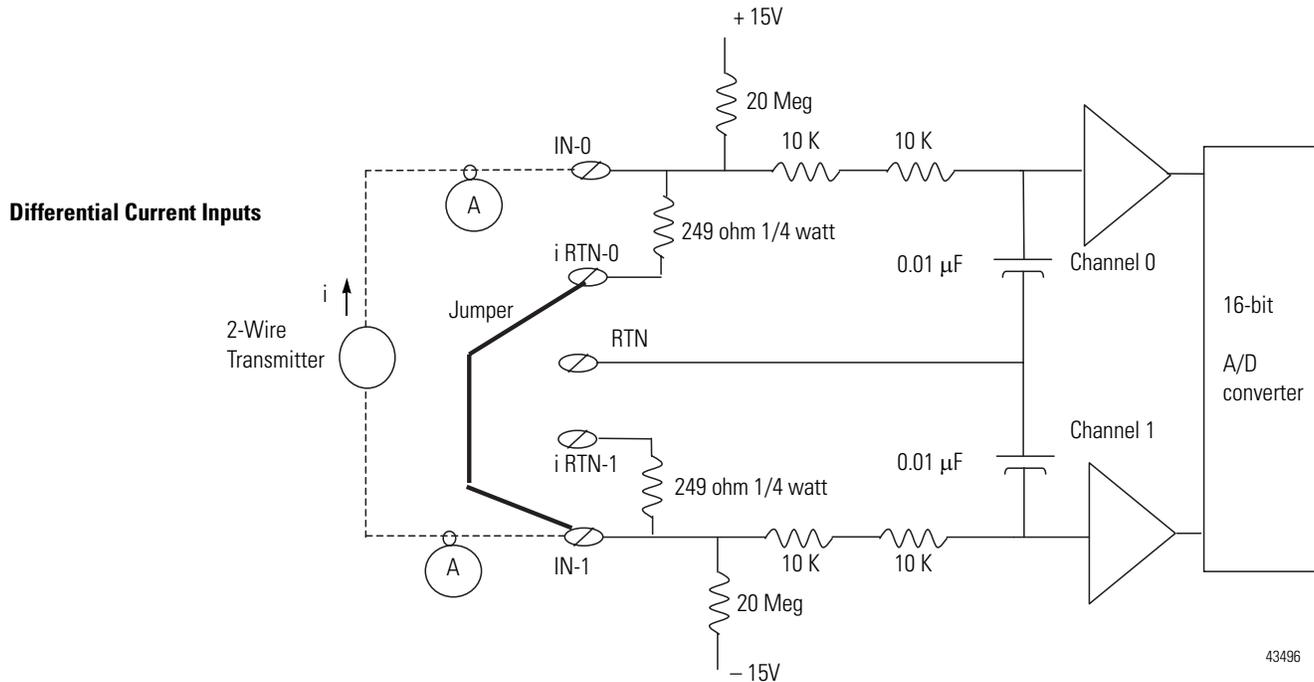
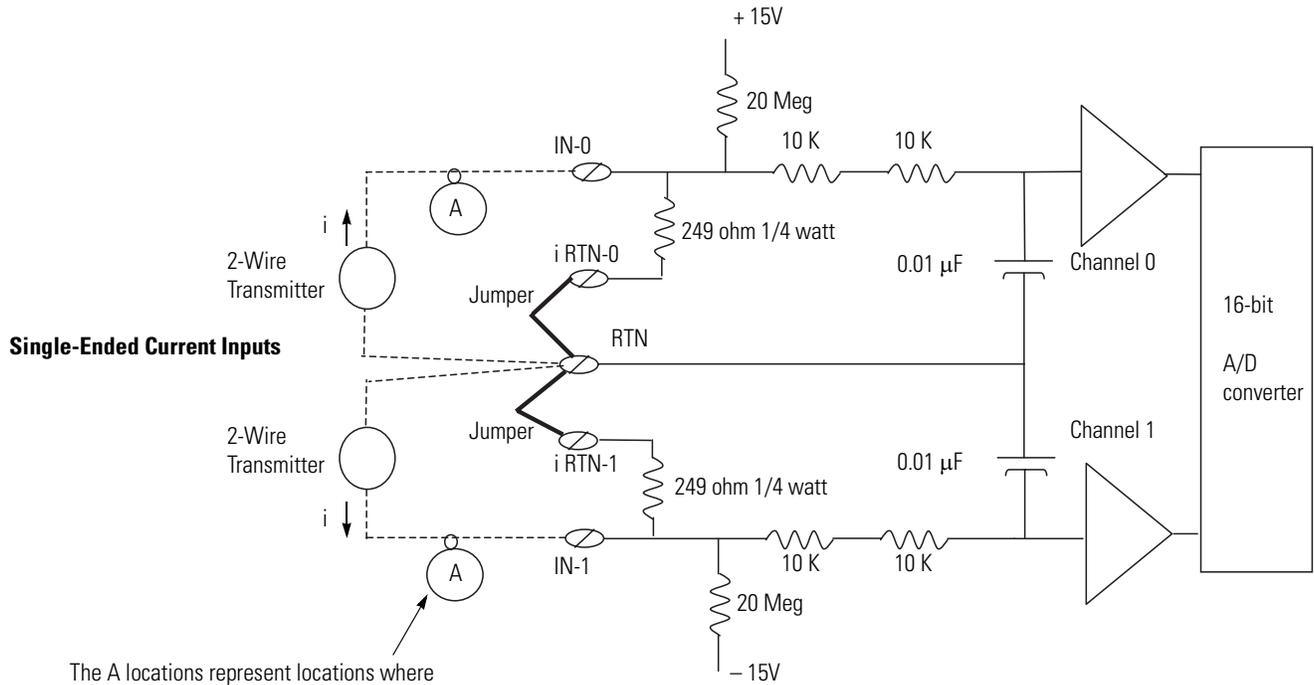


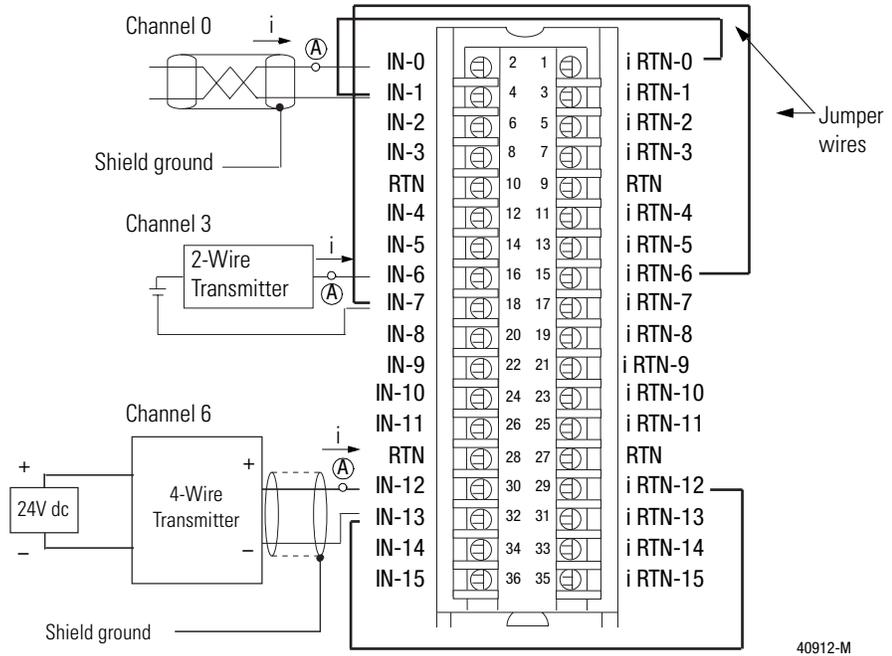
Figure 4.6 1756-IF16 and 1756-IF8 Current Input Circuit



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Wiring the 1756-IF16 Module

Figure 4.7 1756-IF16 Differential Current Wiring Example



40912-M

NOTES:

1. Use the Table D.8 when wiring your module in differential mode

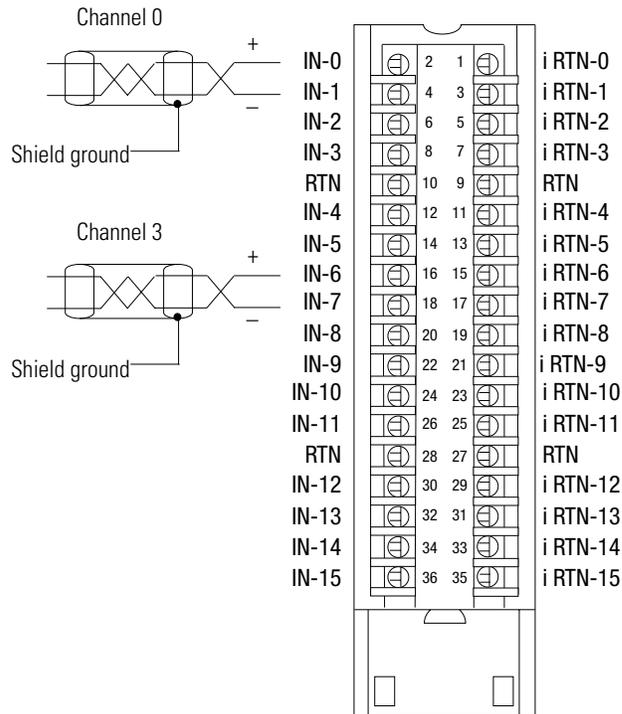
Table D.8

This channel:	Uses these terminals:	This channel:	Uses these terminals:
Channel 0	IN-0 (+), IN-1 (-) & i RTN-0	Channel 4	IN-8 (+), IN-9 (-) & i RTN-8
Channel 1	IN-2 (+), IN-3 (-) & i RTN-2	Channel 5	IN-10 (+), IN-11 (-) & i RTN-10
Channel 2	IN-4 (+), IN-5 (-) & i RTN-4	Channel 6	IN-12 (+), IN-13 (-) & i RTN-12
Channel 3	IN-6 (+), IN-7 (-) & i RTN-6	Channel 7	IN-14 (+), IN-15 (-) & i RTN-14

2. All terminals marked RTN are connected internally.
3. A 249Ω current loop resistor is located between IN-x and i RTN-x terminals.
4. If multiple (+) or multiple (-) terminals are tied together, connect that tie point to a RTN terminal to maintain the module's accuracy.
5. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location in the current loop.
6. Do not connect more than two wires to any single terminal.

IMPORTANT: When operating in 4 channel, **high speed mode**, only use channels 0, 2, 4 and 6.

Figure 4.8 1756-IF16 Differential Voltage Wiring Example



40913-M

NOTES:

1. Use the Table D.9 when wiring your module in differential mode

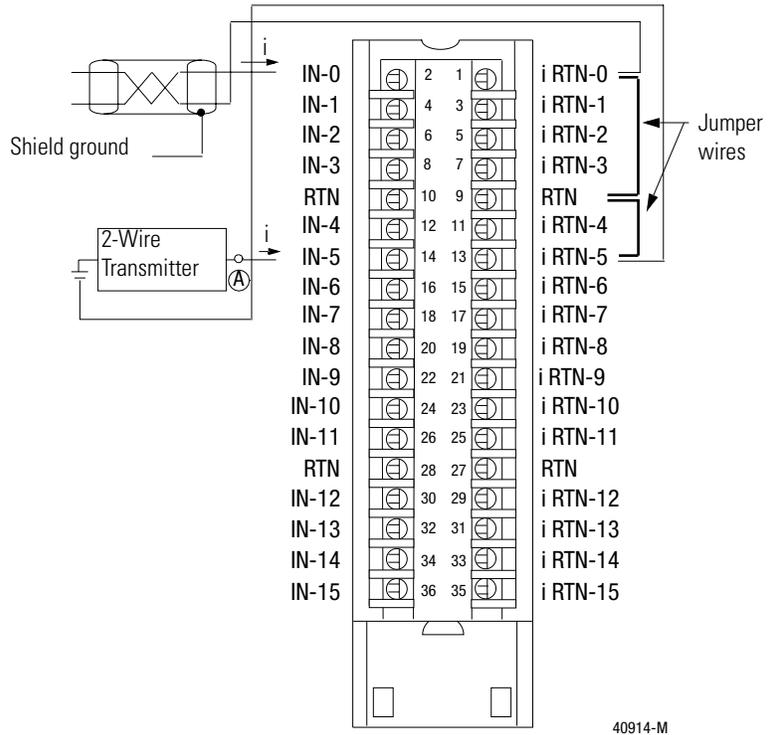
Table D.9

This channel:	Uses these terminals:	This channel:	Uses these terminals:
Channel 0	IN-0 (+) & IN-1 (-)	Channel 4	IN-8 (+) & IN-9 (-)
Channel 1	IN-2 (+) & IN-3 (-)	Channel 5	IN-10 (+) & IN-11 (-)
Channel 2	IN-4 (+) & IN-5 (-)	Channel 6	IN-12 (+) & IN-13 (-)
Channel 3	IN-6 (+) & IN-7 (-)	Channel 7	IN-14 (+) & IN-15 (-)

2. All terminals marked RTN are connected internally.
3. If multiple (+) or multiple (-) terminals are tied together, connect that tie point to a RTN terminal to maintain the module's accuracy.
4. Terminals marked RTN or iRTN are not used for differential voltage wiring.
5. Do not connect more than two wires to any single terminal.

IMPORTANT: When operating in 4 channel, **high speed mode**, only use channels 0, 2, 4 and 6.

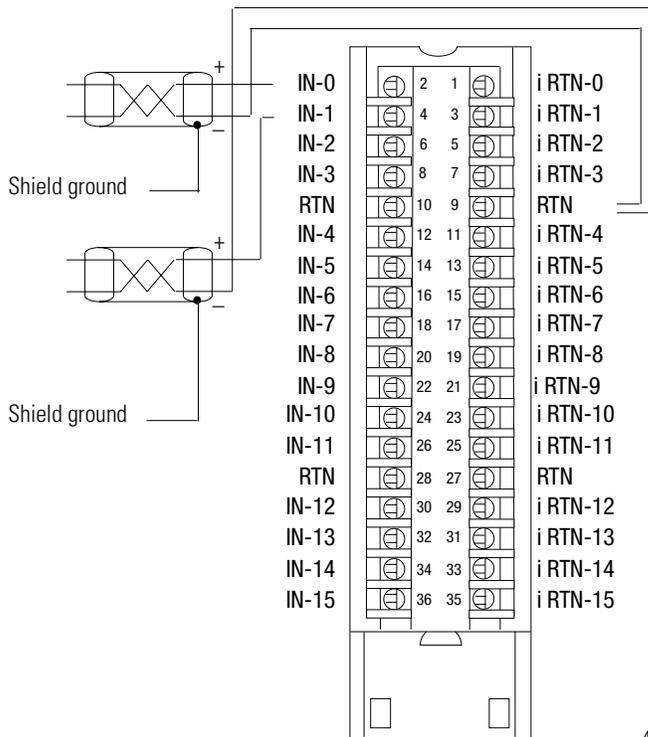
Figure 4.9 1756-IF16 Single-Ended Current Wiring Example



NOTES:

1. All terminals marked RTN are connected internally.
2. For current applications, all terminals marked iRTN must be wired to terminals marked RTN.
3. A 249Ω current loop resistor is located between IN-x and i RTN-x terminals.
4. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location in the current loop.
5. Do not connect more than two wires to any single terminal.

Figure 4.10 1756-IF16 Single-Ended Voltage Wiring Example

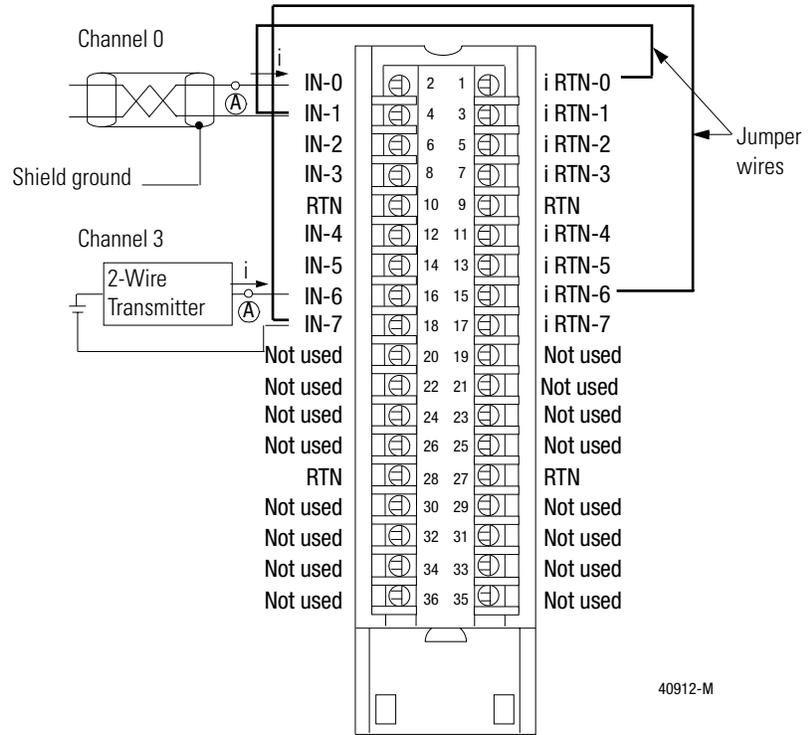


40915-M

NOTES:

1. All terminals marked RTN are connected internally.
2. Terminals marked iRTN are not used for single-ended voltage wiring.
3. Do not connect more than two wires to any single terminal.

Wiring the 1756-IF8 Module Figure 4.11 1756-IF8 Differential Current Wiring Example - 4 Channels



NOTES:

1. Use the Table 4.10 when wiring your module in differential mode

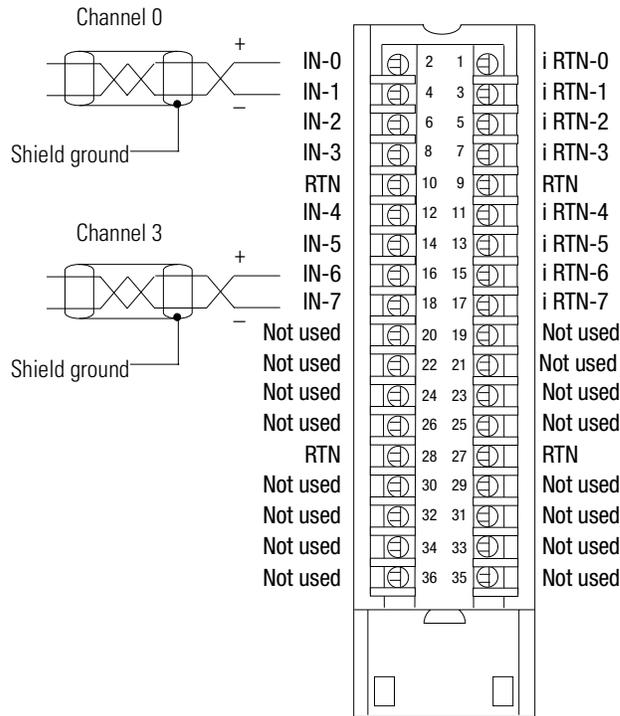
Table 4.10

This channel:	Uses these terminals:
Channel 0	IN-0 (+), IN-1 (-) & i RTN-0
Channel 1	IN-2 (+), IN-3 (-) & i RTN-2
Channel 2	IN-4 (+), IN-5 (-) & i RTN-4
Channel 3	IN-6 (+), IN-7 (-) & i RTN-6

2. All terminals marked RTN are connected internally.
3. A 249Ω current loop resistor is located between IN-x and i RTN-x terminals.
4. If multiple (+) or multiple (-) terminals are tied together, connect that tie point to a RTN terminal to maintain the module's accuracy.
5. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location in the current loop.
6. Do not connect more than two wires to any single terminal.

IMPORTANT: When operating in 2 channel, **high speed mode**, only use channels 0 and 2.

Figure 4.12 1756-IF8 Differential Voltage Wiring Example - 4 Channels



40913-M

NOTES:

1. Use the Table 4.11 when wiring your module in differential mode

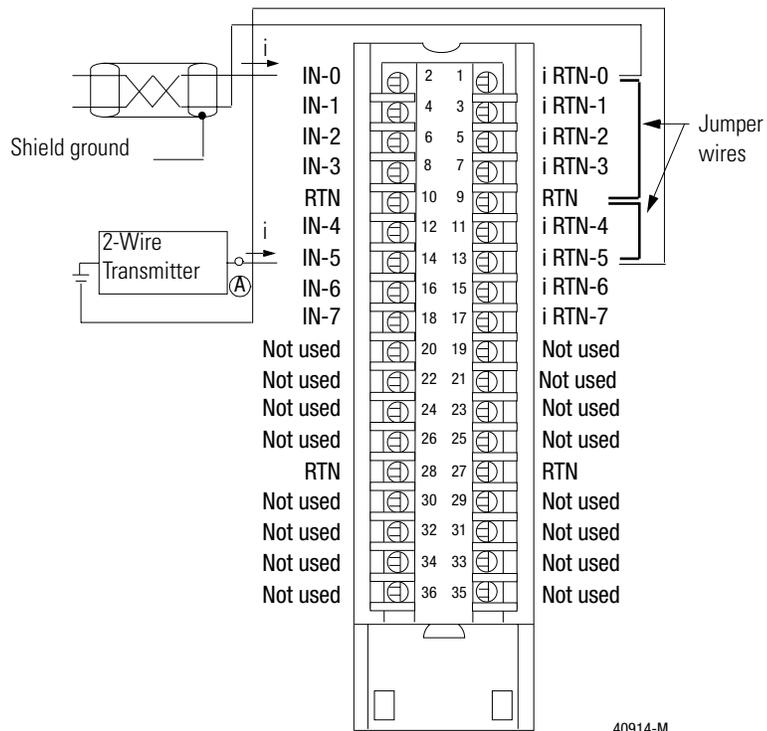
Table 4.11

This channel:	Uses these terminals:
Channel 0	IN-0 (+) & IN-1 (-)
Channel 1	IN-2 (+) & IN-3 (-)
Channel 2	IN-4 (+) & IN-5 (-)
Channel 3	IN-6 (+) & IN-7 (-)

2. All terminals marked RTN are connected internally.
3. If multiple (+) or multiple (-) terminals are tied together, connect that tie point to a RTN terminal to maintain the module's accuracy.
4. Terminals marked RTN or iRTN are not used for differential voltage wiring.
5. Do not connect more than two wires to any single terminal.

IMPORTANT: When operating in 2 channel, **high speed mode**, only use channels 0 and 2.

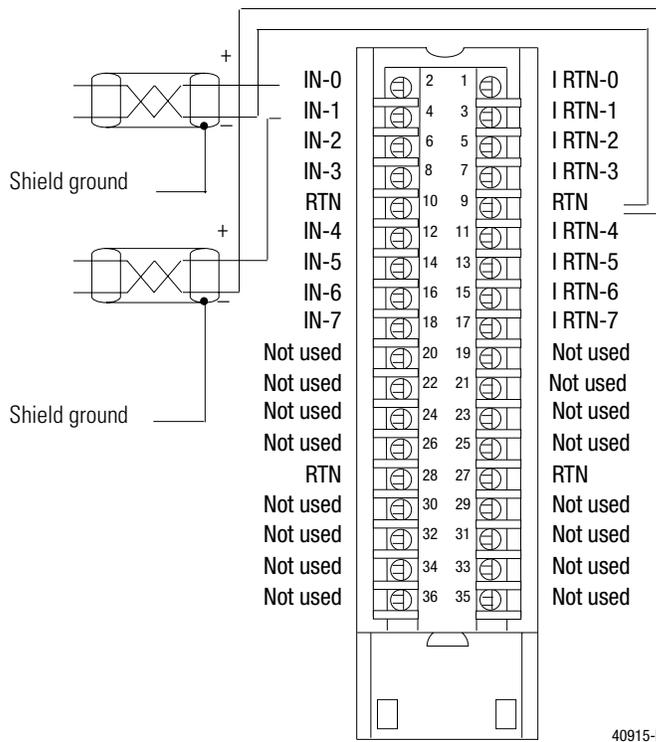
Figure 4.13 1756-IF8 Single-Ended Current Wiring Example



NOTES:

1. All terminals marked RTN are connected internally.
2. For current applications, all terminals marked iRTN must be wired to terminals marked RTN.
3. A 249Ω current loop resistor is located between IN-x and i RTN-x terminals.
4. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location in the current loop.
5. Do not connect more than two wires to any single terminal.

Figure 4.14 1756-IF8 Single-Ended Voltage Wiring Example



NOTES:

1. All terminals marked RTN are connected internally.
2. Terminals marked iRTN are not used for single-ended voltage wiring.
3. Do not connect more than two wires to any single terminal.

1756-IF16 Module Fault and Status Reporting

The 1756-IF16 module multicasts status/fault data to the owner/listening controller with its channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide an increasing degree of detail as to the specific cause of faults on the module.

Table 4.12 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.12

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults. When examining the Channel Fault Word for faults, remember the following: <ul style="list-style-type: none"> • 16 channels are used in single-ended wiring • 8 channels are used in differential wiring • 4 channels are used in high speed differential wiring • All bytes start with bit 0
Channel Status Words	These words, one per channel, provide individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

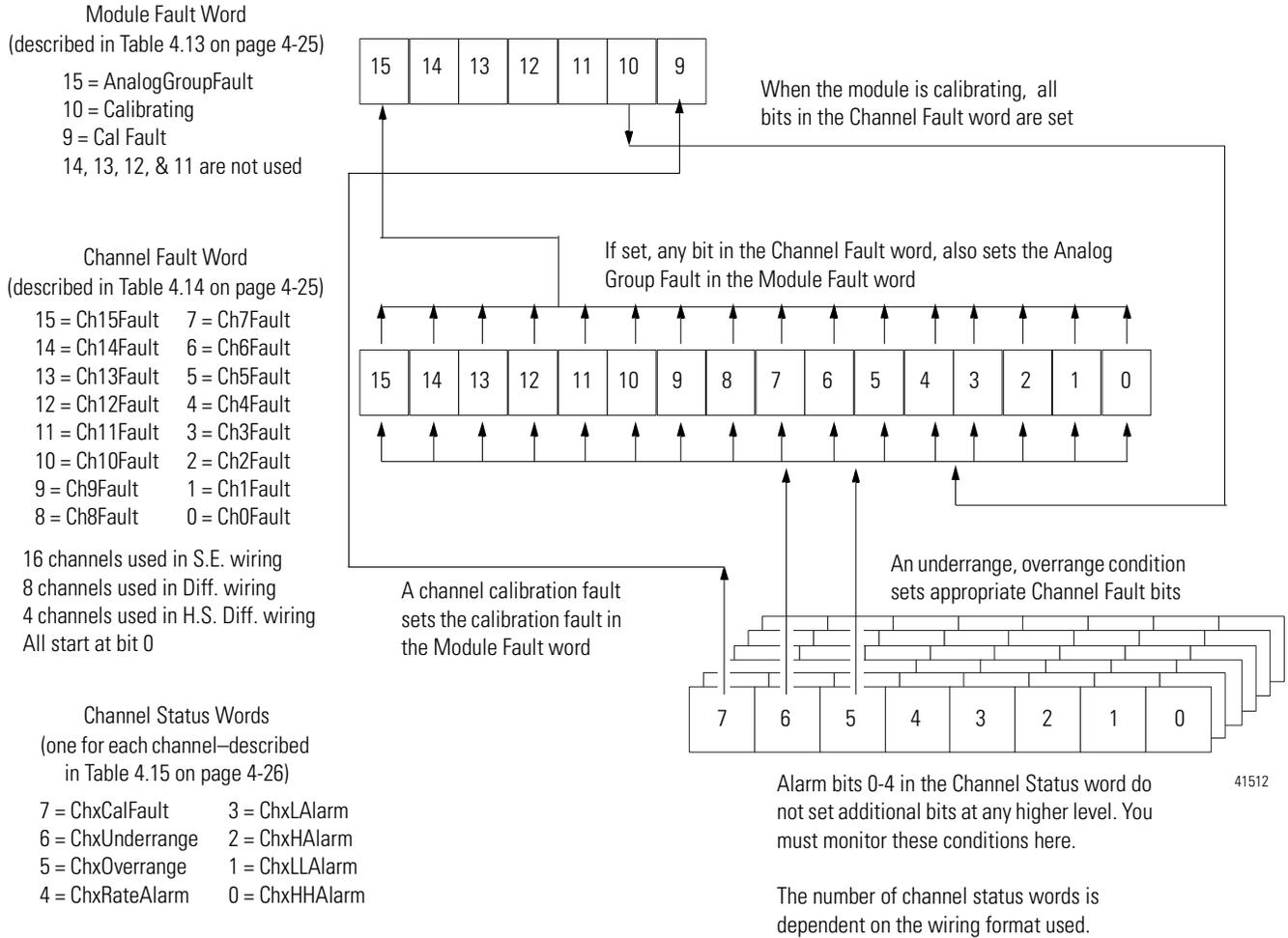
IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

1756-IF16 Fault Reporting in Floating Point Mode

Figure 4.15 an overview of the fault reporting process for the 1756-IF16 module in floating point mode.

Figure 4.15



1756-IF16 Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 4.13 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.13

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

1756-IF16 Channel Fault Word Bits – Floating Point Mode

During normal module operation, bits in the Channel Fault word are set if any of the respective channels has an Under or Overrange condition. Checking this word for a nonzero value is a quick way to check for Under or Overrange conditions on the module.

Table 4.14 lists the conditions that set **all** Channel Fault word bits:

Table 4.14

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	<ul style="list-style-type: none"> • “FFFF” for single-ended operating mode • “00FF” for differential operating mode • “000F” for high speed differential operating mode
A communications fault occurred between the module and its owner-controller	“FFFF” for all bits, regardless of the application

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

1756-IF16 Channel Status Word Bits – Floating Point Mode

Any of the Channel Status words, one for each channel, display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words. When the Underrange or Overrange bits (bits 6 & 5) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 4.15 lists the conditions that set each of the word bits.

Table 4.15

Tag (Status word):	Bit:	Event that sets this tag:
ChxCalFault	Bit 7	This bit is set if an error occurs during calibration for that channel, causing a bad calibration. This bit also sets bit 9 in the Module Fault word.
Underrange	Bit 6	This bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
Overrange	Bit 5	This bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxRateAlarm	Bit 4 ⁽¹⁾	This bit is set when the input channel's rate of change exceeds the configured Rate Alarm parameter. It remains set until the rate of change drops below the configured rate. If latched, the alarm will remain set until it is unlatched.
ChxLAlarm	Bit 3 ⁽¹⁾	This bit is set when the input signal moves beneath the configured Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 2 ⁽¹⁾	This bit is set when the input signal moves above the configured High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxLLAlarm	Bit 1 ⁽¹⁾	This bit is set when the input signal moves beneath the configured Low-Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain latched as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 0 ⁽¹⁾	This bit is set when the input signal moves above the configured High-High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain latched as long as the signal remains within the configured deadband.

⁽¹⁾ Bits 0-4 are **not available** in floating point single-ended mode.

1756-IF16 Fault Reporting in Integer Mode

The following graphic provides an overview of the fault reporting process for the 1756-IF16 module in integer mode.

Figure 4.16

Module Fault Word
(described in Table 4.16 on page 4-28)

- 15 = AnalogGroupFault
- 10 = Calibrating
- 9 = Cal Fault
- 14, 13, 12, & 11 are not used

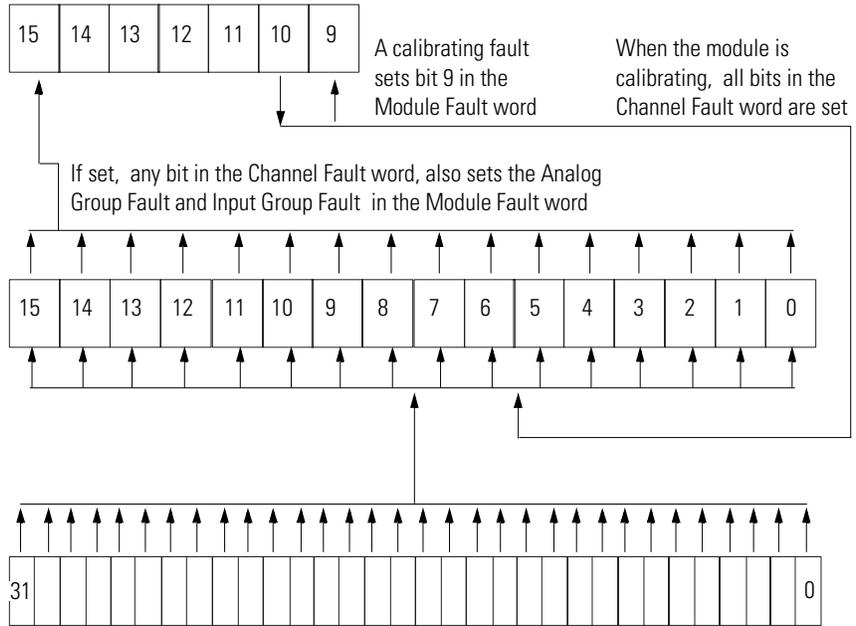
Channel Fault Word
(described in Table 4.17 on page 4-28)

- 15 = Ch15Fault 7 = Ch7Fault
- 14 = Ch14Fault 6 = Ch6Fault
- 13 = Ch13Fault 5 = Ch5Fault
- 12 = Ch12Fault 4 = Ch4Fault
- 11 = Ch11Fault 3 = Ch3Fault
- 10 = Ch10Fault 2 = Ch2Fault
- 9 = Ch9Fault 1 = Ch1Fault
- 8 = Ch8Fault 0 = Ch0Fault
- 16 channels used in S.E. wiring
- 8 channels used in Diff. wiring
- 4 channels used in H.S. Diff. wiring
- All start at bit 0

Channel Status Words
(described in Table 4.18 on page 4-29)

- 31 = Ch0Underrange 23 = Ch4Underrange 15 = Ch8Underrange 7 = Ch12Underrange
- 30 = Ch0Ovrrange 22 = Ch4Ovrrange 14 = Ch8Ovrrange 6 = Ch12Ovrrange
- 29 = Ch1Underrange 21 = Ch5Underrange 13 = Ch9Underrange 5 = Ch13Underrange
- 28 = Ch1Ovrrange 20 = Ch5Ovrrange 12 = Ch9Ovrrange 4 = Ch13Ovrrange
- 27 = Ch2Underrange 19 = Ch6Underrange 11 = Ch10Underrange 3 = Ch14Underrange
- 26 = Ch2Ovrrange 18 = Ch6Ovrrange 10 = Ch10Ovrrange 2 = Ch14Ovrrange
- 25 = Ch3Underrange 17 = Ch7Underrange 9 = Ch11Underrange 1 = Ch15Underrange
- 24 = Ch3Ovrrange 16 = Ch7Ovrrange 8 = Ch11Ovrrange 0 = Ch15Ovrrange

- 16 channels used in S.E. wiring
- 8 channels used in Diff. wiring
- 4 channels used in H.S. Diff. wiring
- All start at bit 31



Underrange and overrange conditions set the corresponding Channel Fault word bit for that channel

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1756-IF16 Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-8) operate exactly as described in floating point mode. Table 4.16 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.16

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

1756-IF16 Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits operate exactly as described in floating point mode. Table 4.17 lists the conditions that set **all** Channel Fault word bits:

Table 4.17

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	<ul style="list-style-type: none"> • "FFFF" for single-ended operating mode • "00FF" for differential operating mode • "000F" for high speed differential operating mode
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits, regardless of the application

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

1756-IF16 Channel Status Word Bits – Integer Mode

The Channel Status word has the following differences when the 1756-IF16 module is used in integer mode:

- Only Underrange and Overrange conditions are reported by the module.
- Alarming and Calibration Fault activities are not available, although the Calibration Fault bit in the Module Fault word activates if a channel is not properly calibrated.
- There is one 32 bit Channel Status word for all 16 channels.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 4.18 lists the conditions that set each of the words.

Table 4.18

Tag (Status word):	Bit:	Event that sets this tag:
ChxUnderrange	Odd-numbered bits from bit 31 to bit 1 (e.g. bit 31 represents channel 0). For a full listing of the channels these bits represent, see Figure 4.16 on page 4-27.	The underrange bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxOverrange	Even-numbered bits from bit 30 to bit 0 (e.g. bit 30 represents channel 0). For a full listing of the channels these bits represent, see Figure 4.16 on page 4-27.	The overrange bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.

1756-IF8 Module Fault and Status Reporting

The 1756-IF8 module multicasts status/fault data to the owner/listening controller with its channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide an increasing degree of detail as to the specific cause of faults on the module.

Table 4.19 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.19

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults. When examining the Channel Fault Word for faults, remember the following: <ul style="list-style-type: none"> • 8 channels are used in single-ended wiring • 4 channels are used in differential wiring • 2 channels are used in high speed differential wiring • All bytes start with bit 0
Channel Status Words	These words, one per channel, provide individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

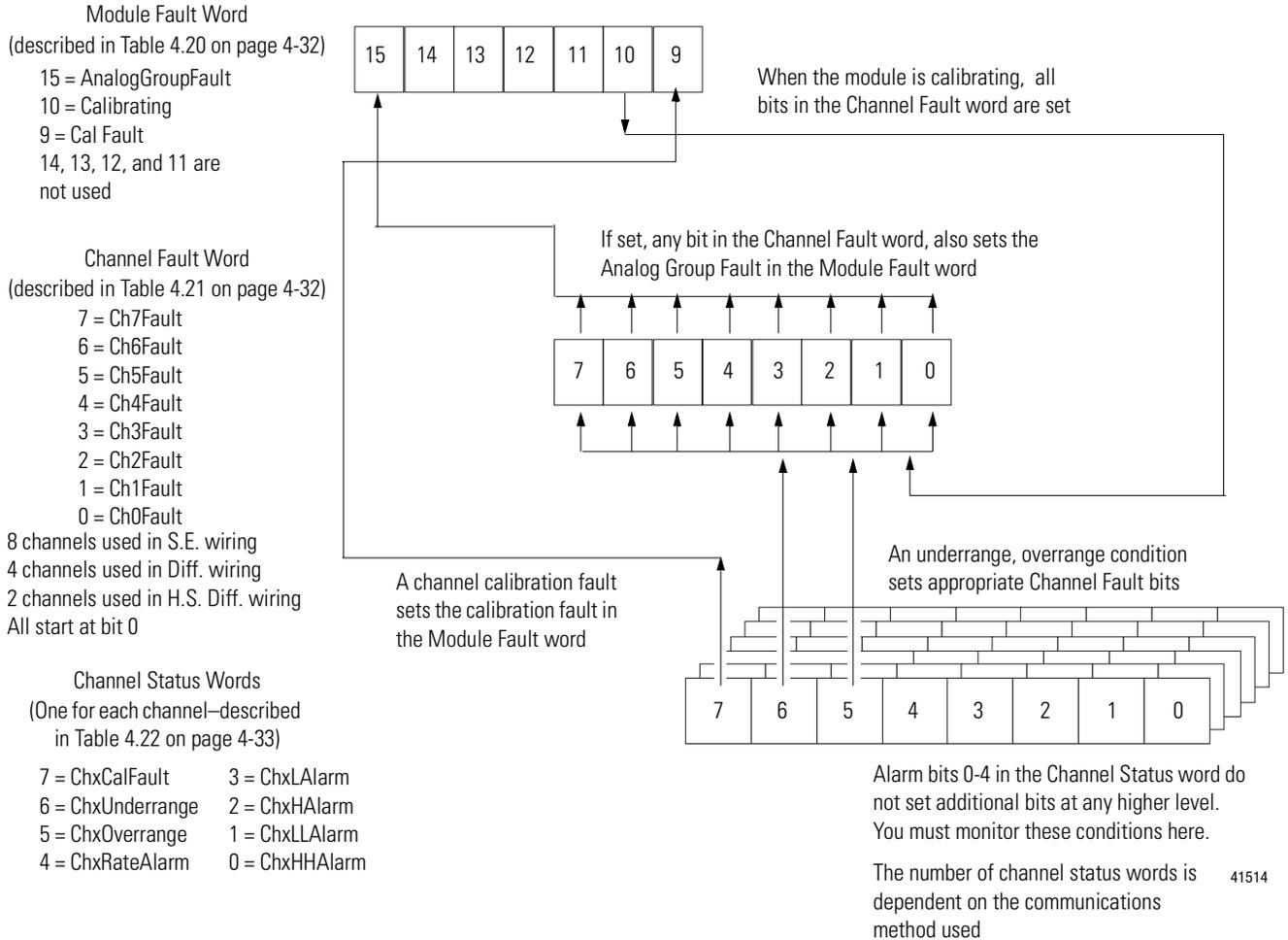
IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

1756-IF8 Fault Reporting in Floating Point Mode

Figure 4.17 offers an overview of the fault reporting process for the 1756-IF8 module in floating point mode.

Figure 4.17



1756-IF8 Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 4.20 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.20

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

1756-IF8 Channel Fault Word Bits – Floating Point Mode

During normal module operation, bits in the Channel Fault word are set if any of the respective channels has an Under or Overrange condition. Checking this word for a nonzero value is a quick way to check for Under or Overrange conditions on the module.

Table 4.21 lists the conditions that set **all** Channel Fault word bits:

Table 4.21

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	<ul style="list-style-type: none"> • "00FF" for single-ended wiring applications • "000F" for differential wiring applications • "0003" for high speed differential wiring applications
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits, regardless of the application

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

1756-IF8 Channel Status Word Bits – Floating Point Mode

Any of the Channel Status words, one for each channel, will display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words. When the Underrange and Overrange bits (bits 6 & 5) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 4.22 lists the conditions that set each of the word bits.

Table 4.22

Tag (Status word):	Bit:	Event that sets this tag:
ChxCalFault	Bit 7	This bit is set if an error occurs during calibration for that channel, causing a bad calibration. This bit also sets bit 9 in the Module Fault word.
Underrange	Bit 6	This bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
Overrange	Bit 5	This bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxRateAlarm	Bit 4	This bit is set when the input channel's rate of change exceeds the configured Rate Alarm parameter. It remains set until the rate of change drops below the configured rate. If latched, the alarm will remain set until it is unlatched.
ChxLAlarm	Bit 3	This bit is set when the input signal moves beneath the configured Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 2	This bit is set when the input signal moves above the configured High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxLLAlarm	Bit 1	This bit is set when the input signal moves beneath the configured Low-Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain latched as long as the signal remains within the configured deadband.
ChxHHighAlarm	Bit 0	This bit is set when the input signal moves above the configured High-High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain latched as long as the signal remains within the configured deadband.

1756-IF8 Fault Reporting in Integer Mode

Figure 4.18 offers an overview of the fault reporting process for the 1756-IF8 module in integer mode.

Figure 4.18

Module Fault Word
(described in Table 4.23 on page 4-35)

- 15 = AnalogGroupFault
- 10 = Calibrating
- 9 = Cal Fault
- 14, 13, 12, & 11 are not used by 1756-IF8

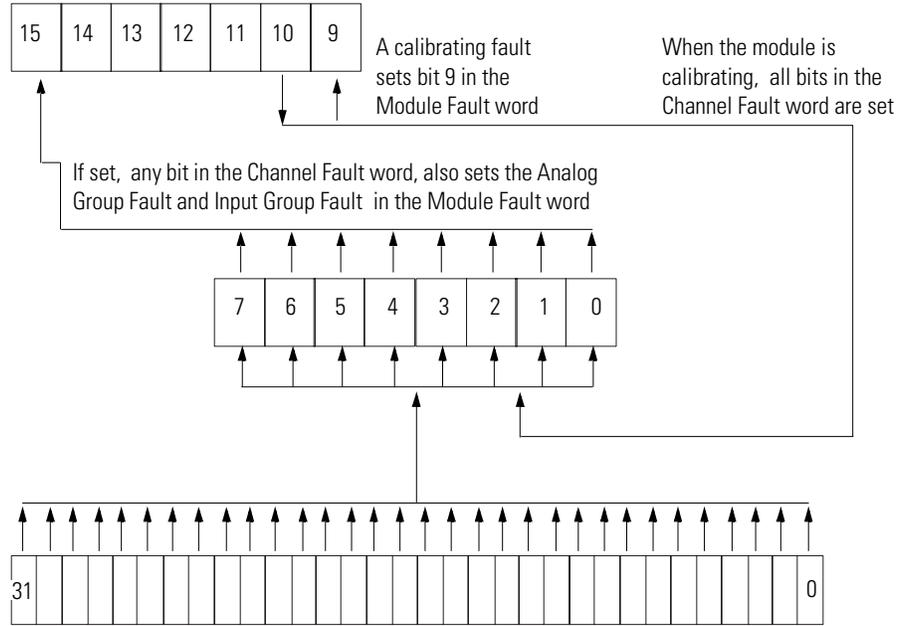
Channel Fault Word
(described in Table 4.24 on page 4-35)

- 7 = Ch7Fault 3 = Ch3Fault
- 6 = Ch6Fault 2 = Ch2Fault
- 5 = Ch5Fault 1 = Ch1Fault
- 4 = Ch4Fault 0 = Ch0Fault

8 channels used in S.E. wiring
4 channels used in Diff. wiring
2 channels used in H.S. Diff. wiring
All start at bit 0

Channel Status Words
(described in Table 4.18 on page 4-29)

- 31 = Ch0Underrange 23 = Ch4Underrange
- 30 = Ch0Overrange 22 = Ch4Overrange
- 29 = Ch1Underrange 21 = Ch5Underrange
- 28 = Ch1Overrange 20 = Ch5Overrange
- 27 = Ch2Underrange 19 = Ch6Underrange
- 26 = Ch2Overrange 18 = Ch6Overrange
- 25 = Ch3Underrange 17 = Ch7Underrange
- 24 = Ch3Overrange 16 = Ch7Overrange



8 channels used in S.E. wiring
4 channels used in Diff. wiring
2 channels used in H.S. Diff. wiring
All start at bit 31

Underrange and overrange conditions set the corresponding Channel Fault word bit for that channel

1756-IF8 Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-8) operate exactly as described in floating point mode. Table 4.23 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 4.23

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

1756-IF8 Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits operate exactly as described in floating point mode. Table 4.24 lists the conditions that set **all** Channel Fault word bits:

Table 4.24

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	<ul style="list-style-type: none"> • "00FF" for single-ended wiring applications • "000F" for differential wiring applications • "0003" for high speed differential wiring applications
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits, regardless of the application

1756-IF8 Channel Status Word Bits – Integer Mode

The Channel Status word has the following differences when the 1756-IF16 module is used in integer mode:

- Only Underrange and Overrange conditions are reported by the module.
- Alarming and Calibration Fault activities are not available, although the Calibration Fault bit in the Module Fault word activates if a channel is not properly calibrated.
- There is one 32 bit Channel Status word for all 8 channels.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 4.25 lists the conditions that set each of the words.

Table 4.25

Tag (Status word):	Bit:	Event that sets this tag:
ChxUnderrange	Odd-numbered bits from bit 31 to bit 1 (e.g. bit 31 represents channel 17). For a full listing of the channels these bits represent, see Figure 4.18 on page 4-34.	The underrange bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxOverrange	Even-numbered bits from bit 30 to bit 16 (e.g. bit 30 represents channel 0). For a full listing of the channels these bits represent, see Figure 4.18 on page 4-34.	The overrange bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 4.6 on page 4-7. This bit also sets the appropriate bit in the Channel Fault word.

Chapter Summary and What's Next

In this chapter you read about the Non-Isolated Analog Voltage/Current Input Modules (1756-IF16, -IF8).

Chapter 5 describes features specific to the Sourcing Current Loop Input Module (1756-IF6CIS) and Isolated Analog Voltage/Current Input Module (1756-IF6I).

Sourcing Current Loop Input Module (1756-IF6CIS) and Isolated Analog Voltage/Current Input Module (1756-IF6I)

What This Chapter Contains

This chapter describes features specific to ControlLogix isolated analog voltage/current input module and the ControlLogix sourcing current loop input module.

For information about:	See page:
Using the Isolated Power Source on the 1756-IF6CIS	5-2
Choosing a Data Format	5-4
Features Specific to the 1756-IF6I and 1756-IF6CIS Modules	5-4
Using Module Block and Input Circuit Diagrams	5-12
Wiring the 1756-IF6CIS Module	5-14
Wiring the 1756-IF6I Module	5-17
1756-IF6CIS or 1756-IF6I Module Fault and Status Reporting	5-19

IMPORTANT

The 1756-IF6CIS and 1756-IF6I modules primarily operate the same with a few exceptions, including:

- The 1756-IF6CIS only operates in current mode
- The 1756-IF6CIS offers an isolated power source for each channel that supplies power to external transmitters

The differences on the 1756-IF6CIS module are described on page 5-2.

With a few noted exceptions included in the descriptions, the rest of the features described in this chapter apply to both modules.

Using the Isolated Power Source on the 1756-IF6CIS

The 1756-IF6CIS module offers an internal power source on each channel. The source is current limited to 28mA and allows the module to power a two-wire transmitter directly without the need for an external power supply. The transmitter can then vary the current to the analog input in proportion to the process variable being measured. The inclusion of an internal on-board current source, saves you the expense of extra power supplies and greatly simplifies the interface wiring to field devices.

In addition to supplying loop power to 2-wire transmitters, the module can also accommodate current loops powered by an external supply and loops using 4-wire transmitters.

Power Calculations with the 1756-IF6CIS Module

The 1756-IF6CIS module uses the system power supply (1756-Px7x) as the source for loop power. Because of the demands placed on that supply (e.g. the 1756-IF6CIS module consumes 7.9W of backplane power), special care must be taken when calculating the power requirements for modules in the same chassis as a 1756-IF6CIS module.

For example, when used with the 1756-L55M13 controller, you can place only 8 1756-IF6CIS modules in the chassis before exceeding the wattage capacity of the power supply.

Including Other Devices in the Wiring Loop

The voltage source on each channel can drive loop impedance of up to 1000 ohms. This allows you to include other devices, such as chart recorders and meters, in the current loop.

For more information on wiring the 1756-IF6CIS module, see page 5-14.

The 1756-IF6CIS and 1756-IF6I modules also support features described in Chapter 3. Table 5.1 lists those additional features.

Table 5.1 Additional Features Supported by the 1756-IF6CIS and 1756-IF6I Modules

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Choosing a Data Format

Data format determines the format of the data returned from the module to the owner-controller and the features that are available to your application. You choose a data format when you choose a Communications Format. For more information on Communications Format, see page 10-6.

You can choose one of the two following data formats:

- Integer mode
- Floating point mode

Table 5.2 shows which features are available in each format.

Table 5.2 Features Available in Each Data Format

Data format:	Features available:	Features not available:
Integer mode	Multiple input ranges Notch filter Real time sampling	Digital filtering Process alarms Rate alarms Scaling
Floating point mode	All features	N/A

Features Specific to the 1756-IF6I and 1756-IF6CIS Modules

Table 5.3 lists features that are specific to the 1756-IF6CIS and 1756-IF6I modules. The features are described later in this section.

Table 5.3

Feature:	Page of description:
Multiple Input Ranges ⁽¹⁾	5-5
Notch Filter	5-6
Real Time Sampling	5-7
Underrange/Ovrrange Detection	5-7
Digital Filter	5-8
Process Alarms	5-9
Rate Alarm	5-10
Wire Off Detection	5-11

⁽¹⁾ Only the 1756-IF6I offers multiple input ranges. The 1756-IF6CIS module only operates in the 0 to 20mA range.

Multiple Input Ranges

You can only use the 1756-IF6CIS module in current applications. Unlike other analog input modules, this module does not allow you to choose an input range. All channels use the 0 to 20mA input range.

For the 1756-IF6I module, however, you can select from a series of operational ranges for **each channel** on your module. The range designates the minimum and maximum signals that are detectable by the module. The 1756-IF6I module offers multiple input ranges in both current and voltage applications.

Table 5.4 lists the possible input ranges available for use with the 1756-IF6CIS and 1756-IF6I modules.

Table 5.4 Possible Input Ranges

Module:	Available input ranges:
1756-IF6CIS	0 to 20mA
1756-IF6I	-10 to 10V 0 to 5V 0 to 10V 0 to 20mA

For an example of how to choose an input range for your module, see page 10-10.

Notch Filter

An Analog-to-Digital Converter (ADC) filter removes line noise in your application for **each channel**.

Choose a notch filter that most closely matches the anticipated noise frequency in your application. Remember that each filter time affects the response time of your module. Also, the highest frequency notch filter settings also limit the effective resolution of the channel.

IMPORTANT

60Hz is the default setting for the notch filter.

Table 5.5 lists the available notch filter setting.

Table 5.5 Module Filter Settings

Notch setting:	10Hz	50Hz	60Hz (Default)	100Hz	250Hz	1000Hz
Minimum Sample Time (RTS)– Integer mode ⁽¹⁾	102mS	22mS	19mS	12mS	10mS	10mS
Minimum Sample Time (RTS)– Floating point mode ⁽²⁾	102mS	25mS	25mS	25mS	25mS	25mS
0-100% Step Response Time ⁽²⁾	400mS + RTS	80mS + RTS	68mS + RTS	40mS + RTS	16mS + RTS	4mS + RTS
-3dB Frequency	3Hz	13Hz	15Hz	26Hz	66Hz	262Hz
Effective Resolution	16 bits	16 bits	16 bits	16 bits	15 bits	10 bits

⁽¹⁾ Integer mode must be used for RTS values lower than 25mS. The minimum RTS value for the module will be dependent on the channel with the lowest notch filter setting.

⁽²⁾ Worst case settling time to 100% of a step change would include 0-100% step response time plus one RTS sample time.

To see how to choose a Notch Filter, see page 10-11.

Real Time Sampling

This parameter instructs the module to scan its input channels and obtain all available data. After the channels are scanned, the module multicasts that data.

During module configuration, you specify a Real Time Sampling (RTS) period and a Requested Packet Interval (RPI) period. These features both instruct the module to multicast data, but only the RTS feature instructs the module to scan its channels before multicasting.

For more information on Real Time Sampling, see page 2-4. For an example of how to set the RTS rate, see page 10-10.

Underrange/Overrange Detection

This feature detects when the isolated input module is operating beyond limits set by the input range. For example, If you are using the 1756-IF6I module in the 0V-10V input range and the module voltage increases to 11V, the Overrange detection detects this condition.

Table 5.6 lists the input ranges of the 1756-IF6CIS and 1756-IF6I modules and the lowest/highest signal available in each range before the module detects an underrange/overrange condition:

Table 5.6 Low and High Signal Limits on the Isolated Input Module

Input module:	Available range:	Lowest signal in range:	Highest signal in range:
1756-IF6CIS	0mA-20mA	0mA	21.09376mA
1756-IF6I	+/- 10V	-10.54688V	10.54688V
	0V-10V	0V	10.54688V
	0V-5V	0V	5.27344V
	0mA-20mA	0mA	21.09376mA

Digital Filter

IMPORTANT

The digital filter is only available in applications using floating point mode.

The digital filter smooths input data noise transients on **each input channel**. This value specifies the time constant for a digital first order lag filter on the input. It is specified in units of milliseconds. A value of 0 disables the filter.

The digital filter equation is a classic first order lag equation.

$$Y_n = Y_{n-1} + \frac{[\Delta t]}{\Delta t + T_A} (X_n - Y_{n-1})$$

Y_n = present output, filtered peak voltage (PV)

Y_{n-1} = previous output, filtered PV

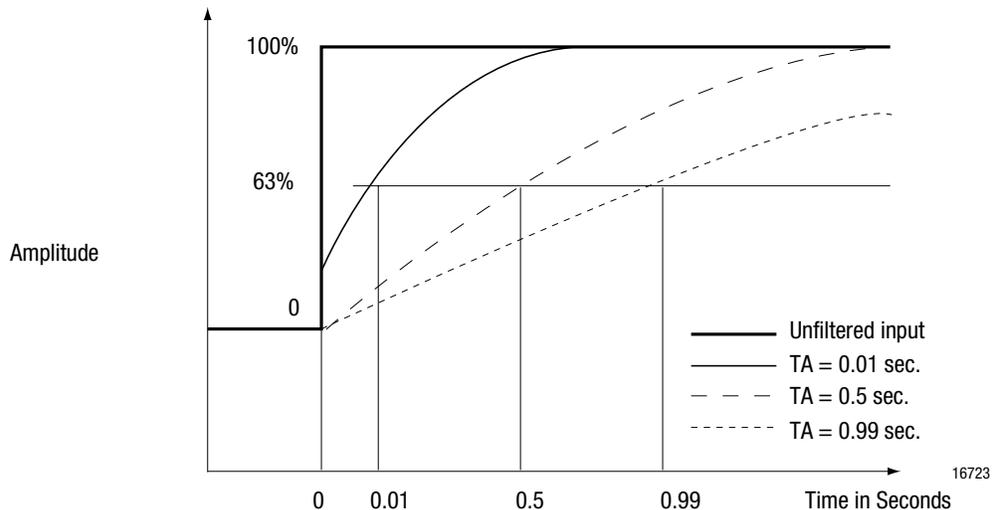
Δt = module channel update time (seconds)

T_A = digital filter time constant (seconds)

X_n = present input, unfiltered PV

Using a step input change to illustrate the filter response, you can see that when the digital filter time constant elapses, 63.2% of the total response is reached. Each additional time constant achieves 63.2% of the remaining response. For more information, see Figure 5.1.

Figure 5.1



To see how to set the Digital Filter, see page 10-10.

Process Alarms

Process alarms alert you when the module has exceeded configured high or low limits for **each channel**. You can latch process alarms. These are set at four user configurable alarm trigger points:

- High high
- High
- Low
- Low low

IMPORTANT

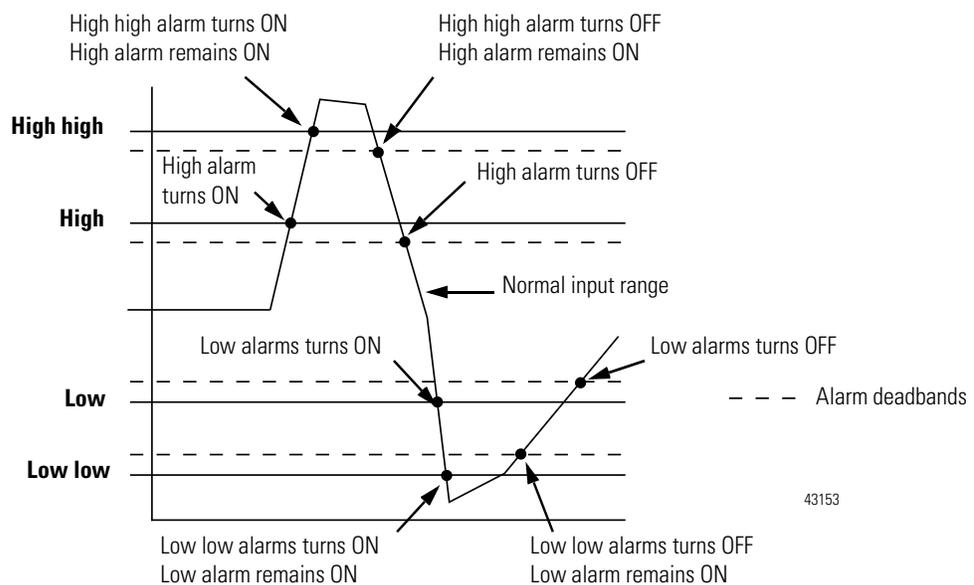
Process alarms are only available in applications using floating point mode. The values for each limit are entered in scaled engineering units.

Alarm Deadband

You may configure an **Alarm Deadband** to work with these alarms. The deadband allows the process alarm status bit to remain set, despite the alarm condition disappearing, as long as the input data remains within the deadband of the process alarm.

Figure 5.2 shows input data that sets each of the four alarms at some point during module operation. In this example, Latching is disabled; therefore, each alarms turns OFF when the condition that caused it to set ceases to exist.

Figure 5.2



To see how to set Process Alarms, see page 10-10.

Rate Alarm

The rate alarm triggers if the rate of change between input samples for **each channel** exceeds the specified trigger point for that channel.

IMPORTANT

The rate alarm is only available in applications using floating point mode.

EXAMPLE**1756-IF6CIS**

For example, if you set an 1756-IF6I (with normal scaling in mA) to a rate alarm of 1.0 mA/S, the rate alarm only triggers if the difference between measured input samples changes at a rate > 1.0 mA/S.

If the module's RTS is 100 ms (i.e. sampling new input data every 100ms) and at time 0, the module measures 5.0mA and at time 100ms measures 5.08mA, the rate of change is $(5.08\text{mA} - 5.0\text{mA}) / (100\text{mS}) = 0.8\text{mA/S}$. The rate alarm would not set as the change is less than the trigger point of 1.0mA/s.

If the next sample taken is 4.9mA, the rate of change is $(4.9\text{mA} - 5.08\text{mA}) / (100\text{mS}) = -1.8\text{mA/S}$. The absolute value of this result is $> 1.0\text{mA/S}$, so the rate alarm will set. Absolute value is used because rate alarm checks for the magnitude of the rate of change being beyond the trigger point, whether a positive or negative excursion.

1756-IF6I

For example, if you set an 1756-IF6I (with normal scaling in Volts) to a rate alarm of 1.0 V/S, the rate alarm only triggers if the difference between measured input samples changes at a rate > 1.0 V/S.

If the module's RTS is 100 ms (i.e. sampling new input data every 100ms) and at time 0, the module measures 5.0 volts and at time 100ms measures 5.08 V, the rate of change is $(5.08\text{V} - 5.0\text{V}) / (100\text{mS}) = 0.8$ V/S. The rate alarm would not set as the change is less than the trigger point of 1.0V/s.

If the next sample taken is 4.9V, the rate of change is $(4.9\text{V} - 5.08\text{V}) / (100\text{mS}) = -1.8\text{V/S}$. The absolute value of this result is $> 1.0\text{V/S}$, so the rate alarm will set. Absolute value is used because rate alarm checks for the magnitude of the rate of change being beyond the trigger point, whether a positive or negative excursion.

To see how to set the Rate Alarm, see page 10-10.

Wire Off Detection

The 1756-IF6CIS and 1756-IF6I modules will alert you when a wire has been disconnected from one of its channels or the RTB has been removed from the module. When a wire off condition occurs for this module, two events occur:

- Input data for that channel changes to a specific scaled value
- A fault bit is set in the owner-controller which may indicate the presence of a wire off condition

Because the 1756-IF6I module can be used in voltage or current applications, differences exist as to how a wire off condition is detected in each application. The 1756-IF6CIS module can only be used in current mode. Table 5.7 lists the differences that occur when a wire off condition occurs in various applications.

Table 5.7

When the Wire Off condition occurs in this application:	The following events occur:
Voltage Applications 1756-IF6I only	<ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the overrange signal value of the selected operational range in floating point mode (maximum possible scaled value) or 32,767 counts in integer mode • The ChxOvrerrange (x=channel number) tag is set to 1
Current Applications	<p>When the condition occurs because a wire is disconnected:</p> <ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the underrange signal value of the selected operational range in floating point mode (minimum possible scaled value) or -32,768 counts in integer mode • The ChxUnderrange (x=channel number) tag is set to 1 <p>When the condition occurs because the RTB has been disconnected from the module (1756-IF6I module only [i.e. the following events only occur when an RTB is disconnected from the 1756-IF6I module]):</p> <ul style="list-style-type: none"> • Input data for that channel changes to the scaled value associated with the overrange signal value of the selected operational range in floating point mode (maximum possible scaled value) or 32,767 counts in integer mode • The ChxOvrerrange (x=channel number) tag is set to 1

For more information about tags in the tag editor, see Appendix B.

Using Module Block and Input Circuit Diagrams

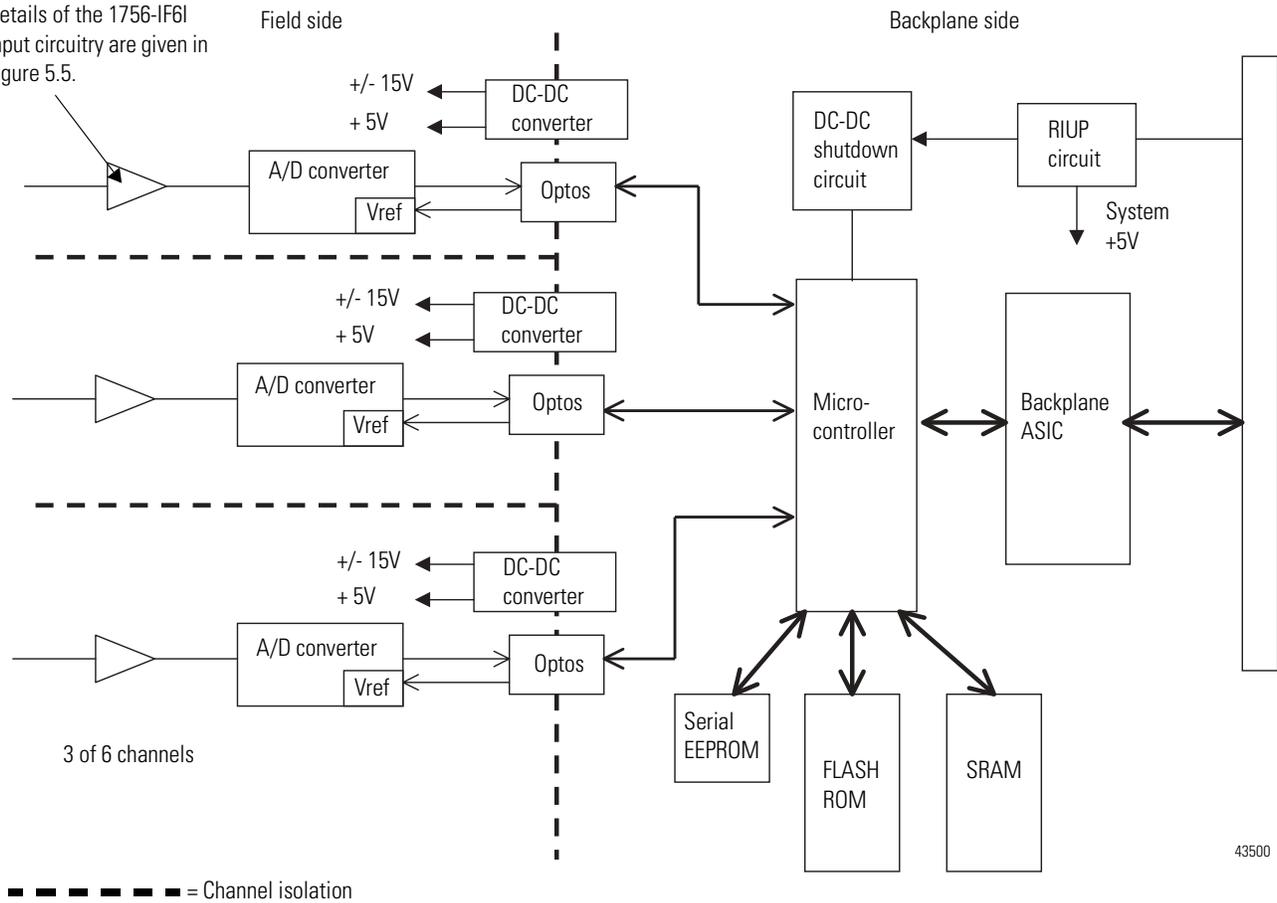
This section shows the 1756-IF6CIS and 1756-IF6I modules' block diagrams and input circuit diagrams.

Module Block Diagrams

Figure 5.3 1756-IF6CIS and 1756-IF6I Module Block Diagram

Details of the 1756-IF6CIS input circuitry are given in Figure 5.4.

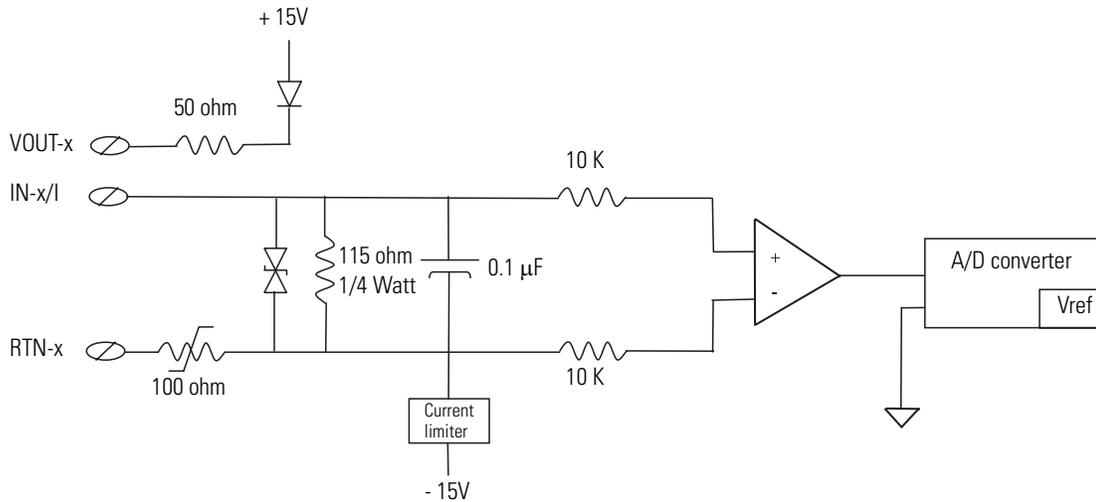
Details of the 1756-IF6I input circuitry are given in Figure 5.5.



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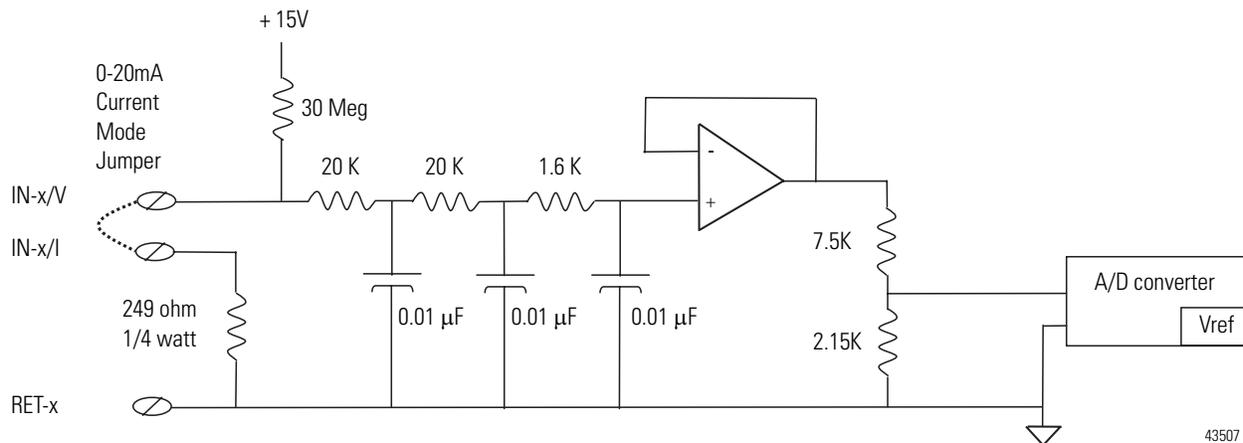
Field Side Circuit Diagrams

Figure 5.4 1756-IF6CIS Input Circuit



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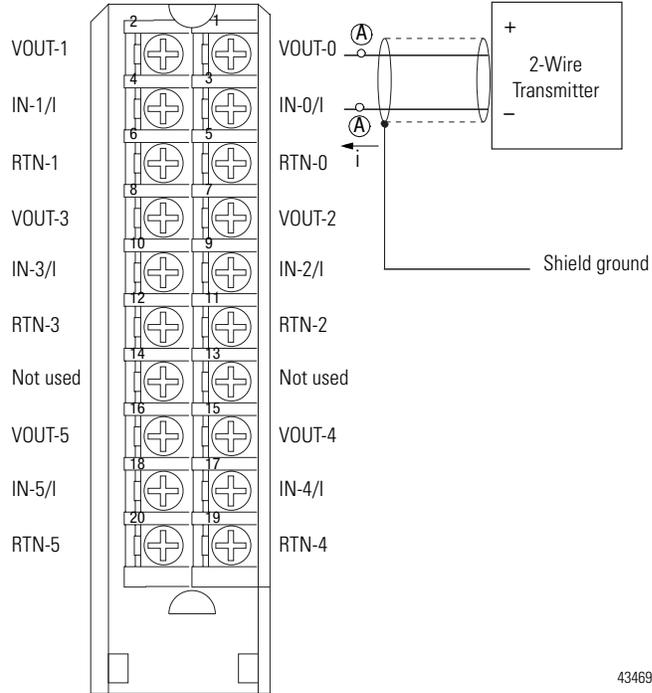
Figure 5.5 1756-IF6I Input Circuit



43507

Wiring the 1756-IF6CIS Module

Figure 5.6 1756-IF6CIS – 2-wire transmitter connected to the module and the module providing 24V dc loop power

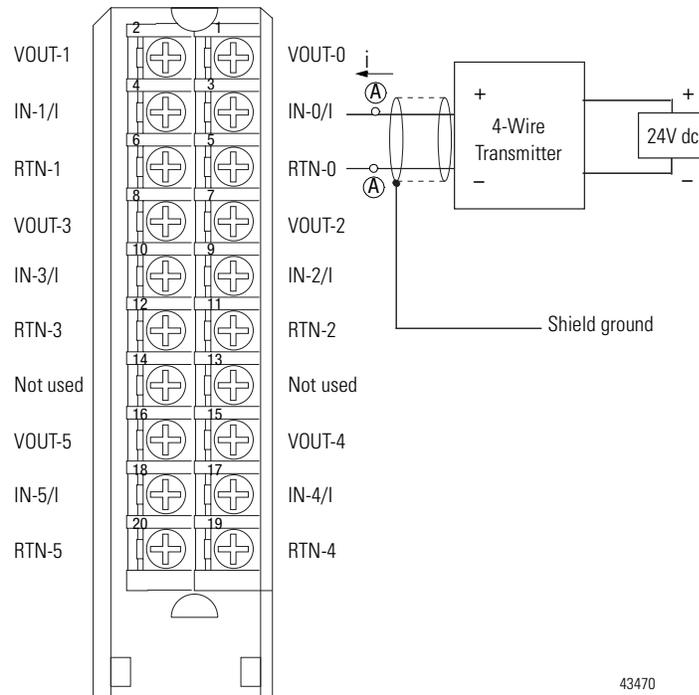


43469

NOTE:

1. Do not connect more than 2 wires to any single terminal.
2. Place additional loop devices (e.g. strip chart recorders) at either A location in the current loop.

Figure 5.7 1756-IF6CIS – 4-wire transmitter connected to the module and an external, user-provided power supply providing 24V dc loop power

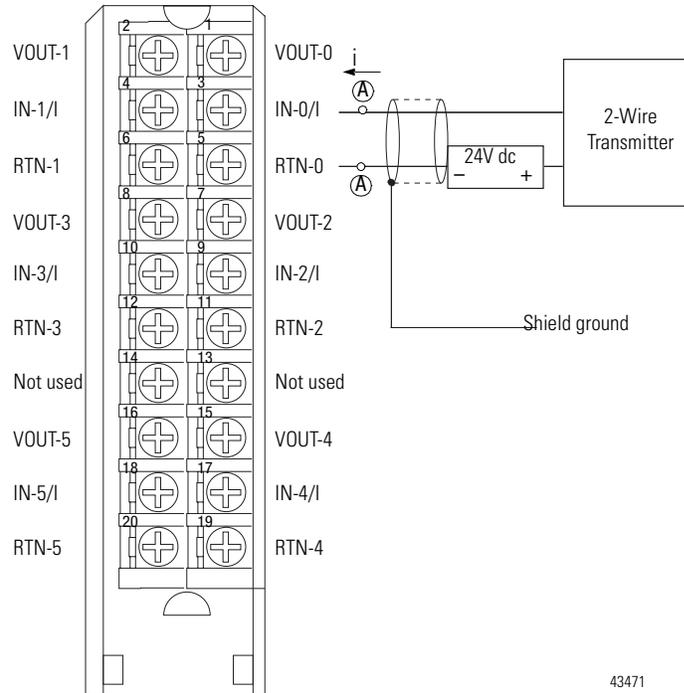


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NOTES:

1. If separate power sources are used, do not exceed the specified isolation voltage.
2. Do not connect more than 2 wires to any single terminal.
3. Place additional loop devices (e.g. strip chart recorders) at either A location in the current loop.

Figure 5.8 1756-IF6CIS – 2-wire transmitter connected to the module and an external, user-provided power supply providing 24V dc loop power

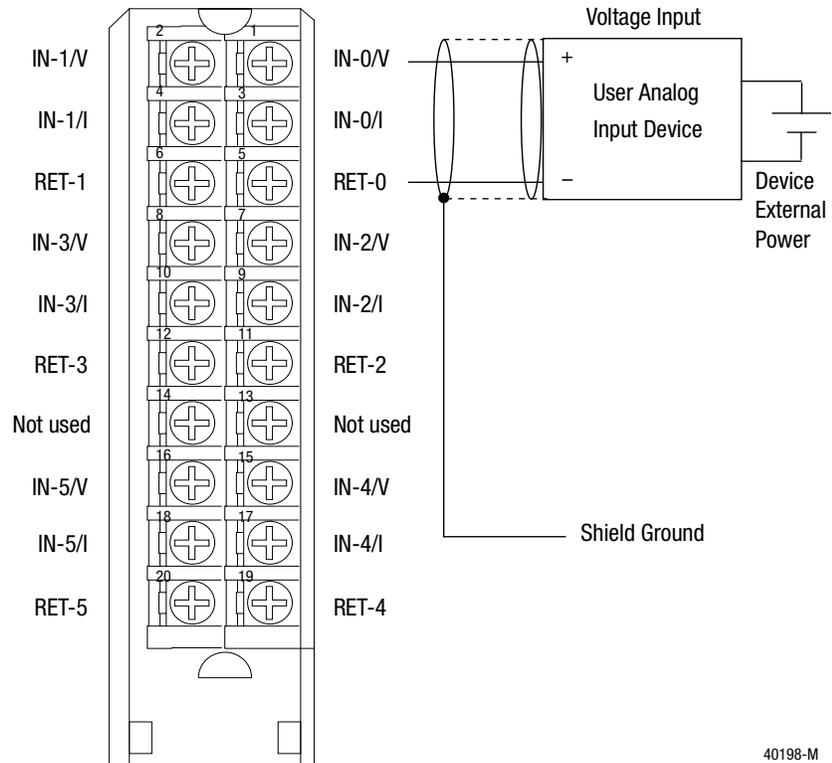


NOTES:

1. If separate power sources are used, do not exceed the specified isolation voltage.
2. Do not connect more than 2 wires to any single terminal.
3. Place additional loop devices (e.g. strip chart recorders) at either A location in the current loop.

Wiring the 1756-IF6I Module

Figure 5.9 1756-IF6I Voltage wiring example

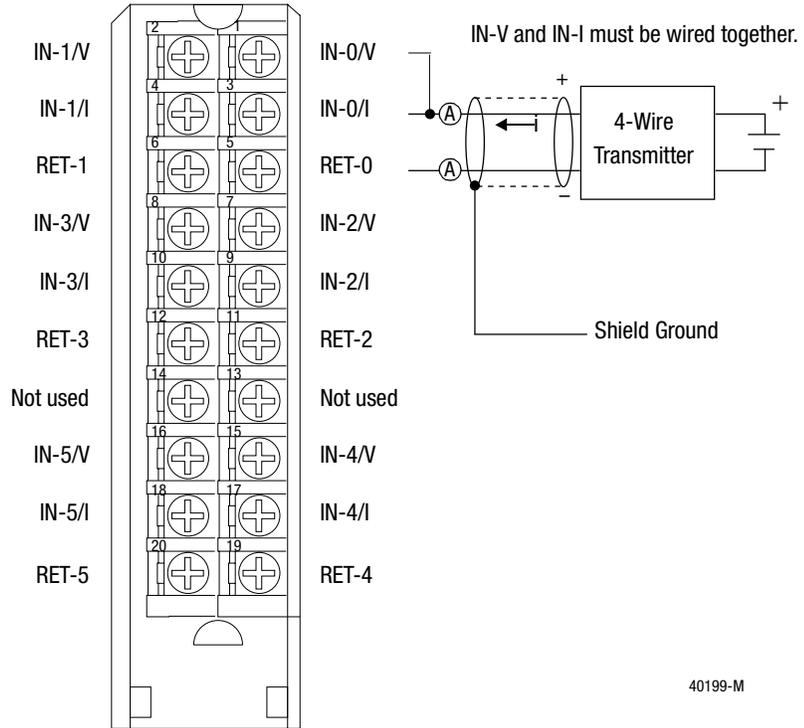


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■ **NOTES:** Do not connect more than 2 wires to any single terminal.

Figure 5.10 1756-IF6I Current wiring example with a 4-wire transmitter

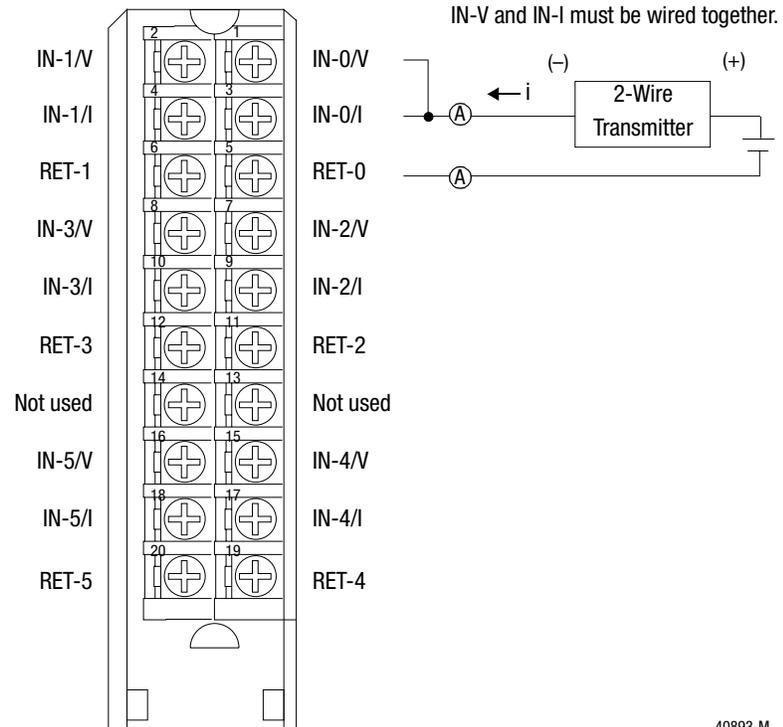
NOTE: Place additional loop devices (e.g. strip chart recorders, etc.) at either A location.



NOTES: Do not connect more than 2 wires to any single terminal.

Figure 5.11 1756-IF6I Current wiring example with a 2-wire transmitter

NOTE: Place additional loop devices (e.g. strip chart recorders, etc.) at either A location.



NOTES: Do not connect more than 2 wires to any single terminal.

1756-IF6CIS or 1756-IF6I Module Fault and Status Reporting

The 1756-IF6CIS and 1756-IF6I modules multicast status/fault data to the owner/listening controllers with its channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide increasing degree of detail as to the specific cause of faults on the module.

Table 5.8 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 5.8

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults.
Channel Status Words	This word provides individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

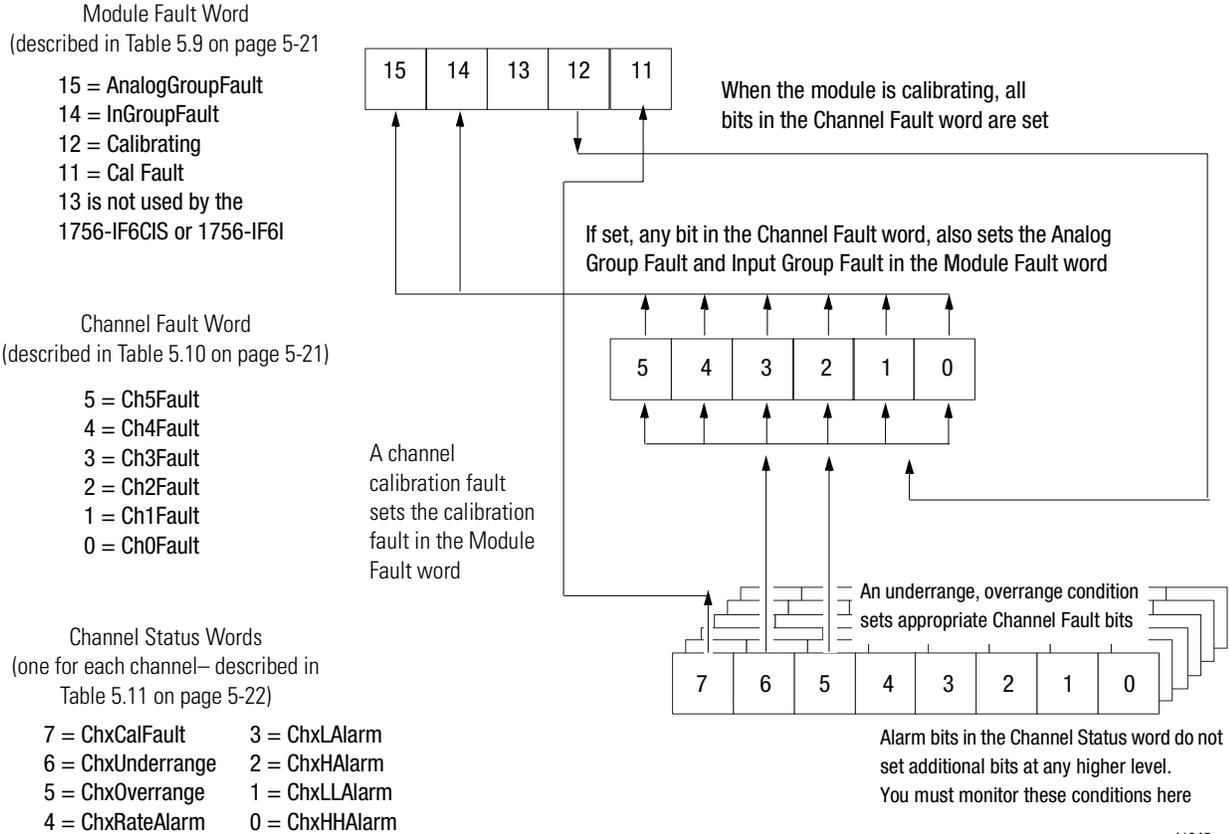
IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

Fault Reporting in Floating Point Mode

Figure 5.12 provides an overview of the fault reporting process in floating point mode.

Figure 5.12



Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 5.9 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 5.9

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Input Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is InputGroup.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Floating Point Mode

During normal module operation, bits in the Channel Fault word are set if any of the respective channels has an Under or Overrange condition. Checking this word for a nonzero value is a quick way to check for Under or Overrange conditions on the module.

Table 5.10 lists the conditions that set **all** Channel Fault word bits:

Table 5.10

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

Channel Status Word Bits – Floating Point Mode

Any of the 6 Channel Status words, one for each channel, will display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words. When the Underrange and Overrange bits (bits 6 & 5) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 11) is set in the Module Fault word. Table 5.11 lists the conditions that set each of the word bits.

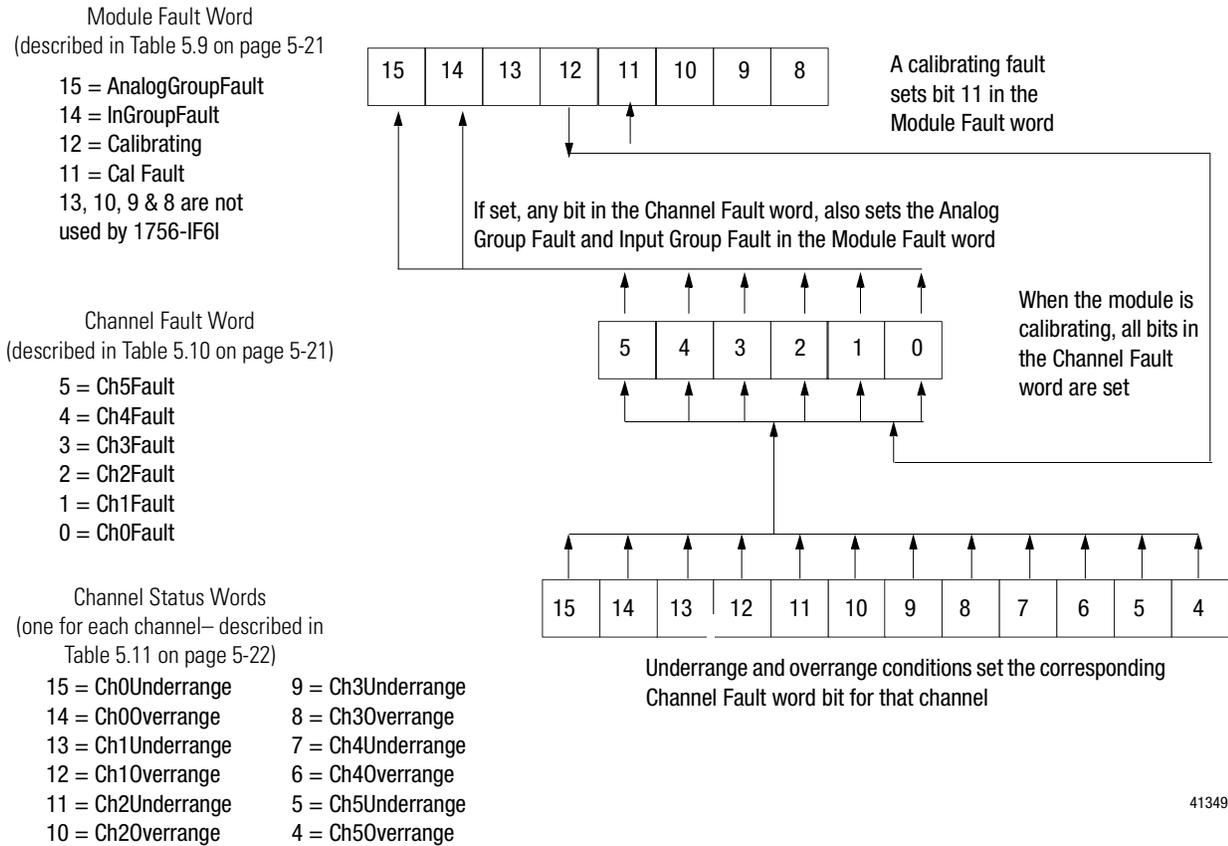
Table 5.11

Tag (Status word):	Bit:	Event that sets this tag:
ChxCalFault	Bit 7	This bit is set if an error occurs during calibration for that channel, causing a bad calibration. This bit also sets bit 9 in the Module Fault word.
Underrange	Bit 6	This bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 5.6 on page 5-7. This bit also sets the appropriate bit in the Channel Fault word.
Overrange	Bit 5	This bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 5.6 on page 5-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxRateAlarm	Bit 4	This bit is set when the input channel's rate of change exceeds the configured Rate Alarm parameter. It remains set until the rate of change drops below the configured rate. If latched, the alarm remains set until it is unlatched.
ChxLAlarm	Bit 3	This bit is set when the input signal moves beneath the configured Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 2	This bit is set when the input signal moves above the configured High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains set as long as the signal remains within the configured deadband.
ChxLLAlarm	Bit 1	This bit is set when the input signal moves beneath the configured Low-Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains latched as long as the signal remains within the configured deadband.
ChxHHighAlarm	Bit 0	This bit is set when the input signal moves above the configured High-High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains latched as long as the signal remains within the configured deadband.

Fault Reporting in Integer Mode

Figure 5.13 offers an overview of the fault reporting process in integer mode.

Figure 5.13



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Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-8) operate exactly as described in floating point mode. Table 5.12 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 5.12

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Input Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is InputGroup.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits operate exactly as described in floating point mode. Table 5.13 lists the conditions that set **all** Channel Fault word bits:

Table 5.13

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

Channel Status Word Bits – Integer Mode

The Channel Status word has the following differences when used in integer mode:

- Only Underrange and Overrange conditions are reported by the module.
- Alarming and Calibration Fault activities are not available, although the Calibration Fault bit in the Module Fault word will activate if a channel is not properly calibrated.
- There is only 1 Channel Status word for all 6 channels.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 5.14 lists the conditions that set each of the words.

Table 5.14

Tag (Status word):	Bit:	Event that sets this tag:
ChxUnderrange	Odd-numbered bits from bit 15 to bit 5 (e.g. bit 15 represents channel 0). For a full listing of the channels these bits represent, see Figure 5.13 on page 5-23.	The underrange bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 5.6 on page 5-7. This bit also sets the appropriate bit in the Channel Fault word.
ChxOverrange	Even-numbered bits from bit 14 to bit 4 (e.g. bit 14 represents channel 0). For a full listing of the channels these bits represent, see Figure 5.13 on page 5-23.	The overrange bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 5.6 on page 5-7. This bit also sets the appropriate bit in the Channel Fault word.

Chapter Summary and What's Next

In this chapter you learned about features specific to the Sourcing Current Loop Input Module (1756-IF6CIS) and Isolated Analog Voltage/Current Input Module (1756-IF6I).

Chapter 6 describes features specific to the Temperature Measuring Analog Modules (1756-IR6I, 1756-IT6I & 1756-IT6I2).

Temperature Measuring Analog Modules (1756-IR6I, 1756-IT6I & 1756-IT6I2)

What This Chapter Contains This chapter describes features specific to temperature measuring ControlLogix analog modules.

For information about:	See page:
Choosing a Data Format	6-2
Features Specific to Temperature Measuring Modules	6-3
Differences Between the 1756-IT6I and 1756-IT6I2 Modules	6-12
Using Module Block and Input Circuit Diagrams	6-17
Wiring the 1756-IR6I Module	6-19
Wiring the 1756-IT6I Module	6-20
Wiring the 1756-IT6I2 Module	6-21
1756-IR6I, 1756-IT6I and 1756-IT6I2 Fault and Status Reporting	6-22

The temperature-measuring modules also support features described in Chapter 3. Table 6.1 lists those additional features.

Table 6.1 Additional Features Supported by the Temperature Measuring Modules

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Choosing a Data Format

Data format determines the features that are available to your application. You choose a data format when you choose a Communications Format. For more information on Communications Format, see page 10-6.

You can choose one of the two following data formats:

- Integer mode
- Floating point mode

Table 6.2 shows what features are available in each format.

Table 6.2 Features Available in Each Data Format

Data format:	Features available:	Features not available:
Integer mode	Multiple input ranges Notch filter Real time sampling Cold Junction Temperature – (1756-IT6I and 1756-IT6I2 only)	Temperature linearization Process alarms Digital filtering Rate alarms
Floating point mode	All features	N/A

IMPORTANT

Integer mode does not support temperature conversion on temperature measuring modules. If you choose integer mode, the 1756-IR6I is strictly an ohms (Ω) module and the 1756-IT6I and 1756-IT6I2 are strictly millivolts (mV) modules.

Features Specific to Temperature Measuring Modules

Table 6.3 lists features that are specific to the temperature-measuring modules. The features are described later in this section.

Table 6.3

Feature:	Page of description:
Multiple Input Ranges	6-3
Notch Filter	6-4
Real Time Sampling	6-5
Underrange/Overrange Detection	6-5
Digital Filter	6-6
Process Alarms	6-7
Rate Alarm	6-8
10 Ohm Offset	6-8
Wire Off Detection	6-9
Sensor Type	6-10
Temperature Units	6-12
Cold Junction Compensation	6-13

Multiple Input Ranges

You can select from a series of operational ranges for **each channel** on your module. The range designates the minimum and maximum signals that are detectable by the module.

Table 6.4 Possible Input Ranges

Module:	Possible ranges:
1756-IR6I	1 to 487 Ω 2 to 1000 Ω 4 to 2000 Ω 8 to 4080 Ω
1756-IT6I and 1756-IT6I2	-12 to +78mV -12 to +30mV

For an example of how to choose an input range for your module, see page 10-10.

Notch Filter

An Analog-to-Digital Converter (ADC) filter removes line noise in your application for **each channel**.

Choose a notch filter that most closely matches the anticipated noise frequency in your application. Remember that each filter time affects the response time of your module. Also, the highest frequency notch filter settings also limit the effective resolution of the channel.

IMPORTANT 60Hz is the default setting for the notch filter.

Table 6.5 lists the available notch filter setting.

Table 6.5 Notch Filter Settings

Notch setting:	10Hz	50Hz	60Hz (Default)	100Hz	250Hz	1000Hz
Minimum Sample Time (RTS – Integer mode) ⁽¹⁾	102mS	22mS	19mS	12mS	10mS	10mS
Minimum Sample Time (RTS – Floating point mode) ⁽²⁾	102mS	25mS	25mS	25mS	25mS	25mS
0-100% Step Response Time ⁽³⁾	400mS + RTS	80mS + RTS	68mS + RTS	40mS + RTS	16mS + RTS	4mS + RTS
-3dB Frequency	3Hz	13Hz	15Hz	26Hz	66Hz	262Hz
Effective Resolution	16 bits	16 bits	16 bits	16 bits	15 bits	10 bits

⁽¹⁾ Integer mode must be used for RTS values lower than 25mS. The minimum RTS value for the module will be dependent on the channel with the lowest notch filter setting.

⁽²⁾ In mV mode, 50mS minimum, if linearizing.

⁽³⁾ Worst case settling time to 100% of a step change would include 0-100% step response time plus one RTS sample time.

To see how to choose a Notch Filter, see page 10-10.

Real Time Sampling

This parameter instructs the module to scan its input channels and obtain all available data. After the channels are scanned, the module multicasts that data.

During module configuration, you specify a Real Time Sampling (RTS) period and a Requested Packet Interval (RPI) period. These features both instruct the module to multicast data, but only the RTS feature instructs the module to scan its channels before multicasting.

For more information on Real Time Sampling, see page 2-4. For an example of how to set the RTS rate, see page 10-10.

Underrange/Overrange Detection

This feature detects when a temperature measuring input module is operating beyond limits set by the input range. For example, If you are using the 1756-IR6I module in the 2Ω-1000Ω input range and the module resistance increases to 1050Ω, the Overrange detection detects this condition.

Table 6.6 lists the input ranges of non-isolated input modules and the lowest/highest signal available in each range before the module detects an underrange/overrange condition:

Table 6.6 Low and High Signal Limits on Temperature Measuring Input Modules

Input module:	Available range:	Lowest signal in range:	Highest signal in range:
1756-IR6I	1Ω – 487Ω	0.859068653Ω	507.862Ω
	2Ω – 1000Ω	2Ω	1016.502Ω
	4Ω – 2000Ω	4Ω	2033.780Ω
	8Ω – 4020Ω	8Ω	4068.392Ω
1756-IT6I and 1756-IT6I2	-12mV to +30mV	-15.80323mV	31.396mV
	-12mV to +78mV	-15.15836mV	79.241mV

Digital Filter

IMPORTANT

The digital filter is only available in applications using floating point mode.

The digital filter smooths input data noise transients on **each input channel**. This value specifies the time constant for a digital first order lag filter on the input. It is specified in units of milliseconds. A value of 0 disables the filter.

The digital filter equation is a classic first order lag equation.

$$Y_n = Y_{n-1} + \frac{[\Delta t]}{\Delta t + T_A} (X_n - Y_{n-1})$$

Y_n = present output, filtered peak voltage (PV)

Y_{n-1} = previous output, filtered PV

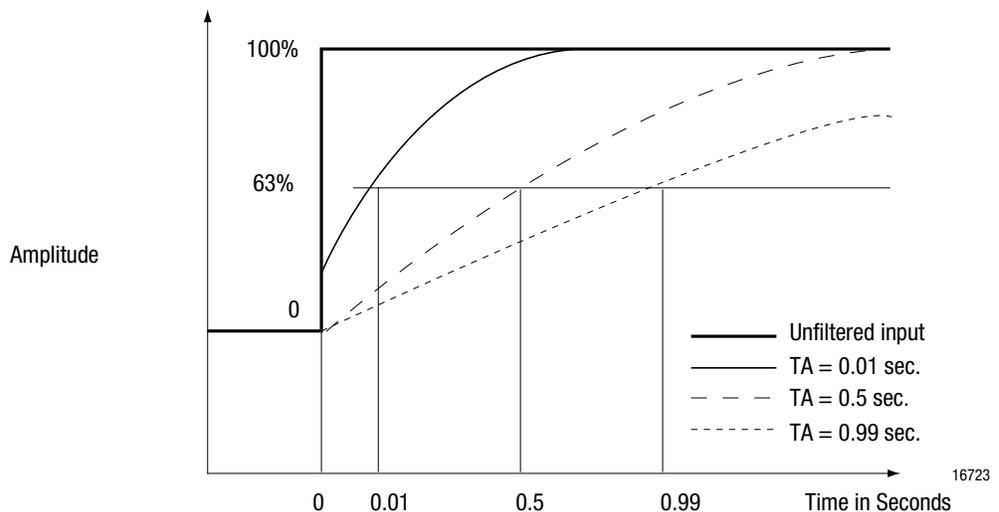
Δt = module channel update time (seconds)

T_A = digital filter time constant (seconds)

X_n = present input, unfiltered PV

Using a step input change to illustrate the filter response, you can see that when the digital filter time constant elapses, 63.2% of the total response is reached. Each additional time constant achieves 63.2% of the remaining response. For more information, see Figure 6.1.

Figure 6.1



To see how to set the Digital Filter, see page 10-10.

Process Alarms

Process alarms alert you when the module has exceeded configured high or low limits for **each channel**. You can latch process alarms. These are set at four user configurable alarm trigger points:

- High high
- High
- Low
- Low low

IMPORTANT

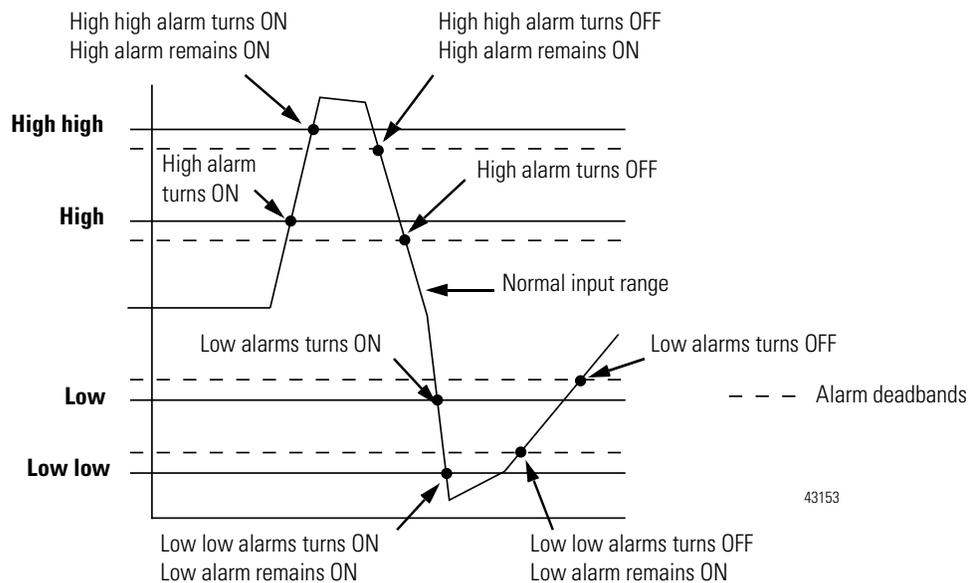
Process alarms are only available in applications using floating point mode. The values for each limit are entered in scaled engineering units.

Alarm Deadband

You may configure an **Alarm Deadband** to work with these alarms. The deadband allows the process alarm status bit to remain set, despite the alarm condition disappearing, as long as the input data remains within the deadband of the process alarm.

Figure 6.2 shows input data that sets each of the four alarms at some point during module operation. In this example, Latching is disabled; therefore, each alarms turns OFF when the condition that caused it to set ceases to exist.

Figure 6.2



To see how to set Process Alarms, see page 10-10.

Rate Alarm

IMPORTANT

Prior to RSLogix 5000, version 12 and module firmware revision 1.10, the rate alarm does not function correctly when linearizing (i.e. non-ohms or non-millivolt input range) temperature inputs on the 1756-IR6I, 1756-IT6I and 1756-IT6I2 modules.

To correctly use the rate alarm for a non-ohm input on the 1756-IR6I module and a non-millivolt input on the 1756-IT6I and 1756-IT6I2 modules, make sure you use RSLogix 5000, version 12 and module firmware 1.10 for these modules.

The rate alarm triggers if the rate of change between input samples for **each channel** exceeds the specified trigger point for that channel. This feature is **only available in applications using floating point**.

EXAMPLE

If you set a 1756-IT6I2 module (with normal scaling in celsius) to a rate alarm of 100.1°C/S, the rate alarm only trigger if the difference between measured input samples changes at a rate > 100.1°C/S.

If the module's RTS is 100 ms (i.e. sampling new input data every 100ms) and at time 0, the module measures 355°C and at time 100ms measures 363°C, the rate of change is $(363^{\circ}\text{C} - 355^{\circ}\text{C}) / (100\text{ms}) = 80^{\circ}\text{C/S}$. The rate alarm would not set as the change is less than the trigger point of 100.1°C/s.

If the next sample taken is 350.3°C, the rate of change is $(350.3^{\circ}\text{C} - 363^{\circ}\text{C}) / (100\text{ms}) = -127^{\circ}\text{C/S}$. The absolute value of this result is > 100.1°C/S, so the rate alarm will set. Absolute value is used because rate alarm checks for the magnitude of the rate of change being beyond the trigger point, whether a positive or negative excursion.

To see how to set the Rate Alarm, see page 10-10.

10 Ohm Offset

With this feature, you can compensate for a small offset error in a 10 ohm copper RTD. Values can range from -0.99 to +0.99 ohms in units of 0.01 ohms. For example, if the resistance of a copper RTD used with a channel is 9.74 ohms at 25°C, you would enter -0.26 in this field. To see how to set the 10 Ohm Offset, see page 10-14.

Wire Off Detection

The ControlLogix temperature measuring modules alert you when a wire has been disconnected from one of their channels. When a wire off condition occurs, two events occur:

- Input data for that channel changes to a specific scaled value
- A fault bit is set in the owner-controller which may indicate the presence of a wire off condition

Because these modules can each be used in various applications, differences exist when a wire off condition is detected in each application. Table 6.7 lists the differences that occur when a wire off condition occurs in various applications.

Table 6.7

In this application:	the following causes a wire off condition:	And if the wire off condition is detected, the following occurs:
1756-IR6I Module in Temperature Applications	Either of the following: <ol style="list-style-type: none"> 1. When any combination of wires are disconnected from the module, except the loss of the wire from terminal A only (see Figure 6.8 on page 6-19 and Figure 6.9 on page 6-19). 2. When only the wire connected to terminal A (see Figure 6.8 on page 6-19 and Figure 6.9 on page 6-19) is lost 	If possibility #1 (in the previous column) is the cause: <ul style="list-style-type: none"> • input data for the channel changes to the lowest scaled temperature value associated with the selected RTD type • the ChxUnderrange (x=channel number) tag is set to 1 If possibility #2 (in the previous column) is the cause: <ul style="list-style-type: none"> • input data for the channel changes to the highest scaled temperature value associated with the selected RTD type • the ChxOverrange (x=channel number) tag is set to 1
1756-IR6I Module in Ohms Applications	Either of the following: <ol style="list-style-type: none"> 1. When any combination of wires are disconnected from the module, except the loss of a wire from terminal A by itself (see Figure 6.8 on page 6-19 and Figure 6.9 on page 6-19) 2. When only the wire connected to terminal A (see Figure 6.8 on page 6-19 and Figure 6.9 on page 6-19) is lost 	If possibility #1 (in the previous column) is the cause: <ul style="list-style-type: none"> • input data for the channel changes to the lowest scaled ohm value associated with the selected ohms range • the ChxUnderrange (x=channel number) tag is set to 1 If possibility #2 (in the previous column) is the cause: <ul style="list-style-type: none"> • input data for the channel changes to the highest scaled ohm value associated with the selected ohms range • the ChxOverrange (x=channel number) tag is set to 1
1756-IT6I or 1756-IT6I2 Module in Temperature Applications	A wire is disconnected from the module.	<ul style="list-style-type: none"> • input data for the channel changes to the highest scaled temperature value associated with the selected thermocouple type • the ChxOverrange (x=channel number) tag is set to 1
1756-IT6I Module or 1756-IT6I2 in Millivolt Applications		<ul style="list-style-type: none"> • input data for the channel changes to the scaled value associated with the overrange signal value of the selected operational range in floating point mode (maximum possible scaled value) or 32,767 counts in integer mode • the ChxOverrange (x=channel number) tag is set to 1

For more information about tags in the tag editor, see Appendix B.

Sensor Type

Three analog modules, the RTD (1756-IR6I) and Thermocouple (1756-IT6I and 1756-IT6I2), allow you to configure a **sensor type for each channel** that linearizes the analog signal into a temperature value. The RTD module linearizes ohms into temperature and the Thermocouple modules linearize millivolts into temperature.

IMPORTANT

Sensor types are only available in applications using floating point mode.

Also, these modules can only linearize signals to temperature values in the floating point mode.

Table 6.8 lists the sensors that are available for your application:

Table 6.8 Available Sensors for Temperature Measuring Modules

Module:	Available sensors or thermocouples:
1756-IR6I	10Ω - Copper 427 type 100Ω - Platinum 385, Platinum 3916, and Nickel 618 types 120Ω - Nickel 618 and Nickel 672 types 200Ω - Platinum 385, Platinum 3916, and Nickel 618 types 500Ω - Platinum 385, Platinum 3916, and Nickel 618 types 1000Ω - Platinum 385 and Platinum 3916 types
1756-IT6I	B, E, J, K, R, S, T, N, C
1756-IT6I2	B, E, J, K, R, S, T, N, C, D, TXK/XK (L)

When you select any of the sensor or thermocouple types listed Table 6.8 during configuration, RSLogix 5000 uses the default values in the scaling box:

Table 6.9 Default Signal and Engineering Values in RSLogix 5000

1756-IR6I		1756-IT6I and 1756-IT6I2	
Low signal = 1	Low engineering = 1	Low signal = -12	Low engineering = -12
High signal = 487	High engineering = 487	High signal = +78	High engineering = +78

IMPORTANT

The module sends back temperature values over the entire sensor range as long as the Low signal value equals the Low engineering value and the High signal value equals the High engineering value. The actual numbers used in the signal and engineering fields are irrelevant as long as they are equal.

Table 6.10 displays the temperature range for each 1756-IR6I sensor type.

Table 6.10 Temperature Limits for 1756-IR6I Sensor Types

1756-IR6I Sensor:	Copper 427	Nickel 618	Nickel 672	Platinum 385	Platinum 3916
Low temperature	-200.0°C	-60.0°C	-80.0°C	-200.0°C	-200.0°C
	-328.0°F	-76.0°F	-112.0°F	-328.0°F	-328.0°F
High temperature	260.0°C	250.0°C	320.0°C	870.0°C	630.0°C
	500.0°F	482.0°F	608.0°F	1598.0°F	1166.0°F

To see how to choose an RTD sensor type, see page 10-14.

Table 6.11 displays the temperature range for each 1756-IT6I and 1756-IT6I2 sensor type.

Table 6.11 Temperature Limits for 1756-IT6I and 1756-IT6I2 Sensor Types

Thermocouple:	B	C	E	J	K	N	R	S	T	D ⁽¹⁾	TXK/XK (L) ⁽¹⁾
Low temperature	300.0°C	0.0°C	-270.0°C	-210.0°C	-270.0°C	-270.0°C	-50.0°C	-50.0°C	-270.0°C	0°C	-200°C
	572.0°F	32.0°F	-454.0°F	-346.0°F	-454.0°F	-454.0°F	-58.0°F	-58.0°F	-454.0°F	32.0°F	-328°F
High temperature	1820.0°C	2315.0°C	1000.0°C	1200.0°C	1372.0°C	1300.0°C	1768.1°C	1768.1°C	400.0°C	2320°C	800°C
	3308.0°F	4199.0°F	1832.0°F	2192.0°F	2502.0°F	2372.0°F	3215.0°F	3215.0°F	752.0°F	4208°F	1472°F

⁽¹⁾ Sensor types D and L are only available on the 1756-IT6I2 module.

IMPORTANT

Table 6.11 lists temperature limits for sensors using the -12 to 78mV range only. When the -12 to 30mV range is used, temperature limits are truncated to the temperature value that corresponds to 30mV.

To see how to choose an thermocouple sensor type, see page 10-15.

Temperature Units

The 1756-IR6I, 1756-IT6I and 1756-IT6I2 modules provide the choice of working in Celsius or Fahrenheit. This choice affects all channels per module.

To see how to choose Temperature Units, see page 10-15.

Differences Between the 1756-IT6I and 1756-IT6I2 Modules

In addition to offering access to two more thermocouple types (i.e. types D and TXK/XK [L]), the 1756-IT6I2 module offers:

- greater cold junction compensation accuracy

While the 1756-IT6I module can report cold junction temperature differences between channels as high as 3°C from the actual temperature, the 1756-IT6I2 module, because it has two Cold Junction Sensors (CJSs), reduces the potential cold junction error from actual temperature to 0.3°C.

Table 6.12 lists cold junction error from actual temperature, depending on the type of cold junction compensation used.

Table 6.12

If you use this module:	with this type of cold junction compensation:	The cold junction error from actual temperature is:
1756-IT6I2	2 cold junction sensors on an RTB	+/-0.3°C
1756-IT6I2	IFM	+/-0.3°C
1756-IT6I	1 cold junction sensor on an RTB	+/-3.2°C maximum ⁽¹⁾
1756-IT6I	IFM	+/-0.3°C

⁽¹⁾ The cold junction error varies for each channel but 3.2°C is the maximum error any channel will show.

For more information on Cold Junction Compensation, see page 6-13.

- improved module accuracy. For more information on the Improved Module Accuracy available with the 1756-IT6I2 module, see page 6-16.

Cold Junction Compensation

When using the Thermocouple (1756-IT6I and 1756-IT6I2) modules, you must account for additional voltage that may alter the input signal. The junction of thermocouple field wires with the screw terminations of an RTB or IFM generates a small voltage. This thermoelectric effect alters the input signal.

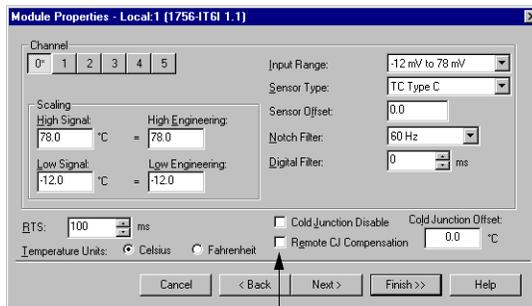
To accurately compensate the input signal from your module, you must use a CJS to account for the increased voltage. Because there are differences if you choose to connect sensors via an RTB or IFM, you must configure the module (via RSLogix 5000) to work with the type of CJS used in your application.

Connecting a Cold Junction Sensor Via a Removable Terminal Block

When you connect a CJS to your thermocouple module via an RTB, the following occurs, depending on module type:

- The 1756-IT6I module uses one (1) CJS in the middle of the module and estimates temperature deviation elsewhere on the connector.
- The 1756-IT6I2 module uses two (2) CJSs at the top and bottom of the module and calculates temperature at each channel's input terminals; this usage of multiple sensors results in increased accuracy.

If you connect a CJS via an IFM, configure the module as shown in the screen below.



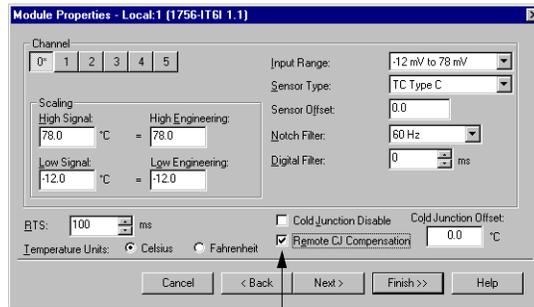
If you are using a CJS on an RTB,
leave all fields unchecked,

To see how to connect a CJS to either thermocouple module, see page 6-14.

Connecting a Cold Junction Sensor Via an Interface Module

The IFMs use an isothermal bar to maintain a steady temperature at all module terminations. When you use the IFM, we recommend you mount it so that the black anodized aluminum bar is in the horizontal position.

If you connect a CJS via an IFM, configure the module as shown in the screen below.

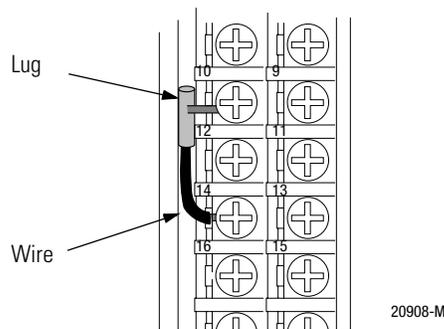


If you are using a CJS on an IFM, check the Remote CJ Compensation field.

Connecting a Cold Junction Sensor to the 1756-IT6I Module

You must connect the CJS to the 1756-IT6I module at terminals 10 and 14. To ease installation, wire terminal #12 (RTN-3) before connecting the cold junction sensor.

Figure 6.3

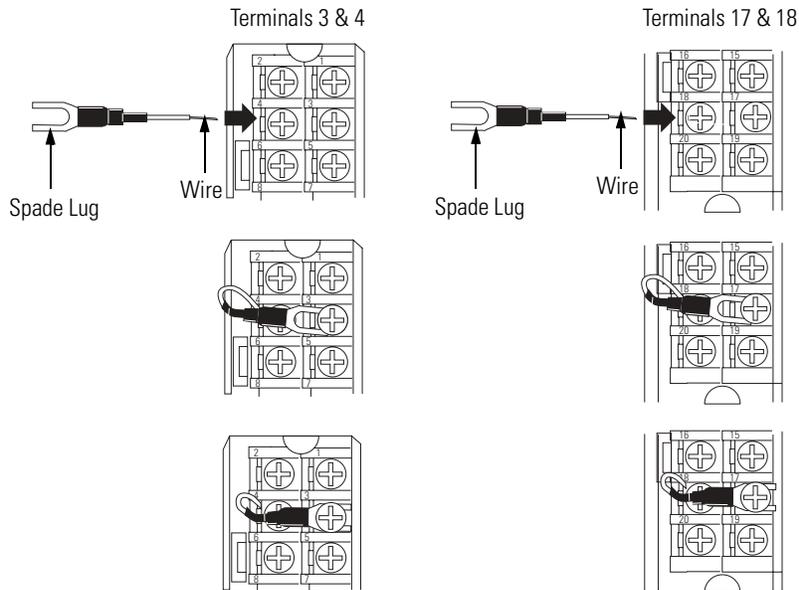


The CJS is part number 94238301. Contact your local distributor or Rockwell Automation sales representative to order additional sensors.

Connecting a Cold Junction Sensor to the 1756-IT6I2 Module

You must connect two CJSs to the 1756-IT6I2 when using an RTB. The additional CJS offers greater accuracy when measuring temperature on the module. Connect the cold junction sensors to terminals 3 & 4 and 17 & 18 as shown in Figure 6.4.

Figure 6.4



The CJS for the 1756-IT6I2 module is part number 94286501. Contact your local distributor or Rockwell Automation sales representative to order additional sensors.

Cold Junction Disable

RSLogix 5000 offers an option to disable cold junction compensation. If used, this option removes all cold junction compensation on all module channels. Typically, this option is only used in systems that have no thermoelectric effect (e.g. test equipment in a controlled lab).

In most applications, we recommend that you do not use the Cold Junction Disable option.

Cold Junction Offset

RSLogix 5000 also offers an option to make module-wide adjustments to cold junction compensation values. If you know that your cold junction compensation values are consistently inaccurate by some level (e.g. 1.2°C), you can set the Cold Junction Offset to -1.2° to account for this inaccuracy.

Improved Module Accuracy

The 1756-IT6I2 also offers an improved Gain Drift with Temperature and Module Error over Temperature Range specifications when compared to the 1756-IT6I module. Table 6.13 highlights the differences. For a full listing of these module's specifications, see Appendix A.

Table 6.13

Catalog Number:	Gain Drift with Temperature:⁽¹⁾	Module Error over Temperature Range:⁽¹⁾
1756-IT6I	80 ppm	0.5%
1756-IT6I2	25 ppm	0.15%

⁽¹⁾ To read a detailed explanation of this specification, see Appendix E.

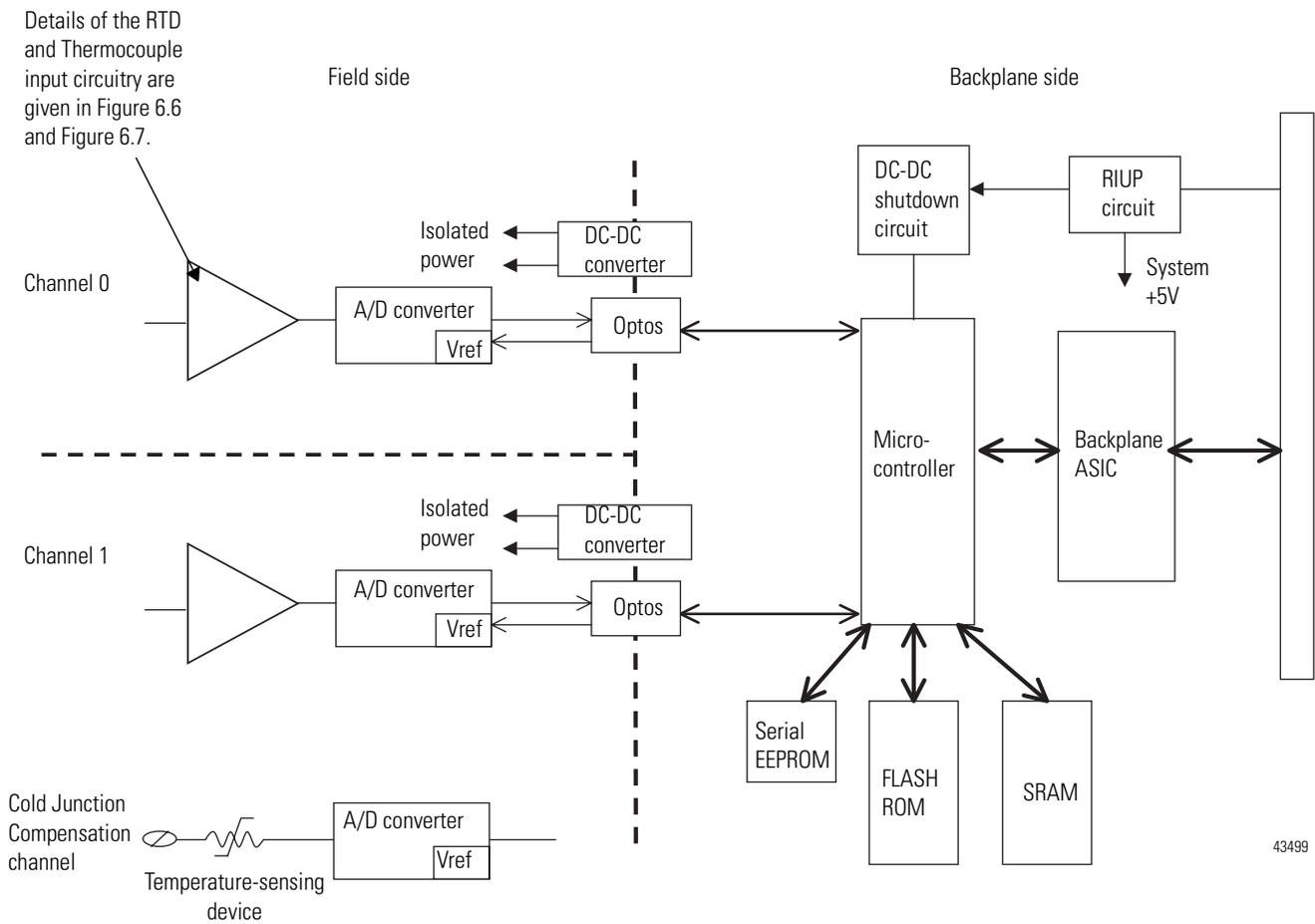
Using Module Block and Input Circuit Diagrams

This section shows the 1756-IR6I, 1756-IT6I and 1756-IT6I2 modules' block diagrams and input circuit diagrams.

Module Block Diagram

Figure 6.5 1756-IR6I, 1756-IT6I and 1756-IT6I2 Module Block Diagram

This diagram shows 2 channels. There are 6 channels on the temperature measuring modules.



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IMPORTANT: The cold junction compensation (CJC) channel is used on thermocouple modules only. The 1756-IT6I module has one CJC channel, and the 1756-IT6I2 module has two CJC channels.

----- = Channel isolation

Field Side Circuit Diagrams

Figure 6.6 1756-IR6I Input Circuit

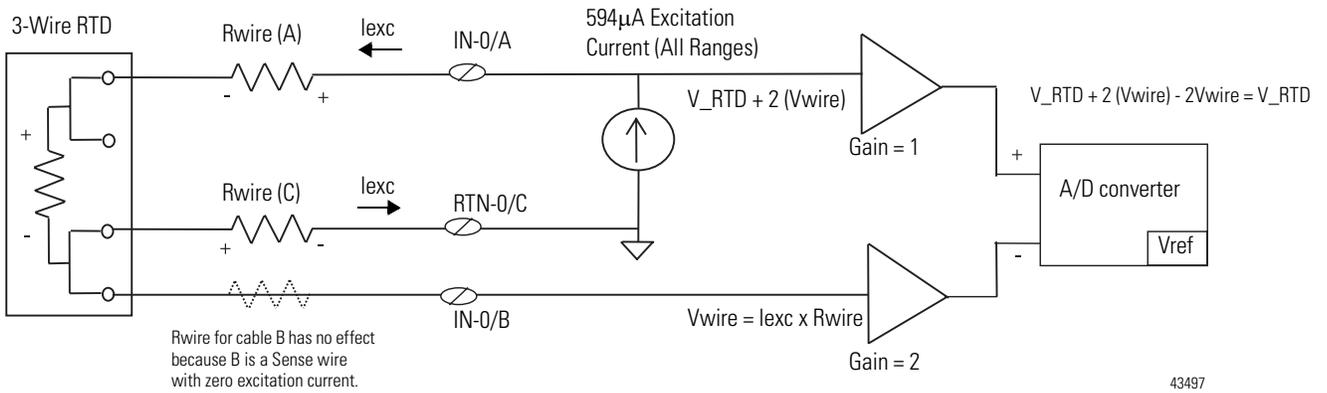
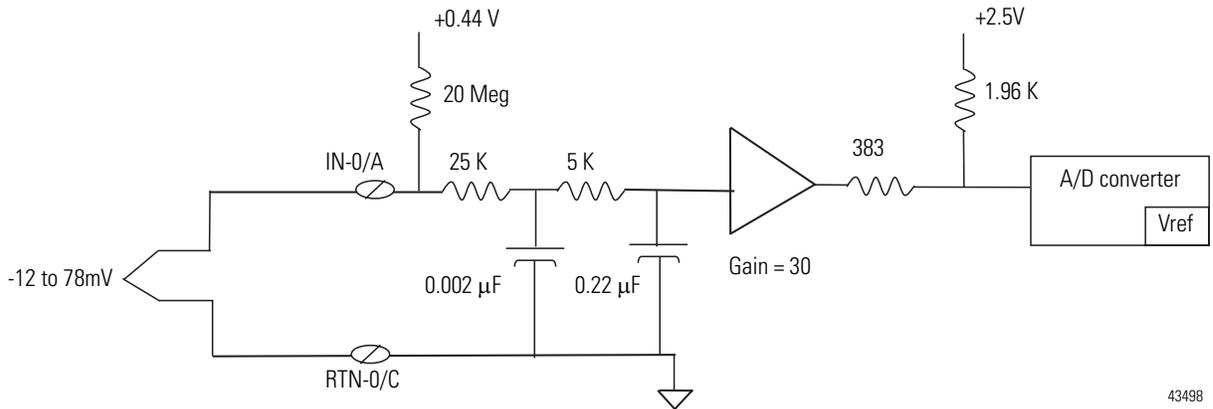
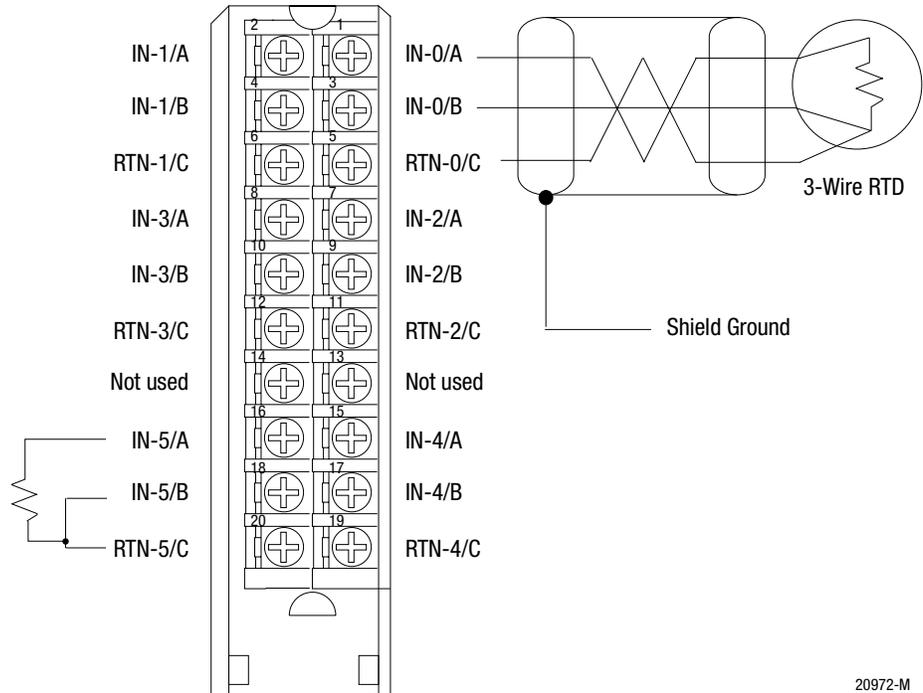


Figure 6.7 1756-IT6I and 1756-IT6I2 Input Circuit



Wiring the 1756-IR6I Module

Figure 6.8 1756-IR6I 3-Wire RTD wiring example

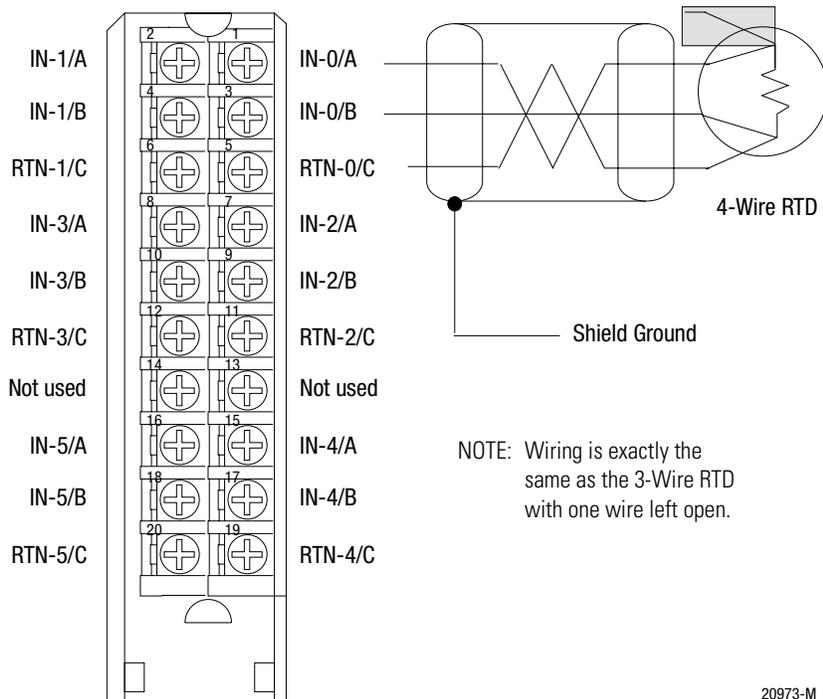


IMPORTANT: For 2-wire resistor applications including calibration, make sure IN-x/B and RTN-x/C are shorted together as shown.

■ **NOTE:** Do not connect more than 2 wires to any single terminal.

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Figure 6.9 1756-IR6I 4-Wire RTD wiring example



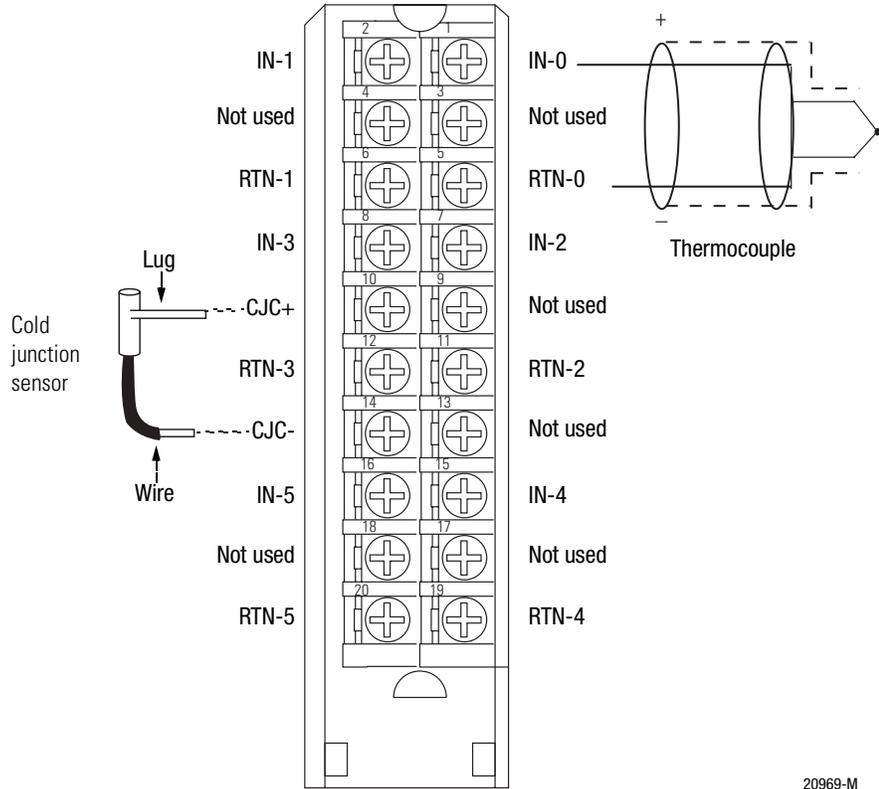
NOTE: Wiring is exactly the same as the 3-Wire RTD with one wire left open.

■ **NOTE:** Do not connect more than 2 wires to any single terminal.

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Wiring the 1756-IT6I Module

Figure 6.10 1756-IT6I wiring example



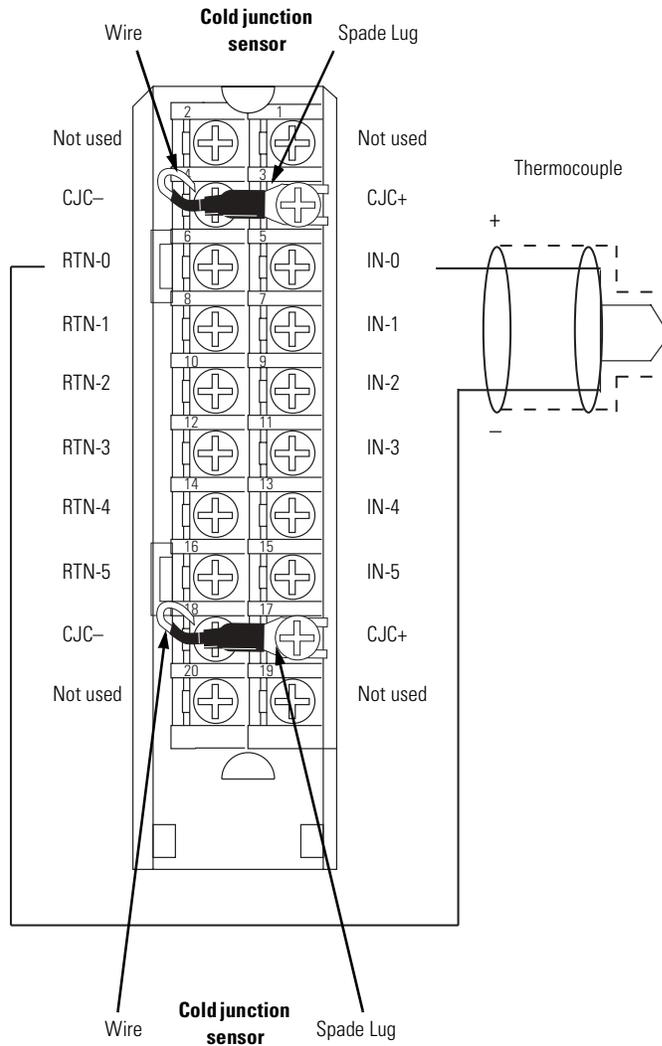
20969-M

■ **NOTES:**

1. Do not connect more than 2 wires to any single terminal.
2. The part number for the cold junction sensor used on the 1756-IT6I module is 94238301.

Wiring the 1756-IT6I2 Module

Figure 6.11 1756-IT6I2 wiring example



NOTES:

1. Do not connect more than 2 wires to any single terminal.
2. The part number for the cold junction sensor used on the 1756-IT6I module is 94286501.

1756-IR6I, 1756-IT6I and 1756-IT6I2 Fault and Status Reporting

The 1756-IR6I, 1756-IT6I and 1756-IT6I2 modules multicast status/fault data to the owner/listening controller with its channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide increasing degree of detail as to the specific cause of faults on the module.

Table 6.14 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 6.14

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults.
Channel Status Words	This word provides individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

Fault Reporting in Floating Point Mode

Figure 6.12 offers an overview of the fault reporting process in floating point mode.

Figure 6.12

Module Fault Word
(described in Table 6.15 on page 6-24)

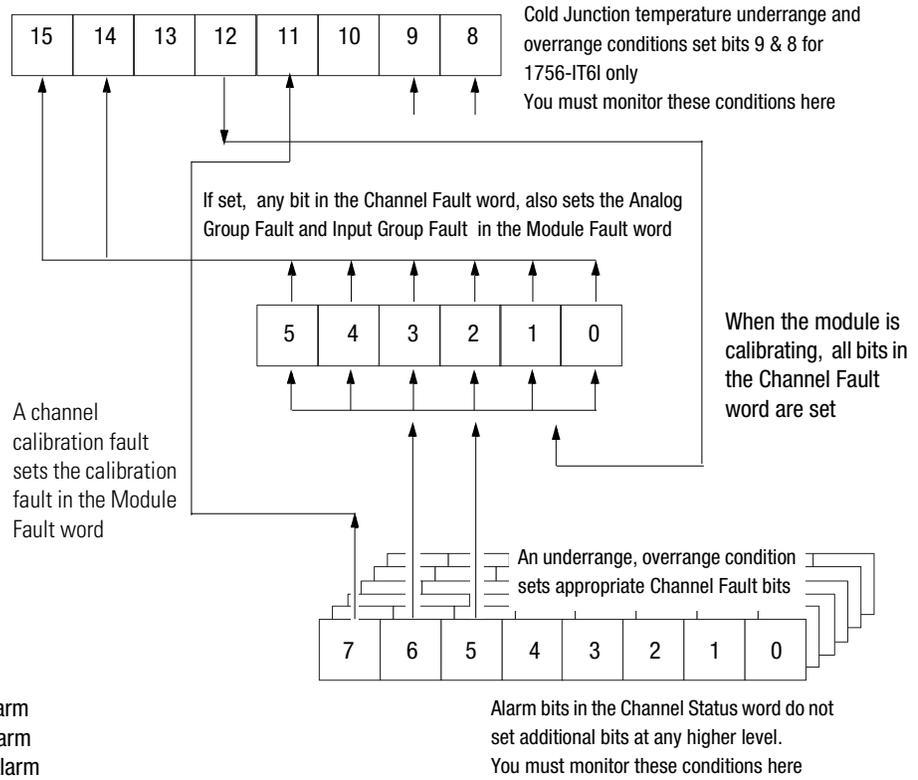
- 15 = AnalogGroupFault
- 14 = InGroupFault
- 12 = Calibrating
- 11 = Cal Fault
- 9 = CJUnderrange (IT6I only)
- 8 = CJOverrange (IT6I only)
- 13 & 10 are not used by 1756-IR6I or 1756-IT6I

Channel Fault Word
(described in Table 6.16 on page 6-24)

- 5 = Ch5Fault
- 4 = Ch4Fault
- 3 = Ch3Fault
- 2 = Ch2Fault
- 1 = Ch1Fault
- 0 = Ch0Fault

Channel Status Words
(one for each channel—described in Table 6.17 on page 6-25)

- 7 = ChxCalFault
- 6 = ChxUnderrange
- 5 = ChxOverrange
- 4 = ChxRateAlarm
- 3 = ChxLAlarm
- 2 = ChxHAlarm
- 1 = ChxLLAlarm
- 0 = ChxHAlarm



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Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 6.15 lists tags that are found in the Module Fault Word:

Table 6.15

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Input Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is InputGroup.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.
Cold Junction Underrange – 1756-IT6I and 1756-IT6I2only	This bit is set when the ambient temperature around the Cold Junction Sensor is below 0°C. Its tag name is CJUnderrange.
Cold Junction Overrange – 1756-IT6I and 1756-IT6I2only	This bit is set when the ambient temperature around the Cold Junction Sensor is above 86°C. Its tag name is CJOverrange.

Channel Fault Word Bits – Floating Point Mode

During normal module operation, bits in the Channel Fault word are set if any of the respective channels has an Under or Overrange condition. Checking this word for a nonzero value is a quick way to check for Under or Overrange conditions on the module.

Table 6.16 lists the conditions that set **all** Channel Fault word bits:

Table 6.16

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

Channel Status Word Bits – Floating Point Mode

Any of the 6 Channel Status words, one for each channel, will display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words. When the Underrange and Overrange bits (bits 6 & 5) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 6.17 lists the conditions that set each of the word bits.

Table 6.17

Tag (Status word):	Bit:	Event that sets this tag:
ChxCalFault	Bit 7	This bit is set if an error occurs during calibration for that channel, causing a bad calibration. This bit also sets bit 9 in the Module Fault word.
Underrange	Bit 6	This bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 6.6 on page 6-5. This bit also sets the appropriate bit in the Channel Fault word.
Overrange	Bit 5	This bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 6.6 on page 6-5. This bit also sets the appropriate bit in the Channel Fault word.
ChxRateAlarm	Bit 4	This bit is set when the input channel's rate of change exceeds the configured Rate Alarm parameter. It remains set until the rate of change drops below the configured rate. If latched, the alarm remains set until it is unlatched.
ChxLAlarm	Bit 3	This bit is set when the input signal moves beneath the configured Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm will remain set until it is unlatched. If a deadband is specified, the alarm will also remain set as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 2	This bit is set when the input signal moves above the configured High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains set as long as the signal remains within the configured deadband.
ChxLLAlarm	Bit 1	This bit is set when the input signal moves beneath the configured Low-Low Alarm limit. It remains set until the signal moves above the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains latched as long as the signal remains within the configured deadband.
ChxHAlarm	Bit 0	This bit is set when the input signal moves above the configured High-High Alarm limit. It remains set until the signal moves below the configured trigger point. If latched, the alarm remains set until it is unlatched. If a deadband is specified, the alarm also remains latched as long as the signal remains within the configured deadband.

Fault Reporting in Integer Mode

Figure 6.13 offers an overview of the fault reporting process in integer mode.

Figure 6.13

Module Fault Word
(described in Table 6.15 on page 6-24)

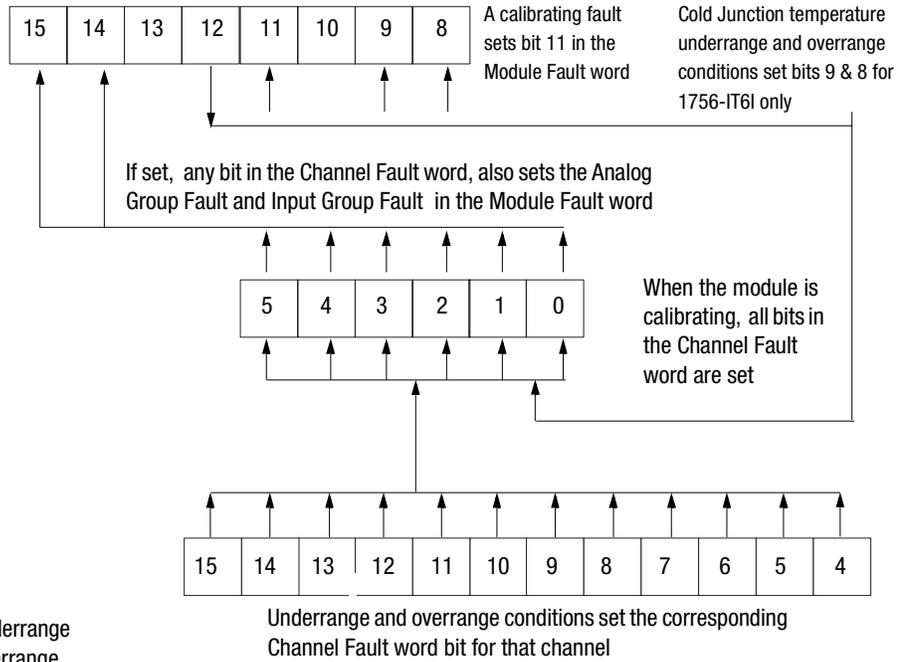
- 15 = AnalogGroupFault
- 14 = InGroupFault
- 12 = Calibrating
- 11 = Cal Fault
- 9 & 8 = CJUnderOver
- 13 & 10 are not used by 1756-IR6I or IT6I

Channel Fault Word
(described in Table 6.16 on page 6-24)

- 5 = Ch5Fault
- 4 = Ch4Fault
- 3 = Ch3Fault
- 2 = Ch2Fault
- 1 = Ch1Fault
- 0 = Ch0Fault

Channel Status Words
(described in Table 6.17 on page 6-25)

- | | |
|--------------------|-------------------|
| 15 = Ch0Underrange | 9 = Ch3Underrange |
| 14 = Ch0Overrange | 8 = Ch3Overrange |
| 13 = Ch1Underrange | 7 = Ch4Underrange |
| 12 = Ch1Overrange | 6 = Ch4Overrange |
| 11 = Ch2Underrange | 5 = Ch5Underrange |
| 10 = Ch2Overrange | 4 = Ch5Overrange |



Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-8) operate exactly as described in floating point mode. Table 6.18 lists tags that are found in the Module Fault Word:

Table 6.18

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Input Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is InputGroup.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.
Cold Junction Underrange – 1756-IT6I only	This bit is set when the ambient temperature around the Cold Junction Sensor is below 0°C. Its tag name is CJUnderrange.
Cold Junction Overrange – 1756-IT6I only	This bit is set when the ambient temperature around the Cold Junction Sensor is above 86°C. Its tag name is CJOverrange.

Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits operate exactly as described in floating point mode. Table 6.19 lists the conditions that set **all** Channel Fault word bits:

Table 6.19

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic can monitor the Channel Fault Word bit for a particular input to determine the state of that point.

Channel Status Word Bits – Integer Mode

The Channel Status word has the following differences when used in integer mode:

- Only Underrange and Overrange conditions are reported by the module.
- Alarming and Calibration Fault activities are not available, although the Calibration Fault bit in the Module Fault word will activate if a channel is not properly calibrated.
- There is only 1 Channel Status word for all 6 channels.

When the Calibration Fault bit (bit 7) is set in any of the words, the Calibration Fault bit (bit 9) is set in the Module Fault word. Table 6.20 lists the conditions that set each of the words.

Table 6.20

Tag (Status word):	Bit:	Event that sets this tag:
ChxUnderrange	Odd-numbered bits from bit 15 to bit 5 (e.g. bit 15 represents channel 0). For a full listing of the channels these bits represent, see Figure 6.13 on page 6-26.	The underrange bit is set when the input signal at the channel is less than or equal to the minimum detectable signal. For more information on the minimum detectable signal for each module, see Table 6.6 on page 6-5. This bit also sets the appropriate bit in the Channel Fault word.
ChxOverrange	Even-numbered bits from bit 14 to bit 4 (e.g. bit 14 represents channel 0). For a full listing of the channels these bits represent, see Figure 6.13 on page 6-26.	The overrange bit is set when the input signal at the channel is greater than or equal to the maximum detectable signal. For more information on the maximum detectable signal for each module, see Table 6.6 on page 6-5. This bit also sets the appropriate bit in the Channel Fault word.

Chapter Summary and What's Next

In this chapter you read about features specific to the Temperature Measuring Analog Modules (1756-IR6I, 1756-IT6I & 1756-IT6I2).

Chapter 7 describes features specific to the Non-Isolated Analog Output Modules (1756-OF4 & 1756-OF8).

Non-Isolated Analog Output Modules (1756-OF4 & 1756-OF8)

What This Chapter Contains This chapter describes features specific to ControlLogix non-isolated analog output modules.

For information about:	See page:
Choosing a Data Format	7-2
Features Specific to Analog Output Modules	7-2
Using Module Block and Output Circuit Diagrams	7-6
Wiring the 1756-OF4 Module	7-9
Wiring the 1756-OF8 Module	7-10
1756-OF4 and 1756-OF8 Module Fault and Status Reporting	7-11

The non-isolated analog output modules also support features described in Chapter 3. Table 7.1 lists those additional features.

Table 7.1 Additional Features Supported by the Non-Isolated Analog Output Modules

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Choosing a Data Format

Data format defines the format of channel data sent from the controller to the module, defines the format of the “data echo” that the module produces, and determines the features that are available to your application. You choose a data format when you choose a Communications Format. For more information on Communications Format, see page 10-6.

You can choose one of the two following data formats:

- Integer mode
- Floating point mode

Table 7.2 lists the features that are available in each format.

Table 7.2 Features Available in Each Data Format

Data format:	Features available:	Features not available:
Integer mode	Ramp to program value Ramp to fault value Hold for initialization Hold Last State or User Value in fault or program mode	Clamping Ramp in Run mode Rate and Limit alarms Scaling
Floating point mode	All features	N/A

Features Specific to Analog Output Modules

Table 7.3 lists features that are specific to the non-isolated analog output modules. The features are described later in this section.

Table 7.3

Feature:	Page of description:
Ramping/Rate Limiting	7-3
Hold for Initialization	7-4
Open Wire Detection	7-4
Clamping/Limiting	7-5
Clamp/Limit Alarms	7-5
Data Echo	7-6

Ramping/Rate Limiting

Ramping limits the speed at which an analog output signal can change. This prevents fast transitions in the output from damaging the devices that an output module controls. Ramping is also known as **rate limiting**.

Table 7.4 describes the types of ramping that are possible:

Table 7.4

Ramping type:	Description:
Run mode ramping	This type of ramping occurs when the module is in Run mode and begins operation at the configured maximum ramp rate when the module receives a new output level. IMPORTANT: This is only available in floating point mode.
Ramp to program mode	This type of ramping occurs when the present output value changes to the Program Value after a Program Command is received from the controller.
Ramp to fault mode	This type of ramping occurs when the present output value changes to the Fault Value after a communications fault occurs.

The maximum rate of change in outputs is expressed in engineering units per second and called the **maximum ramp rate**. To see how to enable Run mode ramping and set the maximum ramp rate, see page 10-13.

Hold for Initialization

Hold for Initialization causes outputs to hold present state until the value commanded by the controller matches the value at the output screw terminal within 0.1% of full scale, providing a bumpless transfer.

If Hold for Initialization is selected, outputs hold if any of the three conditions occur:

- Initial connection is established after power-up
- A new connection is established after a communications fault occurs
- There is a transition to Run mode from Program state

The InHold bit for a channel indicates that the channel is holding. To see how to enable the Hold for Initialization bit, see page 10-12.

Open Wire Detection

This feature detects when current flow is not present at any channel. The 1756-OF4 and 1756-OF8 modules must be configured for 0-20mA operation to use this feature. At least 0.1mA of current must be flowing from the output for detection to occur.

When an open wire condition occurs at any channel, a status bit is set for that channel. For more information on the use of status bits, see page 7-11.

Clamping/Limiting

Clamping limits the output from the analog module to remain within a range configured by the controller, even when the controller commands an output outside that range. This safety feature sets a high clamp and a low clamp.

Once clamps are determined for a module, any data received from the controller that exceeds those clamps sets an appropriate limit alarm and transitions the output to that limit but not beyond the requested value.

For example, an application may set the high clamp on a module for 8V and the low clamp for -8V. If a controller sends a value corresponding to 9V to the module, the module will only apply 8V to its screw terminals.

Clamping alarms can be disabled or latched on a per channel basis.

IMPORTANT

Clamping is only available in floating point mode.

To see how to set the clamping limits, see page 10-13.

Clamp/Limit Alarms

This function works directly with clamping. When a module receives a data value from the controller that exceeds clamping limits, it applies signal values to the clamping limit but also sends a status bit to the controller notifying it that the value sent exceeds the clamping limits.

Using the example above, if a module has clamping limits of 8V and -8V but then receives data to apply 9V, only 8V is applied to the screw terminals and the module sends a status bit back to the controller informing it that the 9V value exceeds the module's clamping limits.

IMPORTANT

Limit alarms are only available in floating point mode.

To see how to enable all alarms, see page 10-13.

Data Echo

Data Echo automatically multicasts channel data values which match the analog value that was sent to the module's screw terminals at that time.

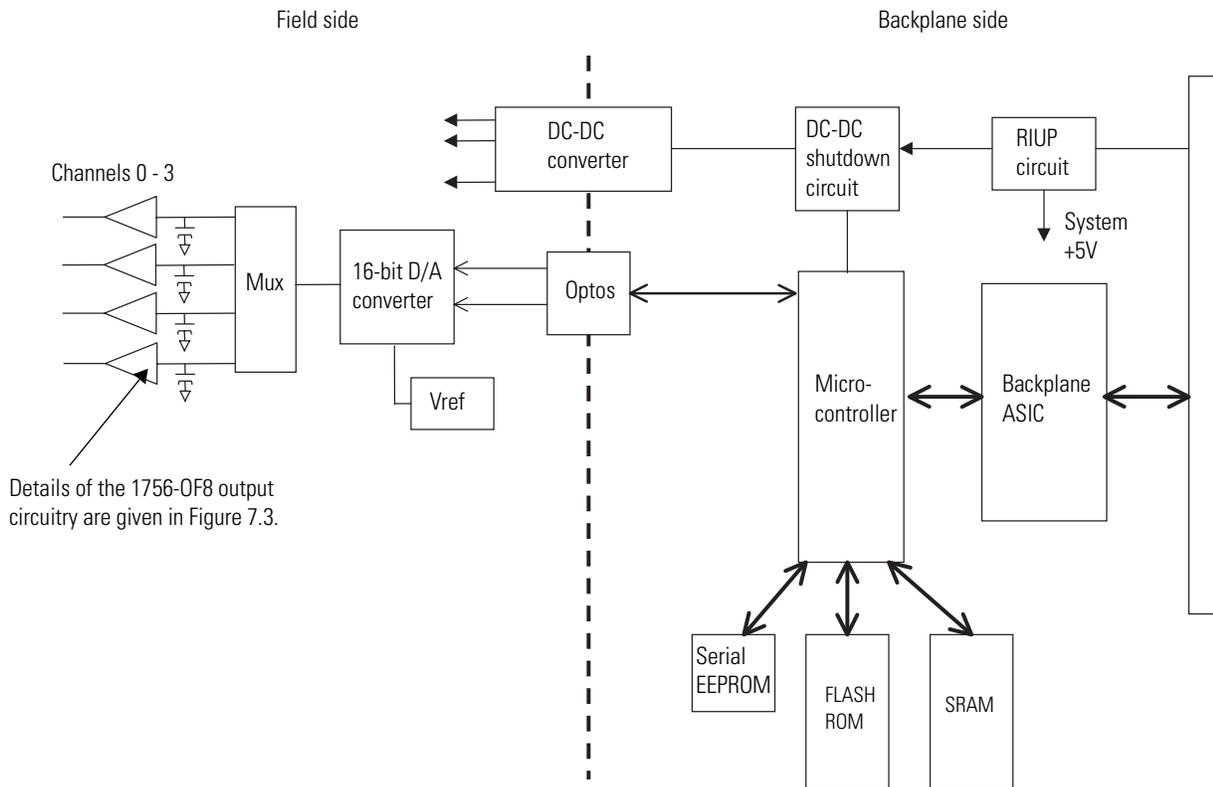
Fault and status data is also sent. This data is sent in the format (floating point or integer) selected at the Requested Packet Interval (RPI).

Using Module Block and Output Circuit Diagrams

This section shows the 1756-OF4 and 1756-OF8 modules' block diagrams and output circuit diagrams.

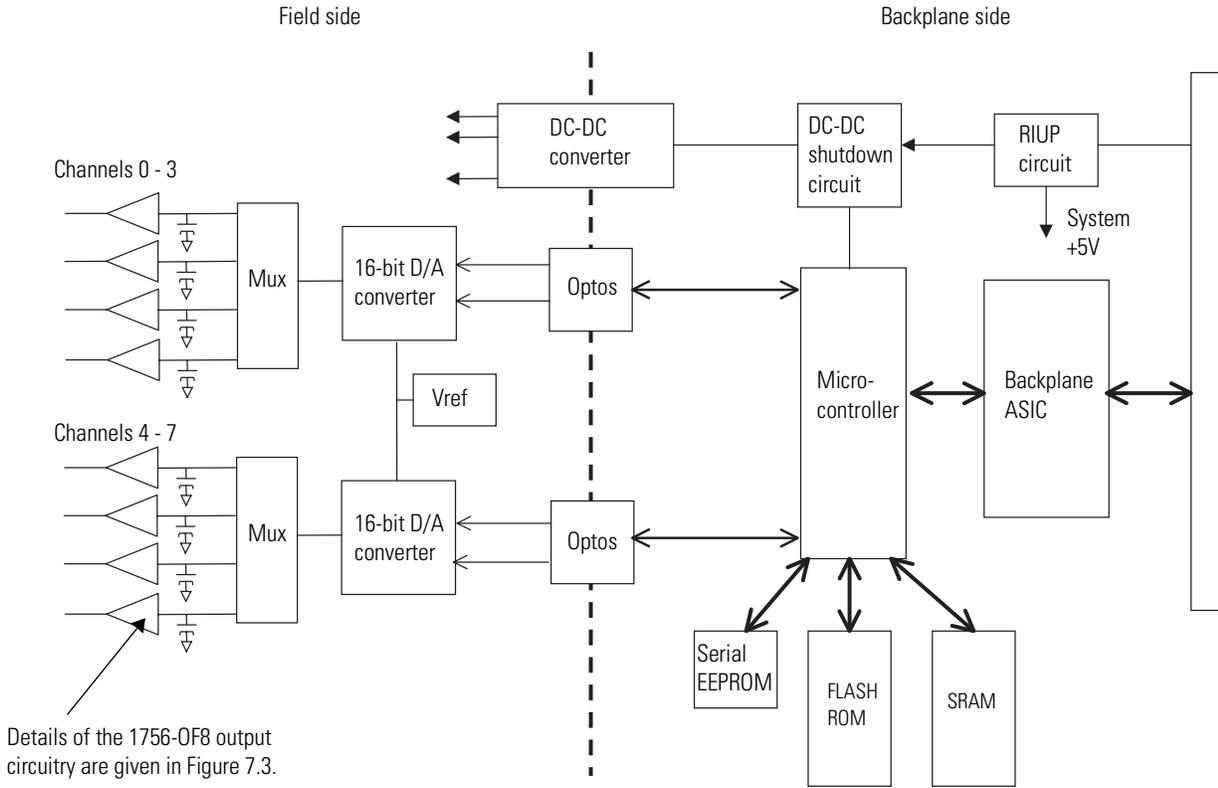
Module Block Diagram

Figure 7.1 1756-OF4 Module Block Diagram



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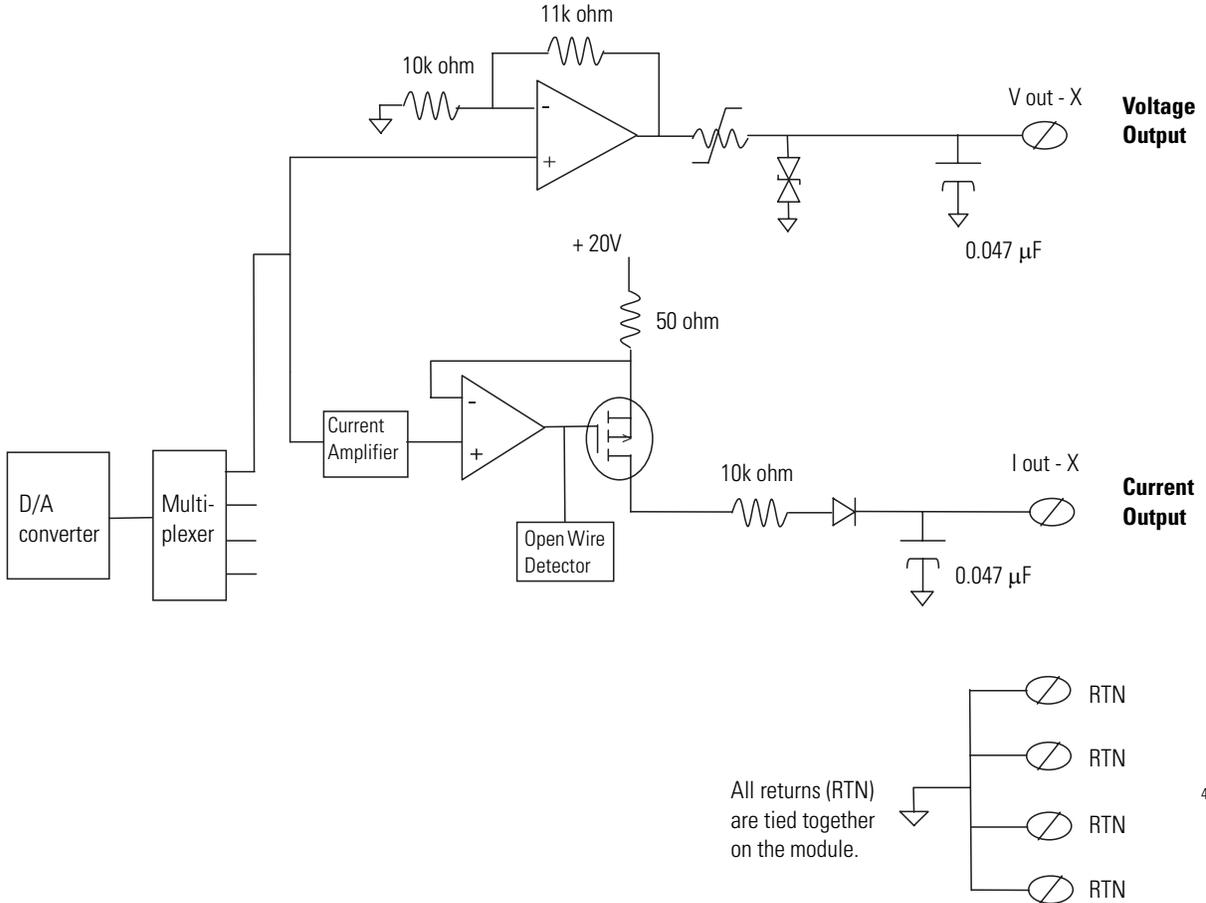
Figure 7.2 1756-OF8 Module Block Diagram



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Field Side Circuit Diagrams

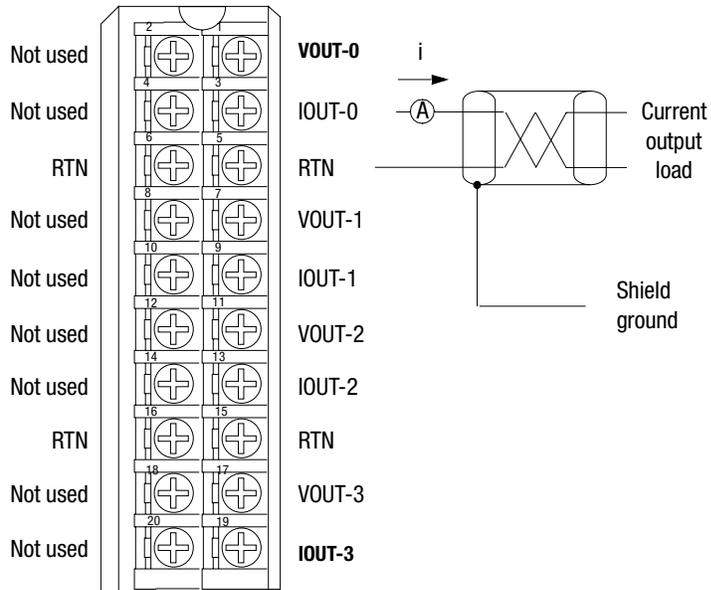
Figure 7.3 1756-OF4 and 1756-OF8 Output Circuit



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Wiring the 1756-OF4 Module

Figure 7.4 1756-OF4 Current wiring example

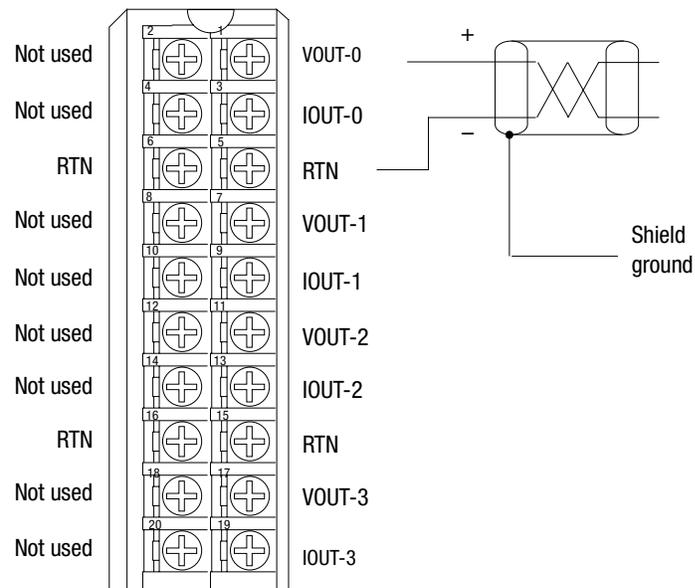


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NOTES:

1. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location noted above.
2. Do not connect more than 2 wires to any single terminal.
3. All terminals marked RTN are connected internally.

Figure 7.5 1756-OF4 Voltage wiring example



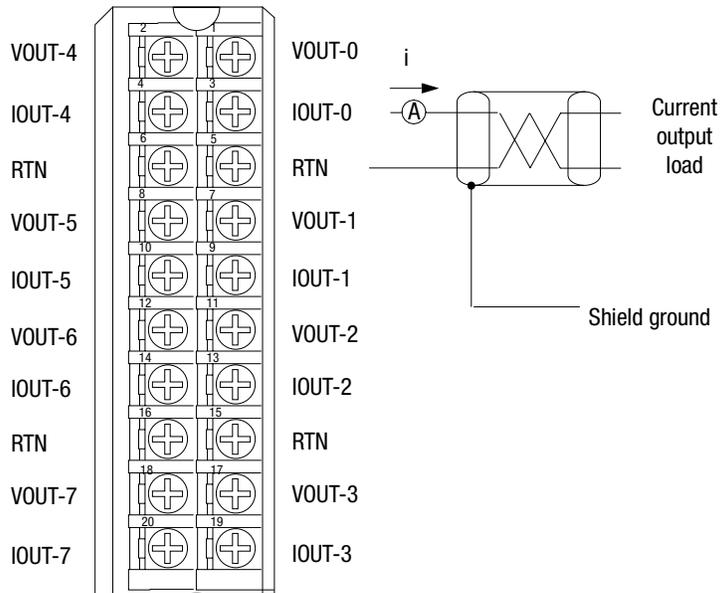
NOTES:

1. Do not connect more than 2 wires to any single terminal.
2. All terminals marked RTN are connected internally.

40917-M

Wiring the 1756-OF8 Module

Figure 7.6 1756-OF8 Current wiring example

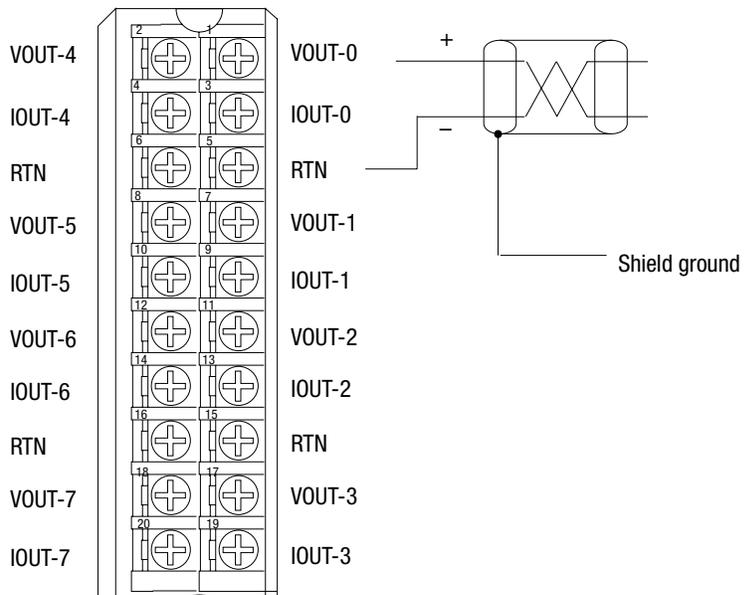


NOTES:

1. Place additional loop devices (e.g. strip chart recorders, etc.) at the A location noted above.
2. Do not connect more than 2 wires to any single terminal.
3. All terminals marked RTN are connected internally.

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Figure 7.7 1756-OF8 Voltage wiring example



NOTES:

1. Do not connect more than 2 wires to any single terminal.
2. All terminals marked RTN are connected internally.

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1756-OF4 and 1756-OF8 Module Fault and Status Reporting

The 1756-OF4 and 1756-OF8 modules multicast status/fault data to the owner/listening controller with their channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide increasing degree of detail as to the specific cause of faults on the module.

Table 7.5 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 7.5

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults.
Channel Status Words	This word provides individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

1756-OF4 and 1756-OF8 Fault Reporting in Floating Point Mode

Figure 7.8 offers an overview of the fault reporting process in floating point mode.

Figure 7.8

Module Fault Word
(described in Table 7.6 on page 7-13)

- 15 = AnalogGroupFault
- 12 = Calibrating
- 11 = Cal Fault
- 14 & 13 are not used by the 1756-OF4 or -OF8

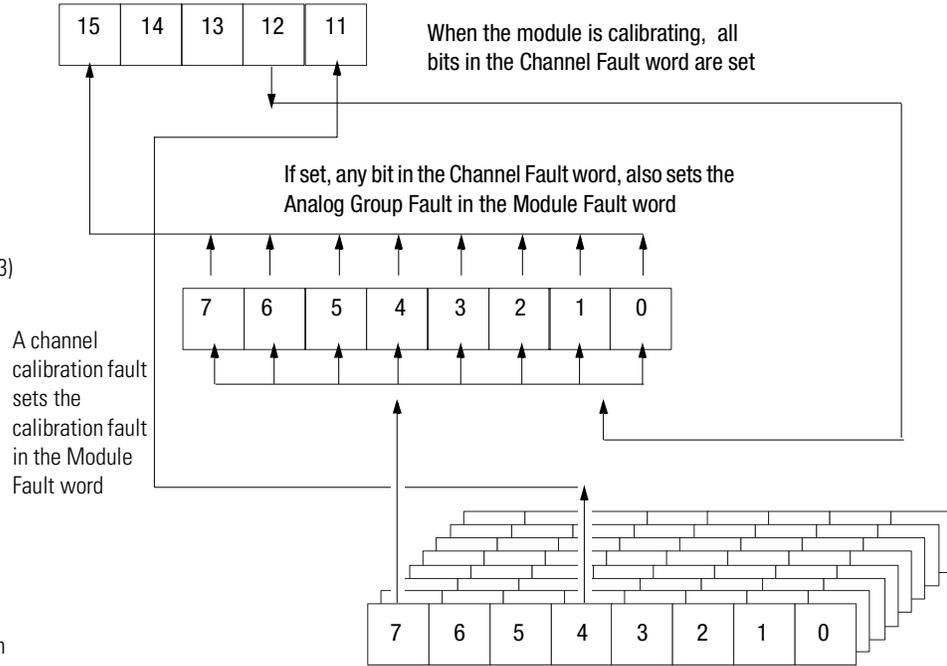
Channel Fault Word
(described in Table 7.7 on page 7-13)

- 7 = Ch7Fault
- 6 = Ch6Fault
- 5 = Ch5Fault
- 4 = Ch4Fault
- 3 = Ch3Fault
- 2 = Ch2Fault
- 1 = Ch1Fault
- 0 = Ch0Fault

Channel Status Words
(one for each channel—described in Table 7.8 on page 7-14)

- 7 = ChxOpenWire
 - 5 = ChxNotANumber
 - 4 = ChxCalfault
 - 3 = ChxInHold
 - 2 = ChxRampAlarm
 - 1 = ChxLLimitAlarm
 - 0 = ChxHLimitAlarm
- 6 is not used by 1756-OF4 or -OF8

IMPORTANT: 1756-OF4 uses 4 Channel Status Words. 1756-OF8 uses 8 Channel Status words. This graphic shows 8 words.



Not a Number, Output in Hold, and Ramp Alarm conditions do not set additional bits. You must monitor them here

Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 7.6 lists tags that are found in the Module Fault Word:

Table 7.6

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Floating Point Mode

During normal module operation, Channel Fault word bits are set if any of the respective channels has a High or Low Limit Alarm or an Open Wire condition (0-20mA configuration only). When using the Channel Fault Word, the 1756-OF4 module uses bits 0-3, and the 1756-OF8 uses bits 0-7. Checking this word for a nonzero condition is a quick way to check for these conditions on a channel.

Table 7.7 lists the conditions that set **all** Channel Fault word bits:

Table 7.7

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"000F" for all bits on the 1756-OF4 module "00FF" for all bits on the 1756-OF8 module
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits on either module

Your logic should monitor the Channel Fault bit for a particular output, if you either:

- enable output clamping

or

- are checking for a open wire condition (0-20mA configuration only).

Channel Status Words Bits – Floating Point Mode

Any of the Channel Status words (4 words for 1756-OF4 and 8 words for 1756-OF8), one for each channel, will display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words.

When the High or Low Limit Alarm bits (bits 1 & 0) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 4) is set in any of the words, the Calibration Fault bit (bit 11) is set in the Module Fault word. Table 7.8 lists the conditions that set each of the word bits.

Table 7.8

Tag (Status word):	Bit:	Event that sets this tag:
ChxOpenWire	Bit 7	This bit is set only if the configured Output Range is 0-20mA, and the circuit becomes open due to a wire falling or being cut when the output being driven is above 0.1mA. The bit will remain set until correct wiring is restored.
ChxNotaNumber	Bit 5	This bit is set when the output value received from the controller is NotANumber (the IEEE NAN value). The output channel will hold its last state.
ChxCalFault	Bit 4	This bit is set when an error occurred when calibrating. This bit also sets the appropriate bit in the Channel Fault word.
ChxInHold	Bit 3	This bit is set when the output channel is currently holding. The bit resets when the requested Run mode output value is within 0.1% of full-scale of the current echo value.
ChxRampAlarm	Bit 2	This bit is set when the output channel's requested rate of change would exceed the configured maximum ramp rate requested parameter. It remains set until the output reaches its target value and ramping stops. If the bit is latched, it will remain set until it is unlatched.
ChxLLimitAlarm	Bit 1	This bit is set when the requested output value is beneath the configured low limit value. It remains set until the requested output is above the low limit. If the bit is latched, it will remain set until it is unlatched.
ChxHLimitAlarm	Bit 0	This bit is set when the requested output value is above the configured high limit value. It remains set until the requested output is below the high limit. If the bit is latched, it will remain set until it is unlatched.

IMPORTANT

Notice that the 1756-OF4 and 1756-OF8 modules do not use **bit 6**.

1756-OF4 and 1756-OF8 Fault Reporting in Integer Mode

The following graphic provides an overview of the fault reporting process in integer mode.

Figure 7.9

Module Fault Word
(described in Table 7.9 on page 7-16)

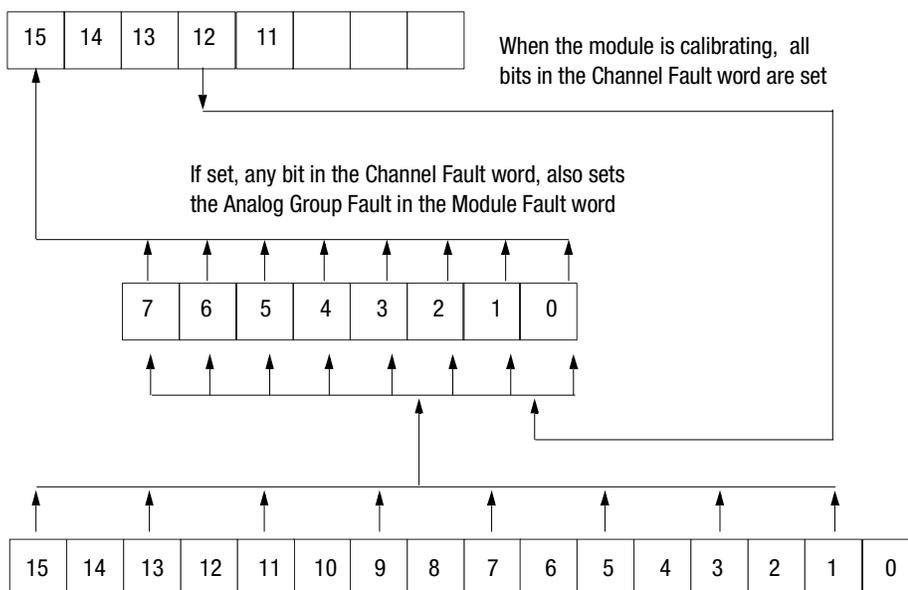
- 15 = AnalogGroupFault
- 12 = Calibrating
- 11 = Cal Fault
- 14 & 13 are not used by 1756-OF4 or -OF8

Channel Fault Word
(described in Table 7.10 on page 7-16)

- 7 = Ch7Fault 3 = Ch3Fault
- 6 = Ch6Fault 2 = Ch2Fault
- 5 = Ch5Fault 1 = Ch1Fault
- 4 = Ch4Fault 0 = Ch0Fault

Channel Status Words
(described in Table 7.11 on page 7-17)

- 15 = Ch0OpenWire 7 = Ch4OpenWire
- 14 = Ch0InHold 6 = Ch4InHold
- 13 = Ch1OpenWire 5 = Ch5OpenWire
- 12 = Ch1InHold 4 = Ch5InHold
- 11 = Ch2OpenWire 3 = Ch6OpenWire
- 10 = Ch2InHold 2 = Ch6InHold
- 9 = Ch3OpenWire 1 = Ch7OpenWire
- 8 = Ch3InHold 0 = Ch7InHold



Open Wire conditions (odd numbered bits) set the appropriate bits in the Channel fault Word

Output in Hold conditions (even numbered bits) must be monitored here

41520

IMPORTANT: Bits 0-7 not used on 1756-OF4

Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-11) operate exactly as described in floating point mode. Table 7.9 lists tags that are found in the Module Fault Word:

Table 7.9

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits (bits 7-0) operate exactly as described in floating point mode for calibration and communications faults. During normal operation, these bits are only set for an open wire condition. Table 7.10 lists the conditions that set **all** Channel Fault word bits:

Table 7.10

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"000F" for all bits on the 1756-OF4 module "00FF" for all bits on the 1756-OF8 module
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits on either module

Your logic should monitor the Channel Fault bit for a particular output, if you either:

- enable output clamping
- or
- are checking for a open wire condition (0-20mA configuration only).

Channel Status Word Bits – Integer Mode

The Channel Status word has the following differences when used in integer mode:

- Only the Output in Hold and Open Wire conditions are reported by the module.
- Calibration Fault reporting is not available in this word, although the Calibration Fault bit in the Module Fault word will still activate when that condition exists on any channel.
- There is only 1 Channel Status word for all 4 channels on 1756-OF4 and all 8 channels on 1756-OF8.

Table 7.11 lists the conditions that set each of the Status Word bits.

Table 7.11

Tag (Status word):	Bit:	Event that sets this tag:
ChxOpenWire	Odd-numbered bits from bit 15 to bit 1 (e.g. bit 15 represents channel 0). For a full listing of the channels these bits represent, see Figure 7.9 on page 7-15.	The Open Wire bit is set only if the configured Output Range is 0-20mA, and the circuit becomes open due to a wire falling or being cut when the output being driven is above 0.1mA. The bit will remain set until correct wiring is restored.
ChxInHold	Even-numbered bits from bit 14 to bit 0 (e.g. bit 14 represents channel 0). For a full listing of the channels these bits represent, see Figure 7.9 on page 7-15.	The Output In Hold bit is set when the output channel is currently holding. The bit resets when the requested Run mode output value is within 0.1% of full-scale of the current echo value.

Chapter Summary and What's Next

In this chapter you read about Non-Isolated Analog Output Modules (1756-OF4 & 1756-OF8).

Chapter 8 describes the Isolated Analog Output Modules (1756-OF6CI & 1756-OF6VI).

Notes:

Isolated Analog Output Modules (1756-OF6CI & 1756-OF6VI)

What This Chapter Contains This chapter describes features specific to ControlLogix non-isolated analog output modules.

For information about:	See page:
Choosing a Data Format	8-2
Features Specific to Analog Output Modules	8-2
Using Module Block and Output Circuit Diagrams	8-5
Wiring the 1756-OF6CI Module	8-9
Wiring the 1756-OF6VI Module	8-10
1756-OF6CI and 1756-OF6VI Module Fault and Status Reporting	8-11

The non-isolated analog output modules also support features described in Chapter 3. Table 8.1 lists those additional features.

Table 8.1 Additional Features Supported by the Isolated Analog Output Modules

Feature:	Page of description:
Removal and Insertion Under Power (RIUP)	3-2
Module Fault Reporting	3-3
Fully Software Configurable	3-3
Electronic Keying	3-4
Access to System Clock for Timestamping Functions	3-6
Rolling Timestamp	3-6
Producer/Consumer Model	3-6
Status Indicator Information	3-7
Full Class I Division 2 Compliance	3-7
UL, CSA, FM, CE, C-Tick, EEx, TUV Agency Certification	3-7
Field Calibration	3-8
Sensor Offset	3-8
Latching of Alarms	3-8

Choosing a Data Format

Data format defines the format of channel data sent from the controller to the module, defines the format of the “data echo” that the module produces, and determines the features that are available to your application. You choose a data format when you choose a Communications Format. For more information on Communications Format, see page 10-6.

You can choose one of the two following data formats:

- Integer mode
- Floating point mode

Table 8.2 lists the features that are available in each format.

Table 8.2 Features Available in Each Data Format

Data format:	Features available:	Features not available:
Integer mode	Ramp to program value Ramp to fault value Hold for initialization Hold Last State or User Value in fault or program mode	Clamping Ramp in Run mode Rate and Limit alarms Scaling
Floating point mode	All features	N/A

Features Specific to Analog Output Modules

Table 8.3 lists features that are specific to the non-isolated analog output modules. The features are described later in this section.

Table 8.3

Feature:	Page of description:
Ramping/Rate Limiting	8-3
Hold for Initialization	8-3
Clamping/Limiting	8-4
Clamp/Limit Alarms	8-4
Data Echo	8-5

Ramping/Rate Limiting

Ramping limits the speed at which an analog output signal can change. This prevents fast transitions in the output from damaging the devices that an output module controls. Ramping is also known as **rate limiting**.

Table 8.4 describes the types of ramping that are possible:

Table 8.4

Ramping type:	Description:
Run mode ramping	This type of ramping occurs when the module is in Run mode and begins operation at the configured maximum ramp rate when the module receives a new output level. IMPORTANT: This is only available in floating point mode.
Ramp to program mode	This type of ramping occurs when the present output value changes to the Program Value after a Program Command is received from the controller.
Ramp to fault mode	This type of ramping occurs when the present output value changes to the Fault Value after a communications fault occurs.

The maximum rate of change in outputs is expressed in engineering units per second and called the **maximum ramp rate**. To see how to enable Run mode ramping and set the maximum ramp rate, see page 10-13.

Hold for Initialization

Hold for Initialization causes outputs to hold present state until the value commanded by the controller matches the value at the output screw terminal within 0.1% of full scale, providing a bumpless transfer.

If Hold for Initialization is selected, outputs hold if any of the three conditions occur:

- Initial connection is established after power-up
- A new connection is established after a communications fault occurs
- There is a transition to Run mode from Program state

The InHold bit for a channel indicates that the channel is holding. To see how to enable the Hold for Initialization bit, see page 10-12.

Clamping/Limiting

Clamping limits the output from the analog module to remain within a range configured by the controller, even when the controller commands an output outside that range. This safety feature sets a high clamp and a low clamp.

Once clamps are determined for a module, any data received from the controller that exceeds those clamps sets an appropriate limit alarm and transitions the output to that limit but not beyond the requested value.

For example, an application may set the high clamp on a module for 8V and the low clamp for -8V. If a controller sends a value corresponding to 9V to the module, the module will only apply 8V to its screw terminals.

Clamping alarms can be disabled or latched on a per channel basis.

IMPORTANT

Clamping is only available in floating point mode.

To see how to set the clamping limits, see page 10-13.

Clamp/Limit Alarms

This function works directly with clamping. When a module receives a data value from the controller that exceeds clamping limits, it applies signal values to the clamping limit but also sends a status bit to the controller notifying it that the value sent exceeds the clamping limits.

Using the example above, if a module has clamping limits of 8V and -8V but then receives data to apply 9V, only 8V is applied to the screw terminals and the module sends a status bit back to the controller informing it that the 9V value exceeds the module's clamping limits.

IMPORTANT

Limit alarms are only available in floating point mode.

To see how to enable all alarms, see page 10-13.

Data Echo

Data Echo automatically multicasts channel data values which match the analog value that was sent to the module's screw terminals at that time.

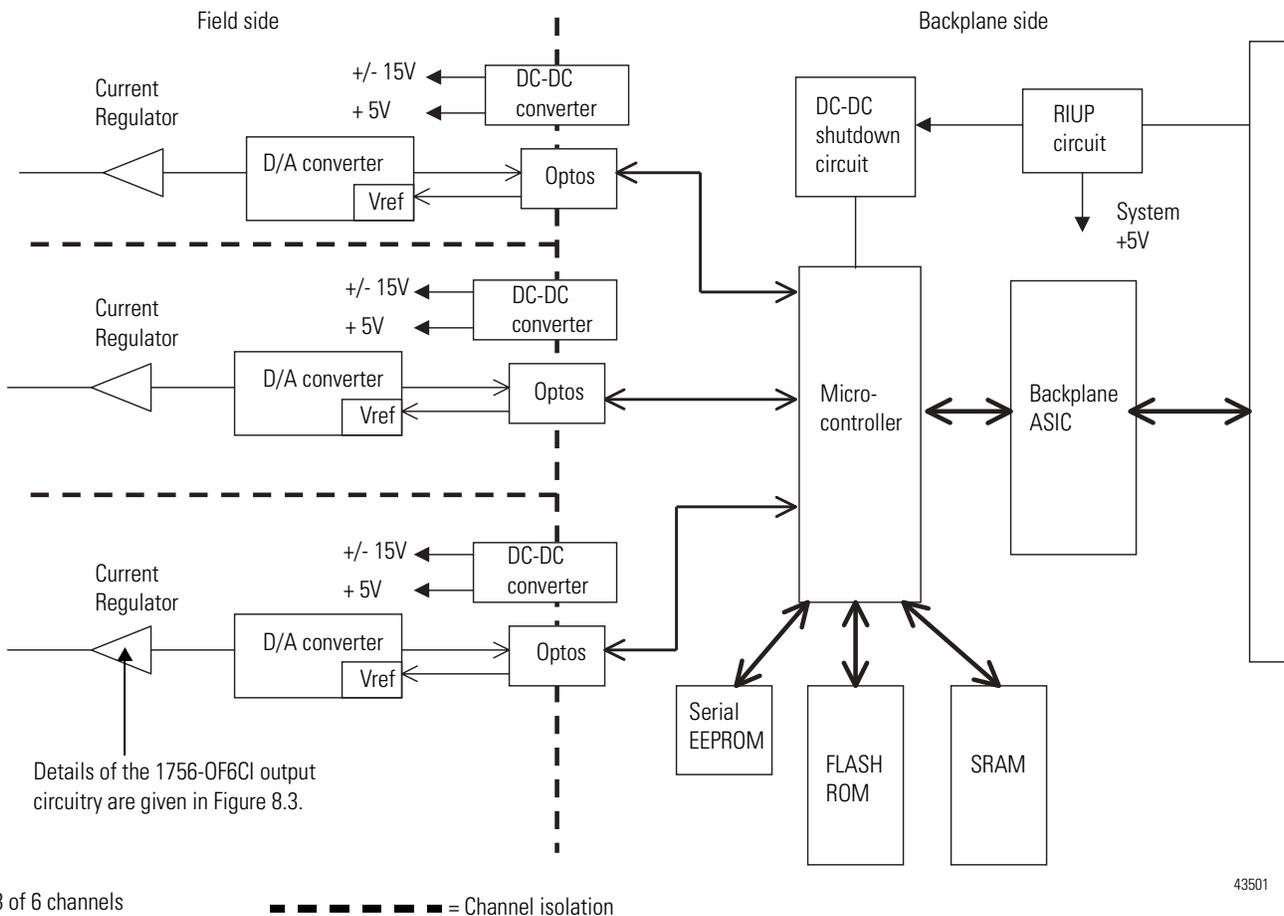
Fault and status data is also sent. This data is sent in the format (floating point or integer) selected at the Requested Packet Interval (RPI).

Using Module Block and Output Circuit Diagrams

This section shows the 1756-OF6CI and 1756-OF6VI modules' block diagrams and output circuit diagrams.

Module Block Diagram

Figure 8.1 1756-OF6CI Module Block Diagram

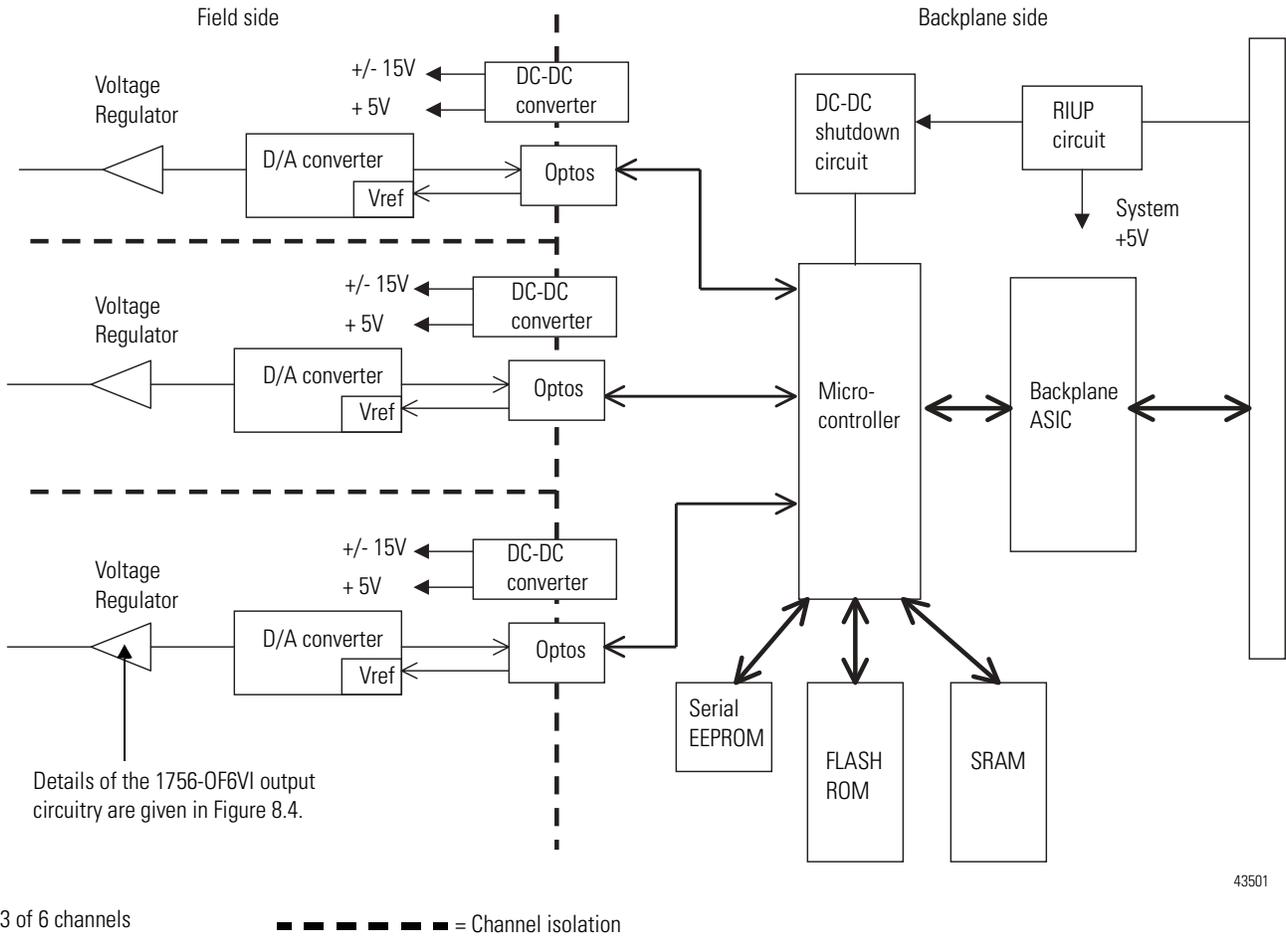


3 of 6 channels

----- = Channel isolation

43501

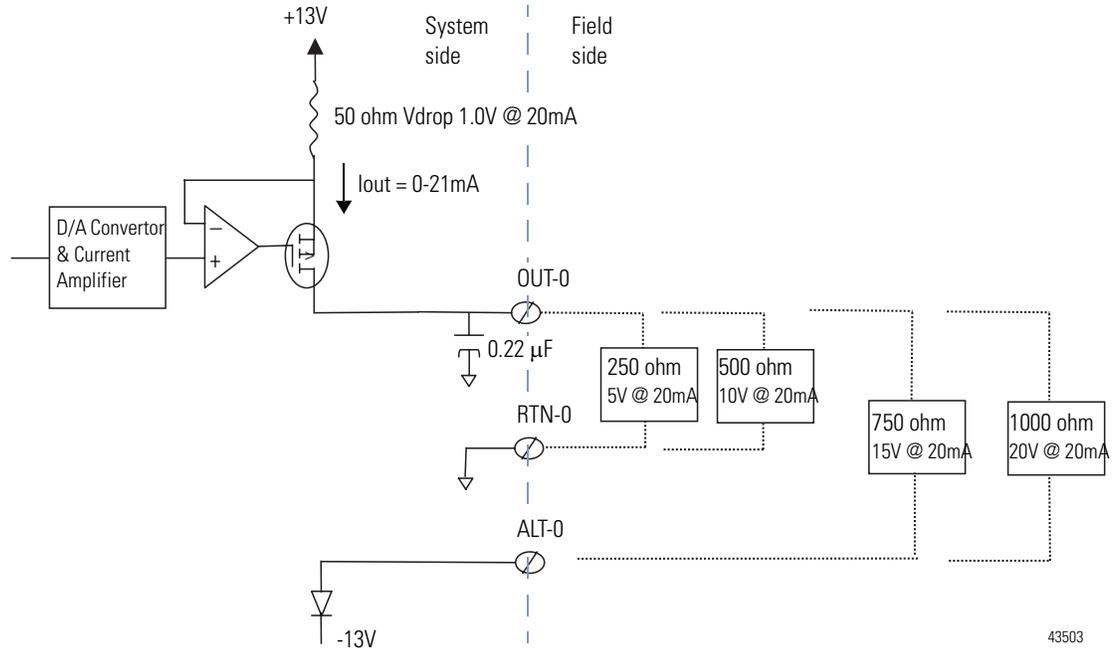
Figure 8.2 1756-OF6VI Module Block Diagram



43501

Field Side Circuit Diagrams

Figure 8.3 1756-OF6CI Output Circuit



43503

Driving Different Loads with the 1756-OF6CI

The 1756-OF6CI module's output stage provides a constant current that flows through its internal electronics and out through the external output load. Since the output current is constant, the only variable in the current loop is the voltage across the output electronics and the voltage across the load. For a given termination option, the sum of the individual voltage drops around the loop components must add up to the total available voltage (13V for OUT-x/RTN-x termination and 26V for OUT-x / ALT-x). As seen above, a larger external output load will drop a larger portion of the available loop voltage, allowing the module to drop less volts across its internal output electronics. This lower drop allows the power dissipation in the module to be lower, minimizing the thermal affect to adjacent modules in the same chassis.

For loads under 550 ohm, the module's +13V internal voltage source can supply voltage for currents up to 21mA. For loads over 550 ohms, additional compliance voltage is required. In this case, you must use the ALT terminal to provide the additional -13V source.

For any size load (i.e. 0-1000 ohms), the output channels function if terminated between OUT-x and ALT-x. To improve module reliability and product life, we recommend you:

- Terminate the output channels between the OUT-x and RTN-x terminals for loads of 0-550 ohms
- Terminate the output channels between the OUT-x and ALT-x terminals for loads of 551 -1000 ohms.

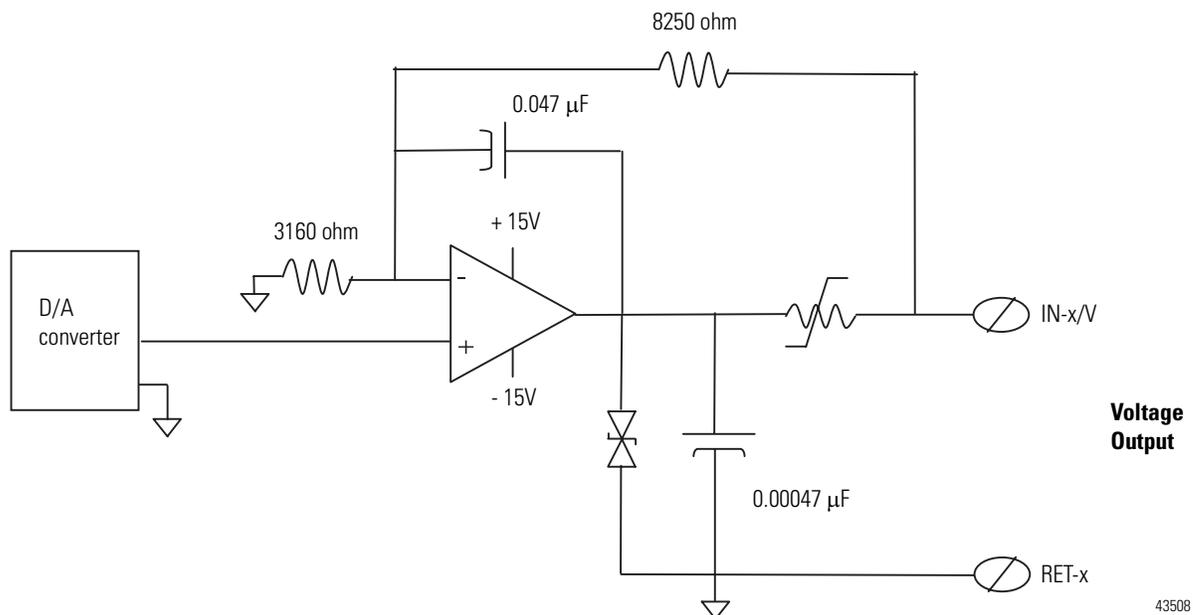
IMPORTANT

If you are unsure of the load, you can terminate the output channels between OUT-x and ALT-x and the module will operate but its reliability may be compromised at elevated temperatures.

For example, if you terminate the output channels between OUT-x and ALT-x and use a 250 ohm load, the module operates but the lower load results in higher operating temperatures and may affect the module's reliability over time.

We recommend you terminate the output channels as described in the bullets above whenever possible.

Figure 8.4 1756-OF6VI Output Circuit



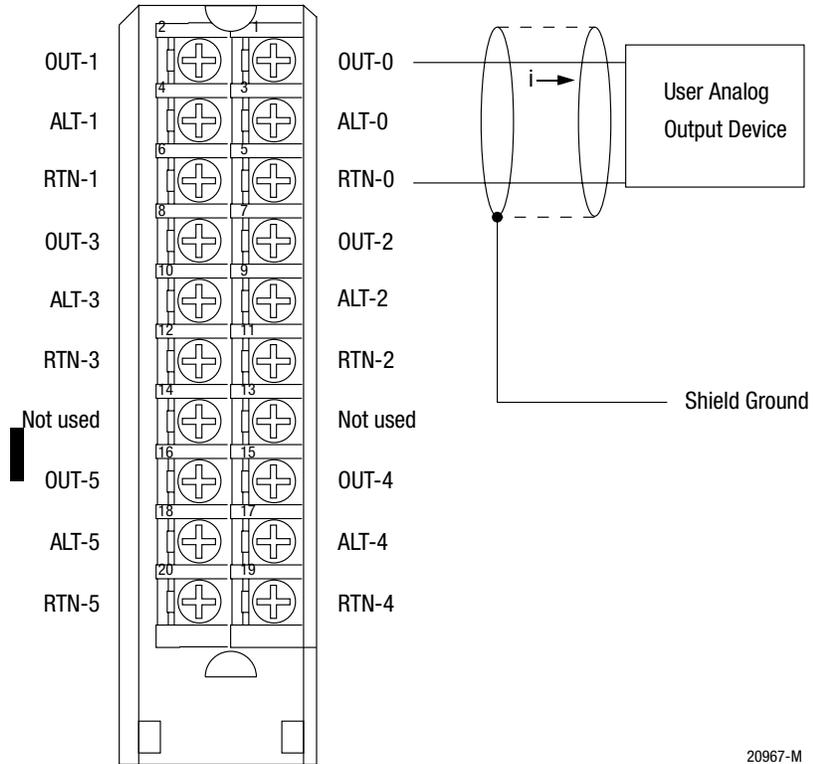
43508

Wiring the 1756-OF6CI Module

Figure 8.5 1756-OF6CI Wiring example for Loads of 0-550Ω

NOTES:

1. Place additional devices anywhere in the loop.
2. Do not connect more than 2 wires to any single terminal.

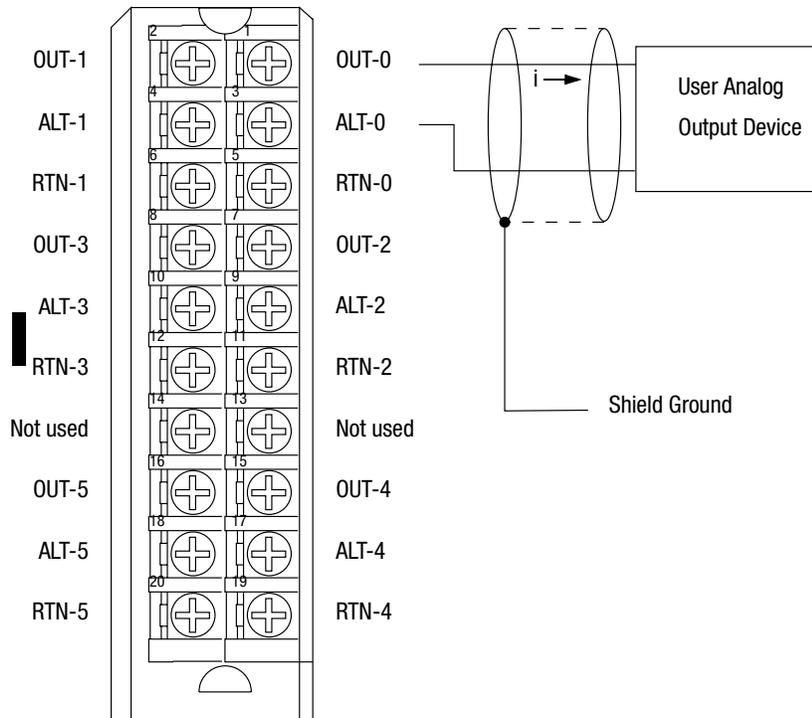


20967-M

Figure 8.6 1756-OF6CI Wiring example for Loads of 551-1000Ω

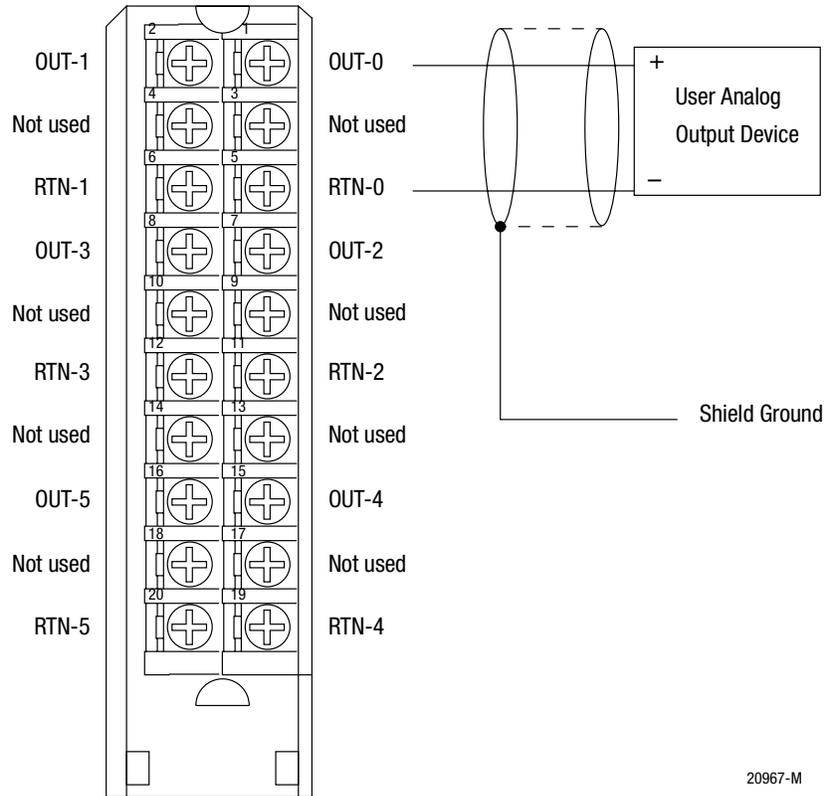
NOTES:

1. Place additional devices anywhere in the loop.
2. Do not connect more than 2 wires to any single terminal.



Wiring the 1756-OF6VI Module

Figure 8.7 1756-OF6VI Wiring example



20967-M

NOTES:

1. Place additional devices anywhere in the loop.
2. Do not connect more than 2 wires to any single terminal.

1756-OF6CI and 1756-OF6VI Module Fault and Status Reporting

The 1756-OF6CI and 1756-OF6VI modules multicast status/fault data to the owner/listening controller with their channel data. The fault data is arranged in such a manner as to allow the user to choose the level of granularity he desires for examining fault conditions.

Three levels of tags work together to provide increasing degree of detail as to the specific cause of faults on the module.

Table 8.5 lists tags that can be examined in ladder logic to indicate when a fault has occurred:

Table 8.5

Tag:	Description:
Module Fault Word	This word provides fault summary reporting. Its tag name is ModuleFaults.
Channel Fault Word	This word provides underrange, overrange and communications fault reporting. Its tag name is ChannelFaults.
Channel Status Words	This word provides individual channel underrange and overrange fault reporting for process alarms, rate alarms and calibration faults. Its tag name is ChxStatus.

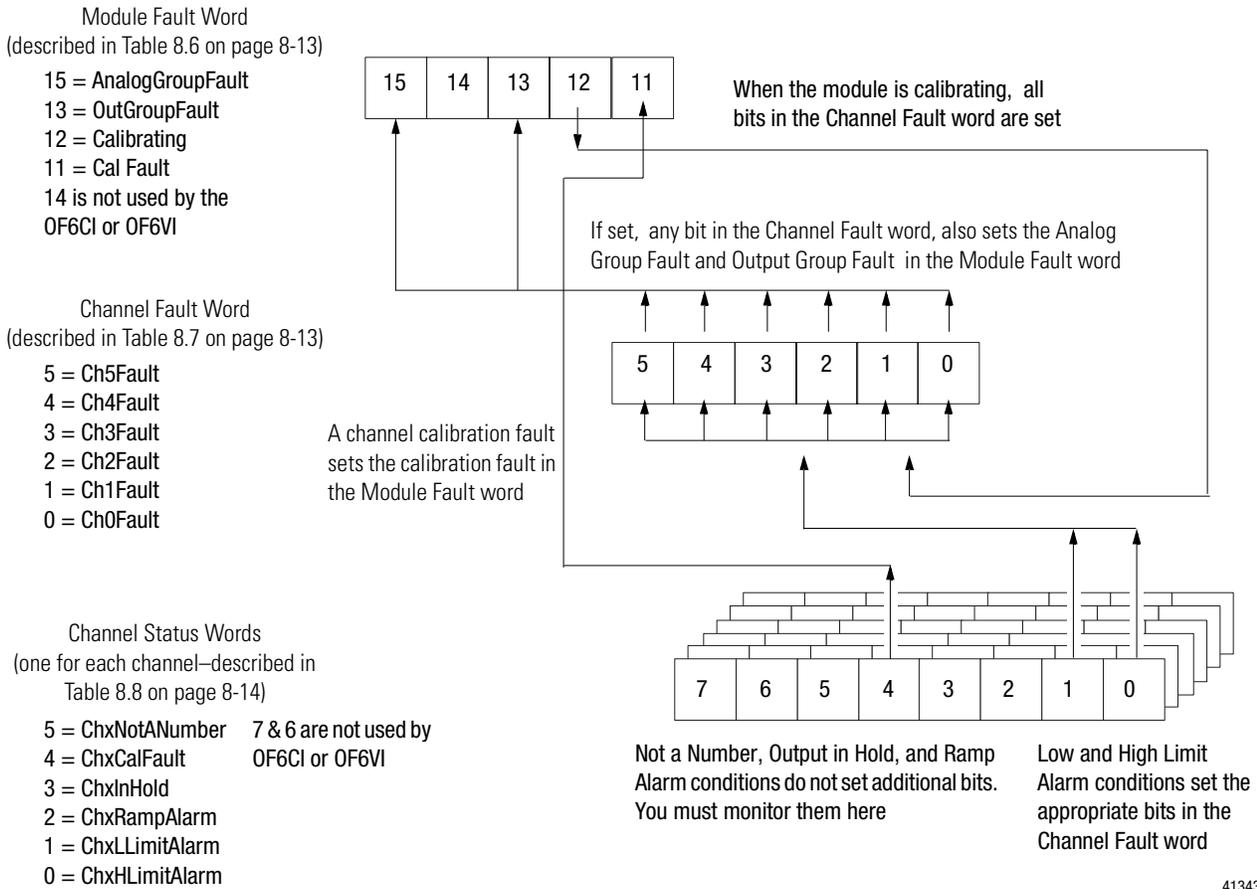
IMPORTANT

Differences exist between floating point and integer modes as they relate to module fault reporting. These differences are explained in the following two sections.

Fault Reporting in Floating Point Mode

Figure 8.8 offers an overview of the fault reporting process in floating point mode.

Figure 8.8



41343

Module Fault Word Bits – Floating Point Mode

Bits in this word provide the highest level of fault detection. A nonzero condition in this word reveals that a fault exists on the module. You can examine further down to isolate the fault.

Table 8.6 lists tags that are found in the Module Fault Word:

Table 8.6

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Output Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is OutputGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Floating Point Mode

During normal module operation, Channel Fault word bits are set if any of the respective channels has a High or Low Limit Alarm. Checking this word for a nonzero condition is a quick way to check for High or Low Limit Alarm condition on a channel.

Table 8.7 lists the conditions that set **all** Channel Fault word bits:

Table 8.7

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic should monitor the Channel Fault bit for a particular output, if you either:

- set the high and low limit alarms outside your operating range

or

- disable output limiting.

Channel Status Word Bits – Floating Point Mode

Any of the 6 Channel Status words, one for each channel, will display a nonzero condition if that particular channel has faulted for the conditions listed below. Some of these bits set bits in other Fault words.

When the High or Low Limit Alarm bits (bits 1 & 0) in any of the words are set, the appropriate bit is set in the Channel Fault word.

When the Calibration Fault bit (bit 4) is set in any of the words, the Calibration Fault bit (bit 11) is set in the Module Fault word. Table 8.8 lists the conditions that set each of the word bits.

Table 8.8

Tag (Status word):	Bit:	Event that sets this tag:
ChxNotaNumber	Bit 5	This bit is set when the output value received from the controller is NotaNumber (the IEEE NAN value). The output channel will hold its last state.
ChxCalFault	Bit 4	This bit is set when an error occurred when calibrating. This bit also sets the appropriate bit in the Channel Fault word.
ChxInHold	Bit 3	This bit is set when the output channel is currently holding. The bit resets when the requested Run mode output value is within 0.1% of full-scale of the current echo value.
ChxRampAlarm	Bit 2	This bit is set when the output channel's requested rate of change would exceed the configured maximum ramp rate requested parameter. It remains set until the output reaches its target value and ramping stops. If the bit is latched, it will remain set until it is unlatched.
ChxLLimitAlarm	Bit 1	This bit is set when the requested output value is beneath the configured low limit value. It remains set until the requested output is above the low limit. If the bit is latched, it will remain set until it is unlatched.
ChxHLimitAlarm	Bit 0	This bit is set when the requested output value is above the configured high limit value. It remains set until the requested output is below the high limit. If the bit is latched, it will remain set until it is unlatched.

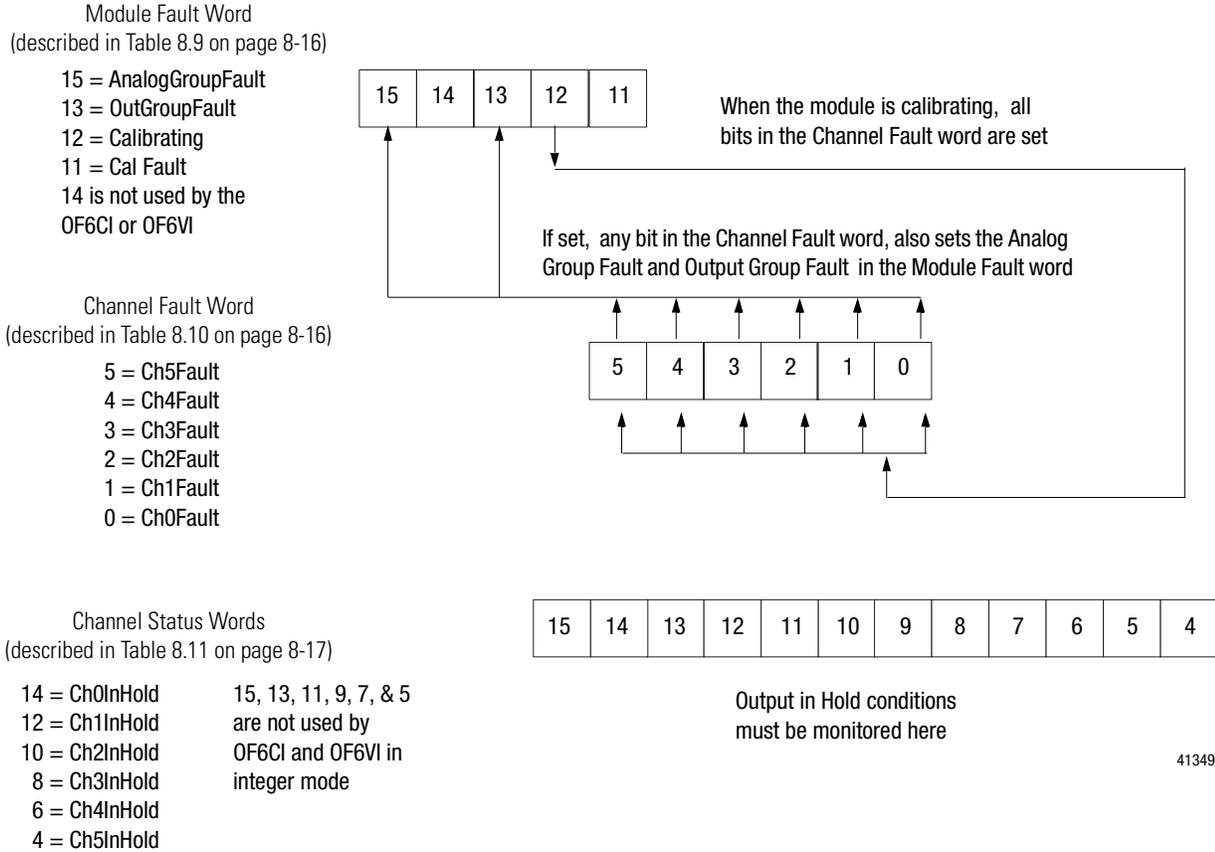
IMPORTANT

Notice that the 1756-OF6CI and 1756-OF6VI modules do not use **bits 6 or 7** in this mode.

Fault Reporting in Integer Mode

Figure 8.9 offers an overview of the fault reporting process in integer mode.

Figure 8.9



41349

Module Fault Word Bits – Integer Mode

In integer mode, Module Fault word bits (bits 15-11) operate exactly as described in floating point mode. Table 8.9 lists tags that are found in the Module Fault Word:

Table 8.9

Tag:	Description:
Analog Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is AnalogGroupFault.
Output Group Fault	This bit is set when any bits in the Channel Fault word are set. Its tag name is OutputGroupFault.
Calibrating	This bit is set when any channel is being calibrated. When this bit is set, all bits in the Channel Fault word are set. Its tag name is Calibrating.
Calibration Fault	This bit is set when any of the individual Channel Calibration Fault bits are set. Its tag name is CalibrationFault.

Channel Fault Word Bits – Integer Mode

In integer mode, Channel Fault word bits (bits 5-0) operate exactly as described in floating point mode for calibration and communications faults. Table 8.10 lists the conditions that set **all** Channel Fault word bits:

Table 8.10

This condition sets all Channel Fault word bits:	And causes the module to display the following in the Channel Fault word bits:
A channel is being calibrated	"003F" for all bits
A communications fault occurred between the module and its owner-controller	"FFFF" for all bits

Your logic should monitor the Channel Fault bit for a particular output, if you either:

- set the high and low limit alarms outside your operating range

or

- disable output limiting.

Channel Status Word Bits in Integer Mode

The Channel Status word has the following differences when used in integer mode:

- Only the Output in Hold condition is reported by the module.
- Calibration Fault reporting is not available in this word, although the Calibration Fault bit in the Module Fault word will still activate when that condition exists on any channel
- There is only 1 Channel Status word for all 6 channels.

Table 8.11 lists the conditions that set each of the word bits.

Table 8.11

Tag (Status word):	Bit:	Event that sets this tag:
ChxInHold	Even-numbered bits from bit 14 to bit 0 (e.g. bit 14 represents channel 0). For a full listing of the channels these bits represent, see Figure 8.9 on page 8-15.	The Output In Hold bit is set when the output channel is currently holding. The bit resets when the requested Run mode output value is within 0.1% of full-scale of the current echo value.

IMPORTANT

Notice that the 1756-OF6CI and 1756-OF6VI modules do not use **bits 15, 13, 11, 9, 7 or 5** in this mode.

Chapter Summary and What's Next

In this chapter you read about features specific to the Isolated Analog Output Modules (1756-OF6CI & 1756-OF6VI).

Chapter 9 describes Installing ControlLogix I/O Modules.

Notes:

Installing ControlLogix I/O Modules

What this Chapter Contains This chapter describes how to install ControlLogix modules.

For information about:	See page:
Installing the ControlLogix I/O Module	9-1
Keying the Removable Terminal Block	9-3
Connecting Wiring	9-4
Assembling The Removable Terminal Block and the Housing	9-8
Installing the Removable Terminal Block onto the Module	9-9
Removing the Removable Terminal Block from the Module	9-10
Removing the Module from the Chassis	9-11

Installing the ControlLogix I/O Module

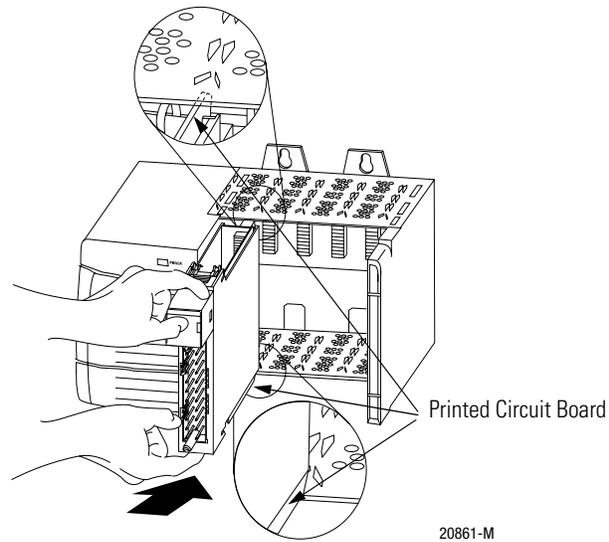
You can install or remove the module while chassis power is applied.

ATTENTION

The module is designed to support Removal and Insertion Under Power (RIUP). However, when you remove or insert an RTB with field-side power applied, **unintended machine motion or loss of process control can occur**. Exercise extreme caution when using this feature.

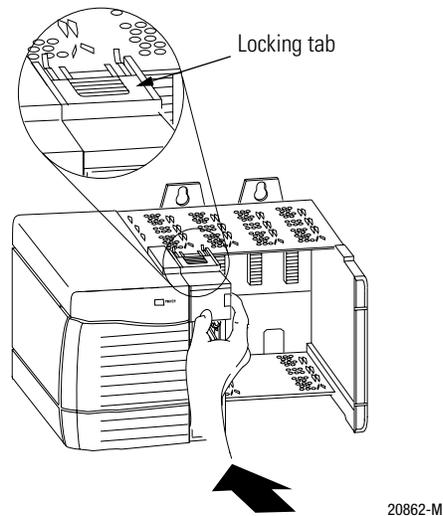
1. Align circuit board with top and bottom chassis guides as shown in Figure 9.1.

Figure 9.1



2. Slide module into chassis until module locking tab clicks.

Figure 9.2



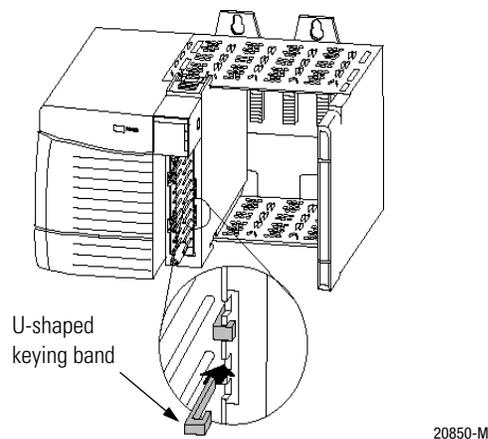
Keying the Removable Terminal Block

Key the RTB to prevent inadvertently connecting the incorrect RTB to your module. When the RTB mounts onto the module, keying positions will match up.

For example, if you place a U-shaped keying band in position #4 on the module, you cannot place a wedge-shaped tab in #4 on the RTB or your RTB will not mount on the module. We recommend that you use a unique keying pattern for each slot in the chassis.

1. Insert the U-shaped band with the long side near the terminals.
2. Push the band onto the module until it snaps into place.

Figure 9.3

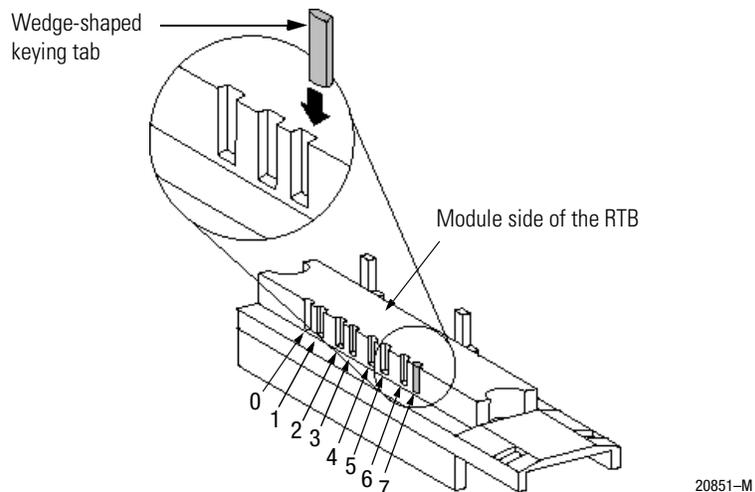


3. Key the RTB in positions that correspond to unkeyed module positions. Insert the wedge-shaped tab on the RTB with the rounded edge first. Push the tab onto the RTB until it stops.

IMPORTANT

When keying your RTB and module, you must begin with a wedge-shaped tab in position #6 or #7.

Figure 9.4



Connecting Wiring

You can use an RTB or a Bulletin 1492 prewired Interface Module (IFM)⁽¹⁾ to connect wiring to your module. If you are using an RTB, follow the directions below to connect wires to the RTB. An IFM has been prewired before you received it.

If you are using an IFM to connect wiring to the module, skip this section and go to page 9-8. To see a listing of the IFMs available for use with the ControlLogix analog I/O modules, see Appendix F, Using 1492 Wiring Systems with Your Analog I/O Module

IMPORTANT

For all ControlLogix analog modules, except the 1756-IR6I, we recommend you use Belden 8761 cable to wire the RTB. For the 1756-IR6I module, we recommend you use Belden 9533 or 83503 cable to wire the RTB. The RTB terminations can accommodate 22-14 gauge shielded wire.

This chapter shows how the general guidelines for wiring your analog I/O modules, including grounding the cable and connecting wiring to each RTB type. For more specific information on wiring individual catalog numbers, refer to Table 9.1.

Table 9.1 Wiring Diagrams

Catalog number:	Wiring diagram on:
1756-IF16	page 4-15
1756-IF8	page 4-19
1756-IF6CIS	page 5-14
1756-IF6I	page 5-17
1756-IR6I	page 6-19
1756-IT6I	page 6-20
1756-IT6I2	page 6-21
1756-OF4	page 7-9
1756-OF8	page 7-10
1756-OF6CI	page 8-9
1756-OF6VI	page 8-10

⁽¹⁾ The Bulletin 1492 IFM may not be used in any application that requires agency certification of the ControlLogix system. Use of the IFM violates the UL, CSA and FM certifications of this product.

Connect Grounded End of the Cable

Before wiring the RTB, you must connect ground wiring.

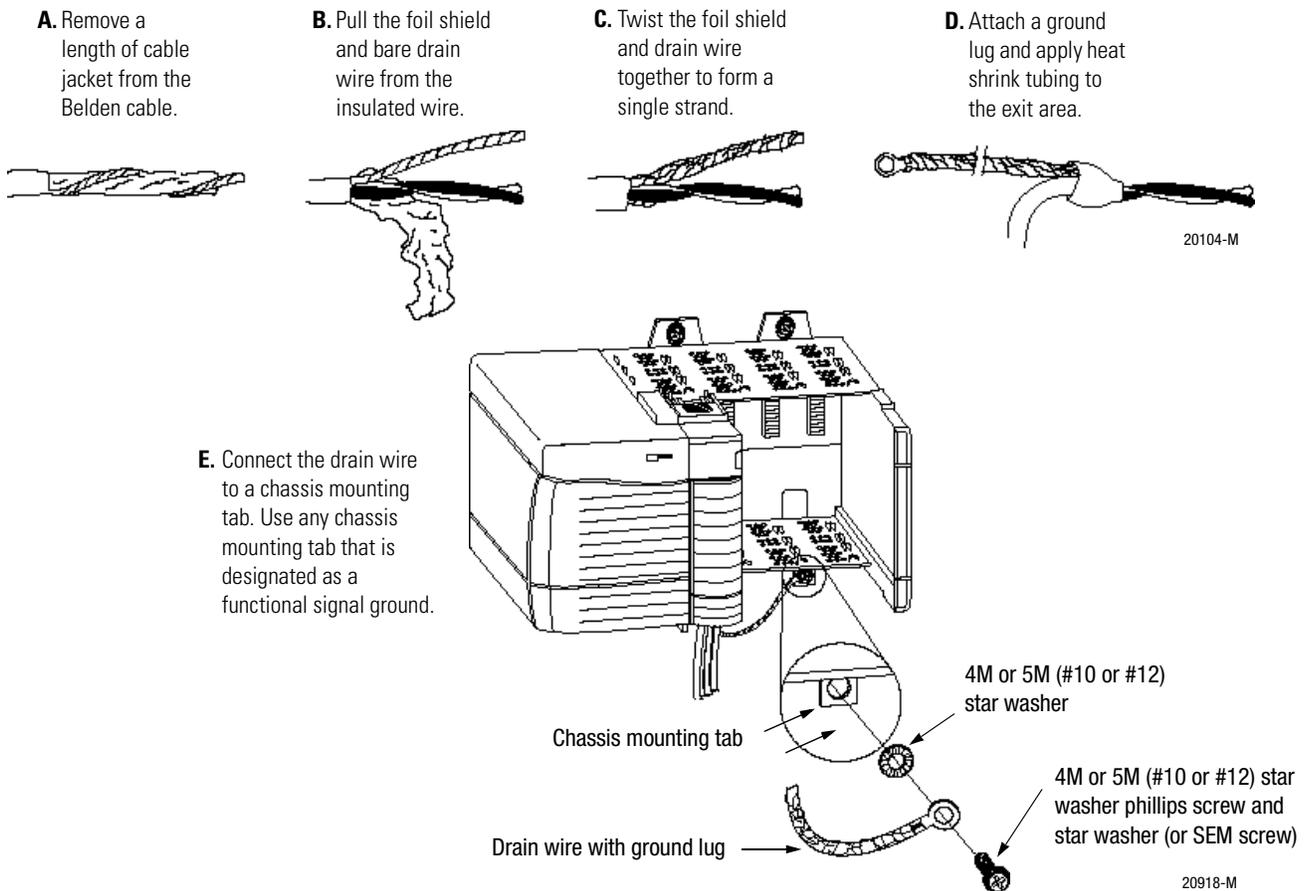
1. Ground the drain wire.

IMPORTANT

For all ControlLogix analog I/O modules except the 1756-IF6CIS module, we recommend you ground the drain wire at the field-side. If you cannot ground at the field-side, ground at an earth ground on the chassis as shown in Figure 9.5.

For the 1756-IF6CIS, we recommend you ground the module as shown in Figure 9.5.

Figure 9.5



2. Connect the insulated wires to the field-side.

Connect Ungrounded End of the Cable

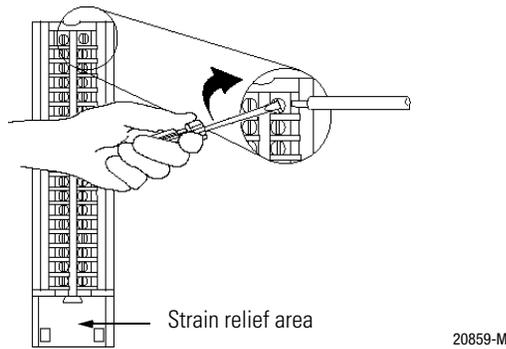
1. Cut the foil shield and drain wire back to the cable casing and apply shrink wrap.
2. Connect the insulated wires to the RTB, as shown below.

Three Types of RTBs (each RTB comes with housing)

- **Cage clamp** - Catalog number 1756-TBCH

1. Insert the wire into the terminal.
2. Turn the screw clockwise to close the terminal on the wire.

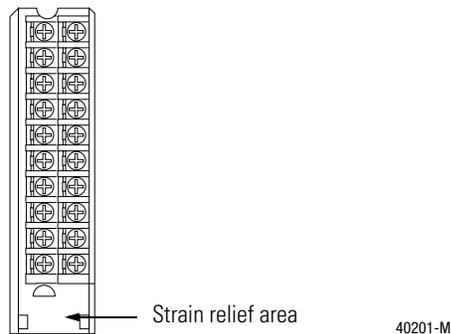
Figure 9.6



- **NEMA clamp** - Catalog number 1756-TBNH

Terminate wires at the screw terminals.

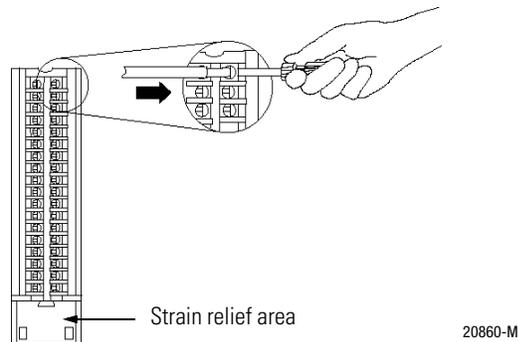
Figure 9.7



- **Spring clamp** - Catalog number 1756-TBSH or TBS6H

1. Insert the screwdriver into the outer hole of the RTB.
2. Insert the wire into the open terminal and remove the screwdriver.

Figure 9.8



Recommendations for Wiring Your RTB

We recommend you follow these guidelines when wiring your RTB:

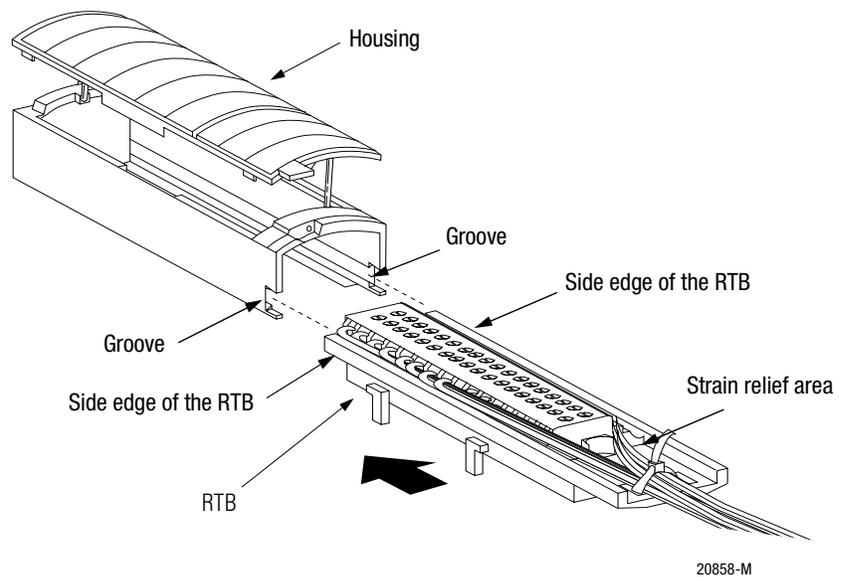
1. Begin wiring the RTB at the bottom terminals and move up.
2. Use a tie to secure the wires in the strain relief area of the RTB.
3. Order and use an extended-depth housing (Cat. No.1756-TBE) for applications that require heavy gauge wiring.

Assembling The Removable Terminal Block and the Housing

Removable housing covers the wired RTB to protect wiring connections when the RTB is seated on the module.

1. Align the grooves at the bottom of each side of the housing with the side edges of the RTB.
2. Slide the RTB into the housing until it snaps into place.

Figure 9.9



IMPORTANT

If additional wire routing space is required for your application, use extended-depth housing 1756-TBE.

Installing the Removable Terminal Block onto the Module

Install the RTB onto the module to connect wiring.

ATTENTION



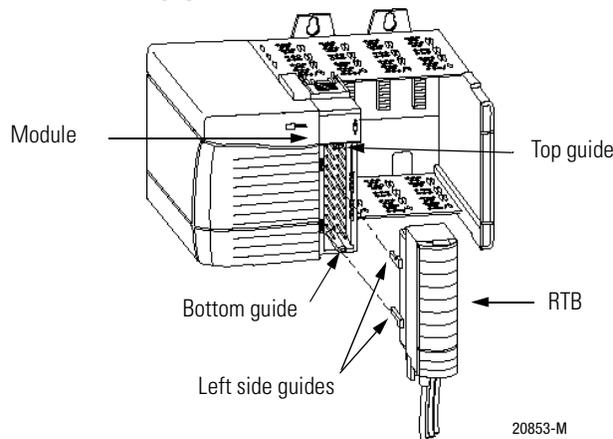
Shock hazard exists. If the RTB is installed onto the module while the field-side power is applied, the RTB will be electrically live. Do not touch the RTB's terminals. Failure to observe this caution may cause personal injury.

The RTB is designed to support Removal and Insertion Under Power (RIUP). However, when you remove or insert an RTB with field-side power applied, **unintended machine motion or loss of process control can occur.** Exercise extreme caution when using this feature. It is recommended that field-side power be removed before installing the RTB onto the module.

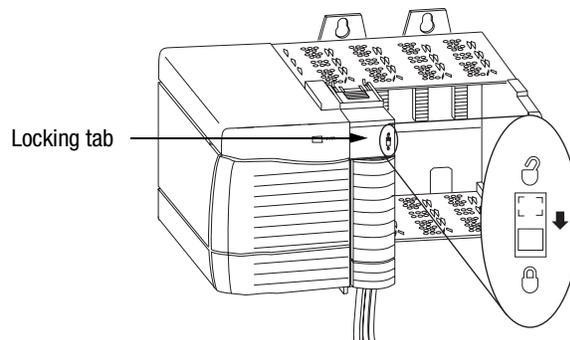
Before installing the RTB, make certain:

- field-side wiring of the RTB has been completed.
- the RTB housing is snapped into place on the RTB.
- the RTB housing door is closed.
- the locking tab at the top of the module is unlocked.

1. Align the top, bottom and left side guides of the RTB with matching guides on the module.



2. Press quickly and evenly to seat the RTB on the module until the latches snap into place.



3. Slide the locking tab down to lock the RTB onto the module.

Removing the Removable Terminal Block from the Module

If you need to remove the module from the chassis, you must first remove the RTB from the module.

ATTENTION



Shock hazard exists. If the RTB is removed from the module while the field-side power is applied, the module will be electrically live. Do not touch the RTB's terminals. Failure to observe this caution may cause personal injury.

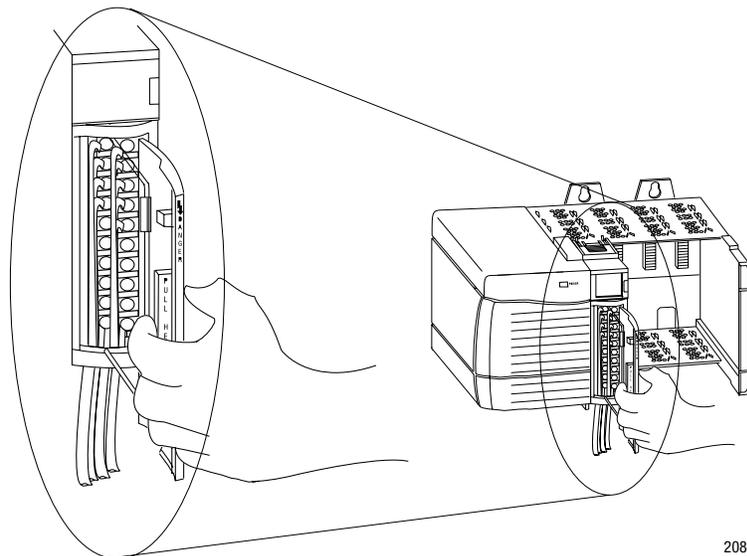
The RTB is designed to support Removal and Insertion Under Power (RIUP). However, when you remove or insert an RTB with field-side power applied, **unintended machine motion or loss of process control can occur.** Exercise extreme caution when using this feature. It is recommended that field-side power be removed before removing the module.

1. Unlock the locking tab at the top of the module.
2. Open the RTB door using the bottom tab.
3. Hold the spot marked PULL HERE and pull the RTB off the module.

IMPORTANT

Do not wrap your fingers around the entire door. A shock hazard exists.

Figure 9.10

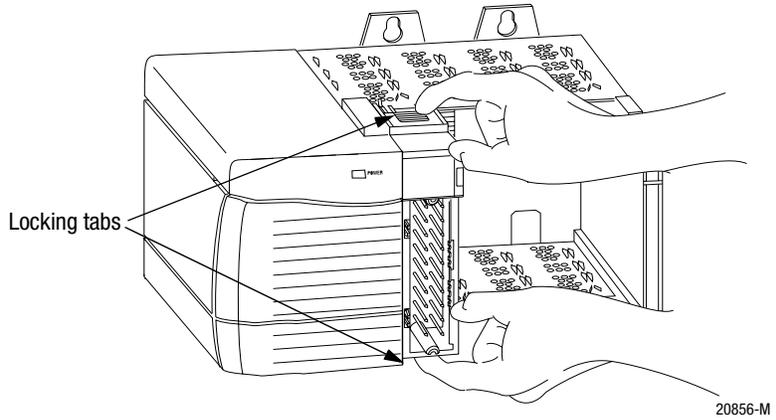


20855-M

Removing the Module from the Chassis

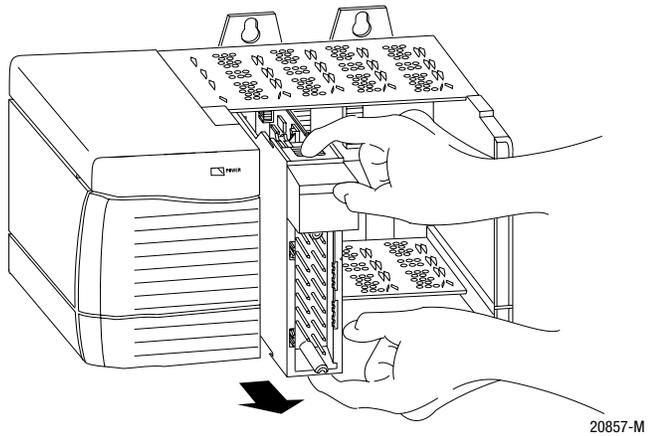
1. Push in the top and bottom locking tabs.

Figure 9.11



2. Pull module out of the chassis.

Figure 9.12



Chapter Summary and What's Next

In this chapter you read about Installing ControlLogix I/O Modules.

Chapter 10 describes Configuring ControlLogix Analog I/O Modules.

Configuring ControlLogix Analog I/O Modules

What This Chapter Contains This chapter describes how to configure ControlLogix analog I/O modules.

For information about:	See page:
Using RSLogix 5000 Online Help	10-1
Configuring Your I/O Module	10-2
Overview of the Configuration Process	10-2
Creating a New Module	10-4
Using the Default Configuration	10-8
Altering the Default Configuration for Input Modules	10-9
Altering the Default Configuration for Output Modules	10-11
Configuring the RTD Module	10-14
Configuring the Thermocouple Modules	10-15
Downloading New Configuration Data	10-16
Editing Configuration	10-17
Reconfiguring Module Parameters in Run Mode	10-18
Reconfiguring Parameters in Program Mode	10-19
Configuring I/O Modules in a Remote Chassis	10-20
Viewing and Changing Module Tags	10-22

Using RSLogix 5000 Online Help

This chapter describes how to configure your ControlLogix analog I/O modules but is limited to a relatively brief explanation of how to use the software. For more information on the full capabilities of the software, see the software's online help.

Configuring Your I/O Module

You must configure your module upon installation. The module will not work until it has been configured.

IMPORTANT

This chapter focuses on configuring I/O modules in a local chassis. To configure I/O modules in a remote chassis, you must follow all the detailed procedures with two additional steps. An explanation of the additional steps is listed at the end of this chapter.

RSLogix 5000 Configuration Software

Use RSLogix 5000 software to write configuration for your ControlLogix analog I/O module. You have the option of accepting the default configuration for your module or writing point level configuration specific to your application.

Both options are explained in detail, including views of software screens, in this chapter.

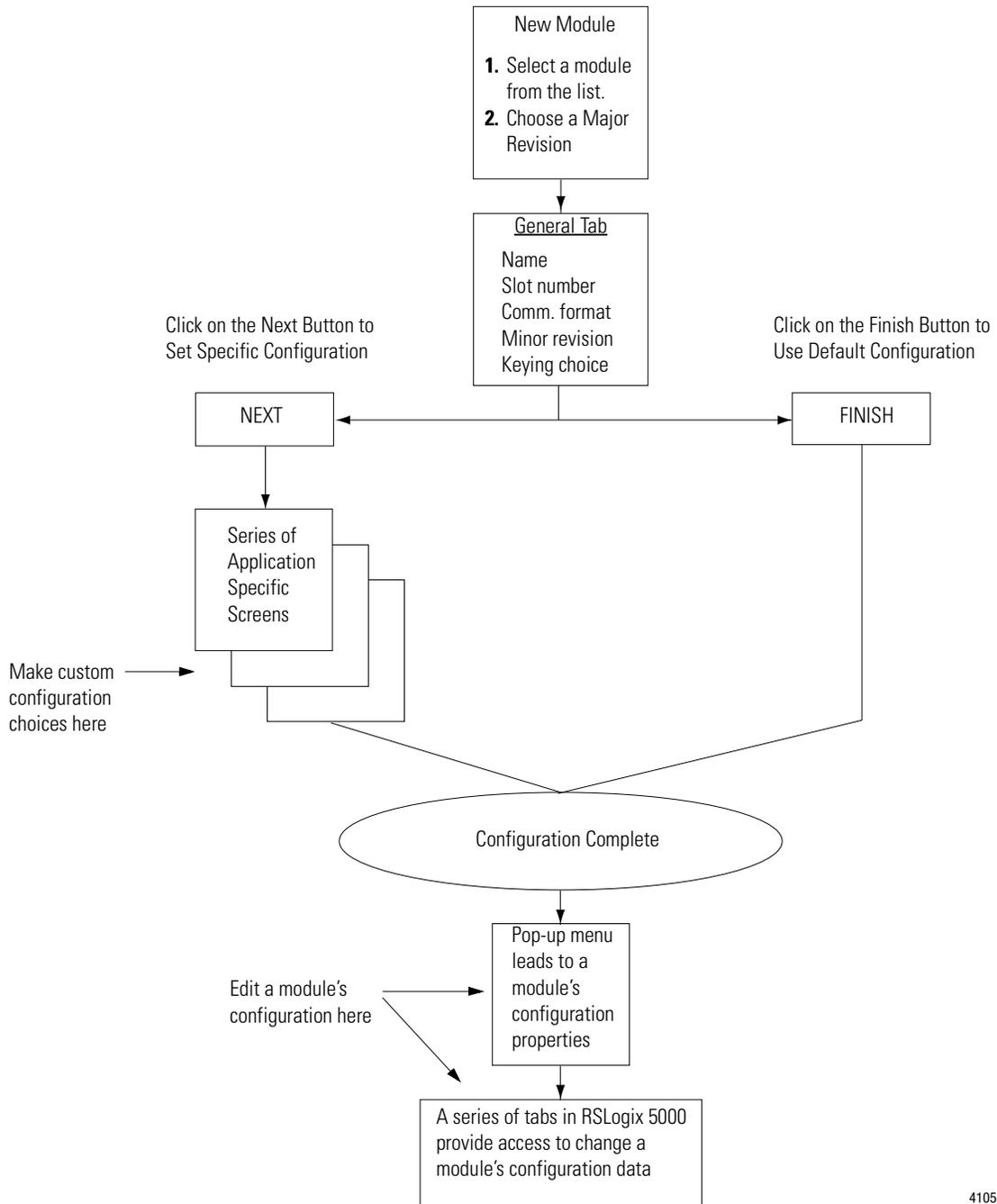
Overview of the Configuration Process

When you use the RSLogix 5000 software to configure a ControlLogix analog I/O module, you must perform the following steps:

1. Create a new module
2. Accept default configuration or write specific configuration for the module
3. Edit configuration for a module when changes are needed

Figure 10.1 shows an overview of the configuration process.

Figure 10.1



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Creating a New Module

After you have started RSLogix 5000 and created a processor, you must create a new module. The wizard allows you to create a new module and configure it.

IMPORTANT

You must be offline when you create a new module.

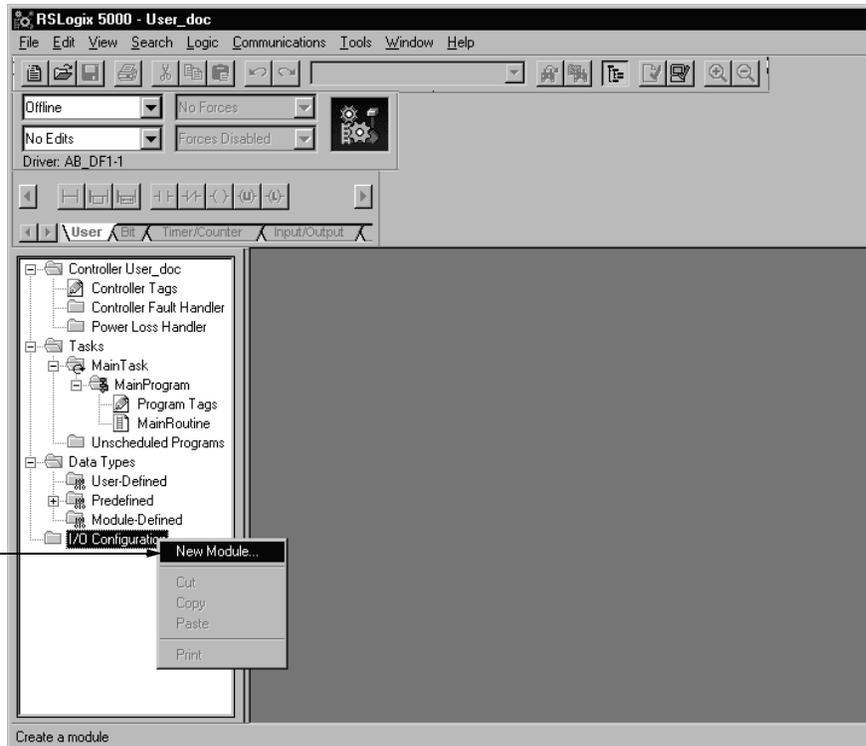
1. If your application is online, go offline.

If you are not offline, use this pull-down menu to go offline



2. Access the Select Module Type screen.

- A. Right-click on I/O Configuration.
- B. Select New Module.



3. Select the module type.

A. Select a module. (Arrow pointing to the selected module in the list)

B. Make sure the Major Revision number matches the label on the side of your module (Arrow pointing to the Major Revision field)

C. Select a module. (Arrow pointing to the OK button)

Type	Description
1756-IB32	32 Point 10V-31.2V DC Input
1756-IC16	16 Point 30V-60V DC Input
1756-IF16	16 Channel Non-Isolated Voltage/Current Analog Input
1756-IF6I	6 Channel Isolated Voltage/Current Analog Input
1756-IF8	8 Channel Non-Isolated Voltage/Current Analog Input
1756-IH16I	16 Point 90V-146V DC Isolated input, Sink/Source
1756-IM16I	16 Point 159V-265V AC Isolated Input
1756-IN16	16 Point 10V-30V AC Input
1756-IR6I	6 Channel Isolated RTD Analog Input
1756-IT6I	6 Channel Isolated Thermocouple Analog Input
1756-L1	ControlLogix5550 Programmable Controller
1756-MO2AE	2 Axis Analog/Encoder Servo

4. Begin configuration on the naming screen.

A. Name the module (optional). (Arrow pointing to the Name field)

B. Type a description (optional). (Arrow pointing to the Description field)

C. Choose a Communications Format (A detailed explanation of this field is provided on page 10-6.) (Arrow pointing to the Comm Format dropdown)

D. Make sure the Minor Revision number matches the label on the side of your module. (Arrow pointing to the Minor Revision field)

E. Select the slot your module resides in. (Arrow pointing to the Slot dropdown)

F. Choose an Electronic Keying method. (A detailed explanation of this field is provided on the next page 3-4.) (Arrow pointing to the Electronic Keying dropdown)

If you are altering the default configuration, click here. (Arrow pointing to the Next > button)

If you are using default configuration, click here and you are finished configuring your module. (Arrow pointing to the Finish >> button)

Go to page 10-9 (Arrow pointing to the Next > button)

Go to page 10-8 (Arrow pointing to the Finish >> button)

Communications Format

The communications format determines:

- what type of configuration options are made available
- what type of data is transferred between the module and its owner-controller
- what tags are generated when configuration is complete
- what type of connection is made between the controller writing the configuration and the module itself.

IMPORTANT

In addition to description below, each format returns status data and rolling timestamp data.

Also, once the module is created, the communications format cannot be changed. The module must be deleted and recreated.

Input Module Formats

Table 10.1 lists the Communications Format available with ControlLogix analog input modules:

Table 10.1

If you want the input module return this data:	Choose this Communications Format:
Floating point input data	Float data
Integer input data	Integer data
Floating point input data with the value of the coordinated system time (from its local chassis) when the input data is sampled	CST timestamped float data
Integer input data with the value of the coordinated system time (from its local chassis) when the input data is sampled	CST timestamped integer data
Floating point input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the differential mode	CST timestamped float data - differential mode
Floating point input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the high speed mode	CST timestamped float data - high speed mode
Floating point input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the single-ended mode	CST timestamped float data - single-ended mode
Integer input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the differential mode	CST timestamped integer data - differential mode
Integer input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the high speed mode	CST timestamped integer data - high speed mode
Integer input data with the value of the coordinated system time (from its local chassis) when the input data is sampled when the 1756-IF16 or 1756-IF8 module is operating in the single-ended mode	CST timestamped integer data - single-ended mode

Table 10.1

If you want the input module return this data:	Choose this Communications Format:
Floating point input data when the 1756-IF16 or 1756-IF8 module is operating in the differential mode only	Float data - differential mode
Returns floating point input data when the 1756-IF16 or 1756-IF8 module is operating in the high speed mode	Float data - high speed mode
Floating point input data when the 1756-IF16 or 1756-IF8 module is operating in the single-ended mode	Float data - single-ended mode
Integer input data when the 1756-IF16 or 1756-IF8 module is operating in the differential mode	Integer data - differential mode
Integer input data when the 1756-IF16 or 1756-IF8 module is operating in the high speed mode	Integer data - high speed mode
Integer input data when the 1756-IF16 or 1756-IF8 module is operating in the single-ended mode	Integer data - single-ended mode
<p>Specific input data that is used by a controller that does not own the input module. These choices have the same definition as the similarly-named options above except that they represent listen-only connections between the analog input module and a listen-only controller.</p>	Listen only CST timestamped float data
	Listen only CST timestamped integer data
	Listen only float data
	Listen only integer data
	Listen only CST timestamped float data - differential mode
	Listen only CST timestamped float data - high speed mode
	Listen only CST timestamped float data - single-ended mode
	Listen only CST timestamped integer data - differential mode
	Listen only CST timestamped integer data - high speed mode
	Listen only CST timestamped integer data - single-ended mode
	Listen only Float data - differential mode
	Listen only Float data - high speed mode
	Listen only Float data - single-ended mode
	Listen only Integer data - differential mode
Listen only Integer data - high speed mode	
Listen only Integer data - single-ended mode	

Output Module Formats

Table 10.2 lists the Communications Format available with ControlLogix analog input modules:

Table 10.2

If you want the output module return this data:	Choose this Communications Format:
Floating point output data	Float data
Integer output data	Integer data
Floating point output data and receives data echo values with a CST timestamp value	CST timestamped float data
Integer output data and receives data echo values with a CST timestamp value	CST timestamped integer data
Specific input data that is used by a controller that does not own the output module. These choices have the same definition as the similarly-named options above except that they represent listen-only connections between the analog output module and a listen-only controller.	Listen only float data
	Listen only integer data
	Listen only CST timestamped float data
	Listen only CST timestamped integer data

Electronic Keying

Electronic keying allows the ControlLogix system to control what modules belong in the various slots of a configured system.

During module configuration, you must choose one of the following keying options for your I/O module:

- Exact Match
- Compatible Match
- Disable Keying

For more information on electronic keying, see page 3-4.

Using the Default Configuration

If you use the default configuration and click on Finish, you are done.

Altering the Default Configuration for Input Modules

If you write specific configuration and click on Next, you see the series of wizard screens that enable you to configure the module. This example shows the process for input modules. To see an example for output modules, see page 10-14.

Although each screen maintains importance during online monitoring, some of the screens that appear during this initial module configuration process are blank. They are not shown here. To see these screens in use, see Appendix A.

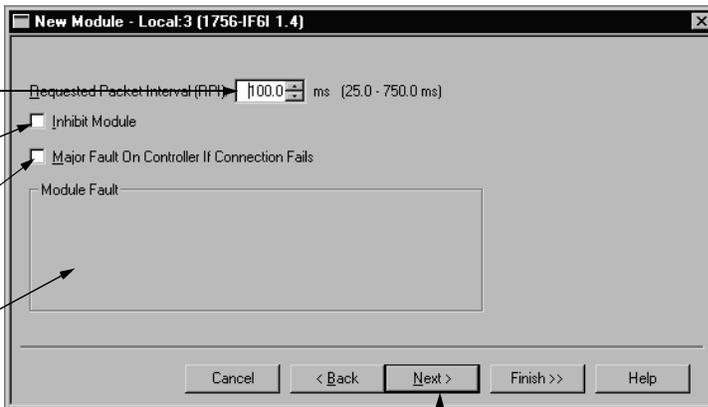
After the naming page, this series of screens appears.

Adjust the Requested Packet Interval here

Inhibit the connection to the module here

If you want a Major Fault on the Controller to occur if there is connection failure with the I/O module while in Run Mode, click here

This Fault box is empty when you are offline. If a fault occurs while the module is online, the type of fault will be displayed here. The fault is a connection fault explaining why a connection did not open.



Click here to move to the next page

The configuration page appears next. For example, this screen appears for the 1756-IF6I module. The choices available on the configuration screen vary according to the module selected.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page

Choose the channel to be configured here

Set the Scaling parameters here

Set the Input Range here

Set a Calibration Bias here

Set the Notch Filter here

Set the Digital Filter here

Set the Real Time Sampling period here

Click here to move to the next page

Click here to accept the parameters you have configured for your module

The screenshot shows a configuration window with the following fields: Channel (0-5), Input Range (-10 V to 10 V), Calibration Bias (0.0), Notch Filter (60 Hz), Digital Filter (0 ms), Low Signal (-10.0 V) = Low Engineering (-10.0), High Signal (10.0 V) = High Engineering (10.0), and RTS (100 ms). Buttons include Cancel, < Back, Next >, Finish >>, and Help.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page

Choose the channel to be configured here

Set the Process Alarm trigger points here

Unlatch Process Alarms here. These buttons are only enabled when the module is online.

Disable or Latch Process and Rate Alarms here

IMPORTANT: When you disable all alarms, you disable process, rate and channel diagnostics alarms (e.g. underrange and overrange).

Set the Process Alarms Deadband here

Set the Rate Alarm here

Moving slide controls will change process alarm trigger points. Hold the shift key down while sliding the control for whole number value selection.

Click here to move to the next page

Click here to accept the parameters you have configured for your module

The screenshot shows a configuration window with the following fields: Channel (0-5), Process Alarms (High High: 10.0, High: 10.0, Low: -10.0, Low Low: -10.0), Unlatch All button, HI/HH and LL/LL indicators, Disable All Alarms, Latch Process Alarms, Latch Rate Alarm, Deadband (0.0), Rate Alarm (0.0), and Unlatch button. Buttons include Cancel, Back, Next >, Finish >>, and Help.

Altering the Default Configuration for Output Modules

If you write specific configuration and click on Next, you see the series of wizard screens that enable you to configure the module. This example shows the process for output modules.

Although each screen maintains importance during online monitoring, some of the screens that appear during this initial module configuration process are blank. They are not shown here. To see these screens in use, see Appendix A.

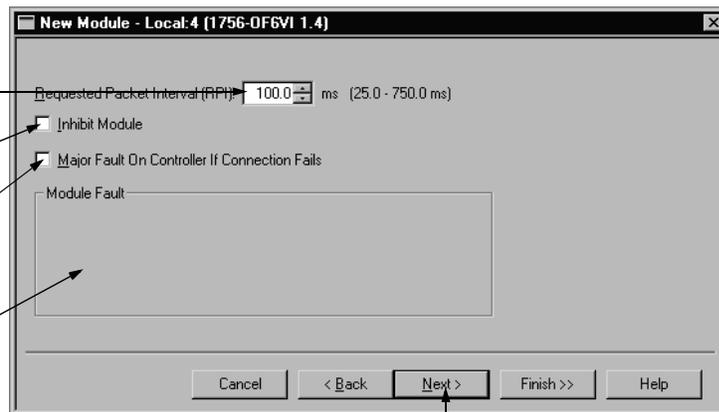
After the naming page, this series of screens appears.

Adjust the Requested Packet Interval here

Inhibit the connection to the module here

If you want a Major Fault on the Controller to occur if there is connection failure with the I/O module while in Run Mode, click here

This Fault box is empty when you are offline. If a fault occurs while the module is online, the type of fault will be displayed here. The fault is a connection fault explaining why a connection did not open.



Click here to move to the next page

The configuration page appears next. For example, this screen appears for the 1756-OF6VI module. The choices available on the configuration screen vary according to the module selected.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page

Choose the channel to be configured here

Set the Scaling parameters here

Set Calibration Bias here

Enable Hold for Initialization here

Click here to move to the next page

Click here to accept the parameters you have configured for your module

The screenshot shows a configuration window titled "New Module - Local: 4 (1756-OF6VI 1.4)". At the top, there is a "Channel" section with a row of buttons labeled 0 through 5. Below this is a "Scaling" section with four input fields: "Low Signal" (set to -10.0 V), "Low Engineering" (set to -10.0), "High Signal" (set to 10.0 V), and "High Engineering" (set to 10.0). To the right of the scaling section is a "Calibration Bias" field set to 0.0 and a checkbox labeled "Hold for Initialization". At the bottom of the window are five buttons: "Cancel", "< Back", "Next >", "Finish >>", and "Help".

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page

Choose the channel to be configured here

Set the behavior of the outputs in Program Mode here

Set the behavior of the outputs if communications fail in Program Mode here

Set the behavior of the outputs in Fault Mode here

IMPORTANT: Outputs always go to Fault mode if communications fail in Run mode

Click here to move to the next page

Click here to accept the parameters you have configured for your module

The screenshot shows the same configuration window as above, but with different settings. The "Channel" button 0 is selected. The "Ramp Rate" is set to 0.00 (per Sec). The "Output State in Program Mode" section has "Hold Last State" selected. The "Output State in Fault Mode" section also has "Hold Last State" selected. The "Communications Failure" section has "Leave outputs in Program Mode state" selected. The "Next >" button is highlighted.

These screens appear next.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page

Choose the channel to be configured here

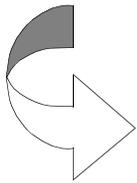
Set Clamp Limits here

Select Ramp in Run here

Set Ramp Rate here

Disable or latch limit Ramp and Rate Alarms here

Unlatch Process Alarms here. These buttons are only enabled when the module is online.



Moving slide controls changes the Clamp Limit trigger points. Hold the shift key down while sliding the control for easier value selection.

Click here to move to the next page

Click here to accept the parameters you have configured for your module

IMPORTANT: The last two screens only appear if you click on Next after setting the process alarms above

This screen appears next in the wizard series of screens. It is used during calibration but not initial configuration

Channel	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	-10 to 10 V			
1	-10 to 10 V			
2	-10 to 10 V			
3	-10 to 10 V			
4	-10 to 10 V			
5	-10 to 10 V			

Click here to accept the parameters you have configured for your module

Configuring the RTD Module

The RTD module (1756-IR6I) has additional configurable points, temperature units and 10Ω copper offset options.

All of this module's configuration screens match the series listed for input modules beginning on page 10-9 except for the third screen. The screen below shows the aforementioned screen for the 1756-IR6I module.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page All configurable options are the same except for the addition of those features that account for the module's temperature measuring capability. They are shown below.

The screenshot shows the configuration window for a 1756-IR6I RTD module. The window title is "New Module - Local:4 (1756-IR6I 1.1)". It features a "Channel" section with tabs for 0 through 5. The "Scaling" section includes "Low Signal" (1.0 °C) and "Low Engineering" (1.0), and "High Signal" (487.0 °C) and "High Engineering" (487.0). The "Input Range" is set to "1 Ohms to 487 Ohms". The "Sensor Type" is set to "10 Ohm Cu 427". The "Calibration Bias" is 0.0, the "Notch Filter" is 60 Hz, and the "Digital Filter" is 0 ms. The "10 Ohm Copper Offset" is 0.0 (Ohms). The "RTS" is 100 ms. The "Temperature Units" are set to Celsius. Annotations with arrows point to the "Sensor Type" dropdown, the "10 Ohm Copper Offset" field, and the "Temperature Units" radio buttons.

Annotations:

- Set the Temperature units for the module here
- Select RTD Sensor Type here
- Select 10 Ohm Copper Offset here
- This feature only needs to be set if you choose a Copper Sensor Type

Configuring the Thermocouple Modules

The 1756-IT6I and 1756-IT6I2 modules have additional configurable points, temperature units and cold junction options.

All of this module's configuration screens match the series listed for input modules beginning on page 10-9 except for the third screen. The screen below shows the aforementioned screen for the 1756-IT6I module.

IMPORTANT: Set all the configuration parameters for each channel on this page before moving to the next page. All configurable options are the same except for the addition of those features that account for the module's temperature measuring capability. They are shown below.

Annotations for the screenshot:

- Set the Temperature units for the module here (points to Celsius/Fahrenheit radio buttons)
- Select Thermocouple Sensor Type here (points to TC Type B dropdown)
- Set Cold Junction options here (points to Cold Junction Offset field)

IMPORTANT

The module sends back temperature values over the entire sensor range as long as the High signal value equals the High engineering value and the Low signal value equals the Low engineering value.

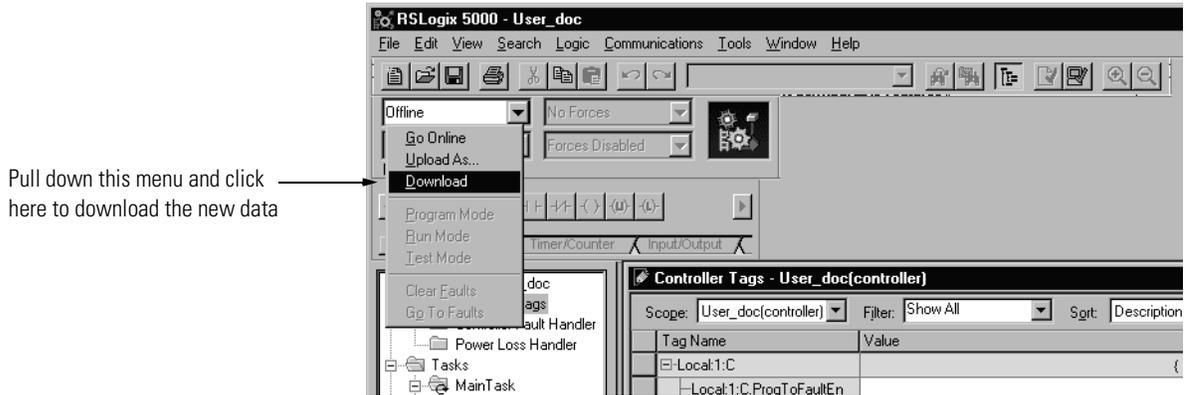
For the example above, if:

High Signal = 78.0°C, High Engineering must = 78.0.

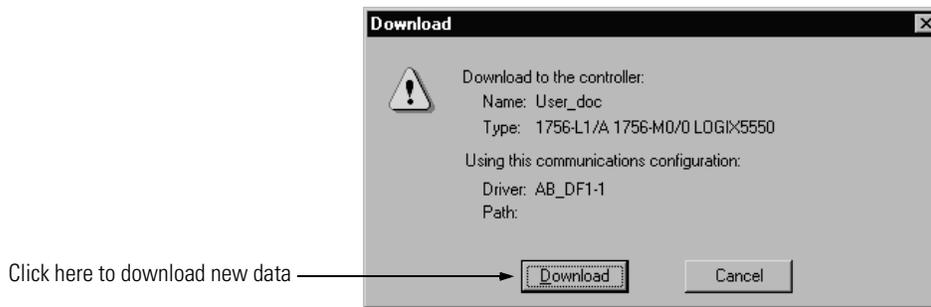
Low signal = -12.0°C, Low Engineering must = -12.0

Downloading New Configuration Data

After you have changed the configuration data for a module, the change does not actually take effect until you download the new program which contains that information. This downloads the entire program to the controller overwriting any existing programs.



RSLogix 5000 verifies the download process with this pop-up screen.



This completes the download process.

Editing Configuration

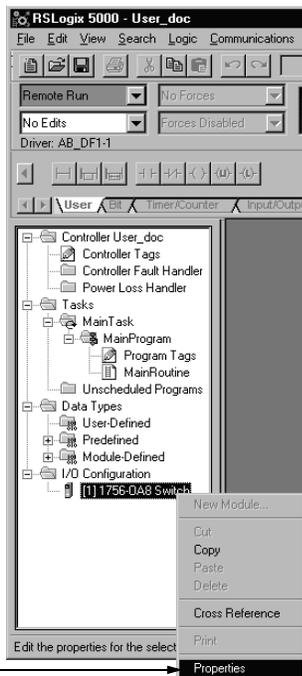
After you set configuration for a module, you can review and change it. You can change configuration data and download it to the controller while online. This is called **dynamic reconfiguration**.

Your freedom to change some configurable features, though, depends on whether the controller is in Remote Run Mode or Program Mode.

IMPORTANT

Although you can change configuration while online, you must go offline to add or delete modules from the program in current RSLogix 5000 revisions.

The editing process begins on the main page of RSLogix 5000.

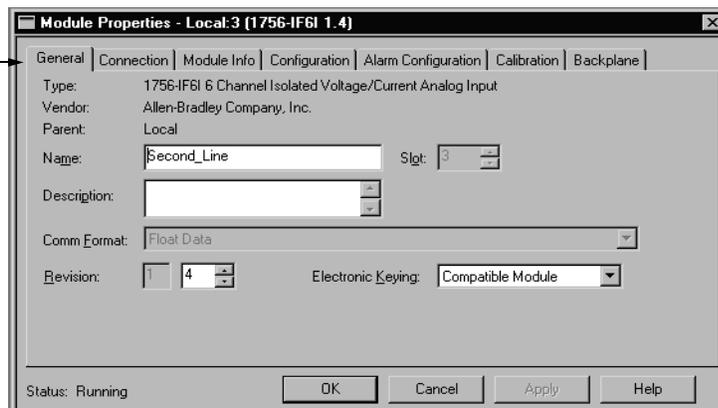


A. Right-click on the module.

B. Select Properties.

You see this screen.

Click on the tab of the page you want to view or reconfigure



Reconfiguring Module Parameters in Run Mode

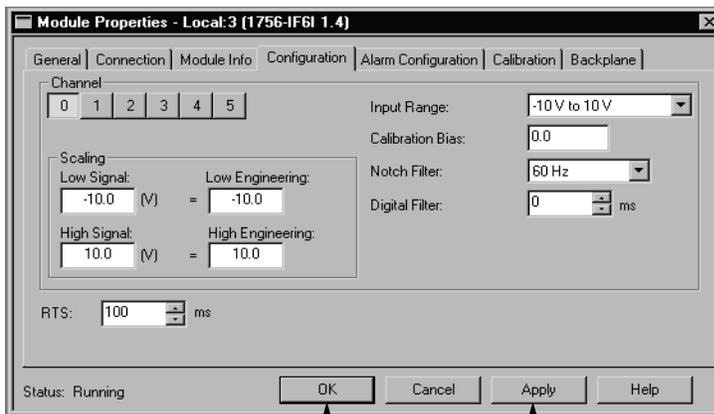
Your module can operate in Remote Run Mode or Hard Run Mode. You can only change any configurable features that are enabled by the software in Remote Run Mode.

If any feature is disabled in either Run Mode, change the controller to Program Mode and make the necessary changes.

For example, the following screen shows the configuration page for the 1756-IF6I module while it is in Run Mode.

A. Make the necessary configuration changes

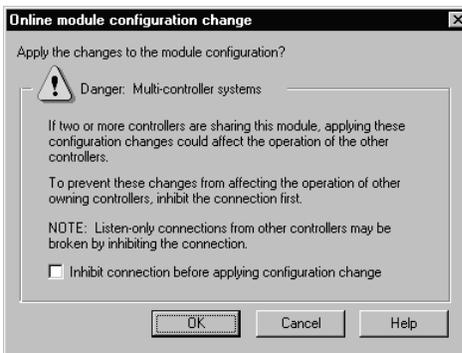
In this example, all configurable features are enabled in Run Mode.



B. Click here to transfer the new data and close the screen.

Click here to transfer the new data and keep the screen open.

When you try to download new configuration data to the module, the following warning appears.



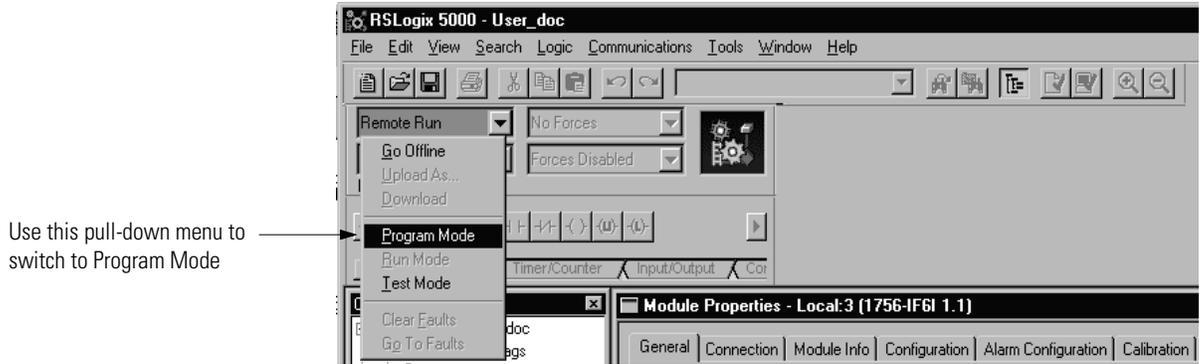
IMPORTANT

If you change the configuration for a module, you must consider whether the module has more than one owner-controller. If so, be sure each owner has exactly the same configuration data as the others.

For more information on changing configuration in a module with multiple owner-controllers, see page 2-13.

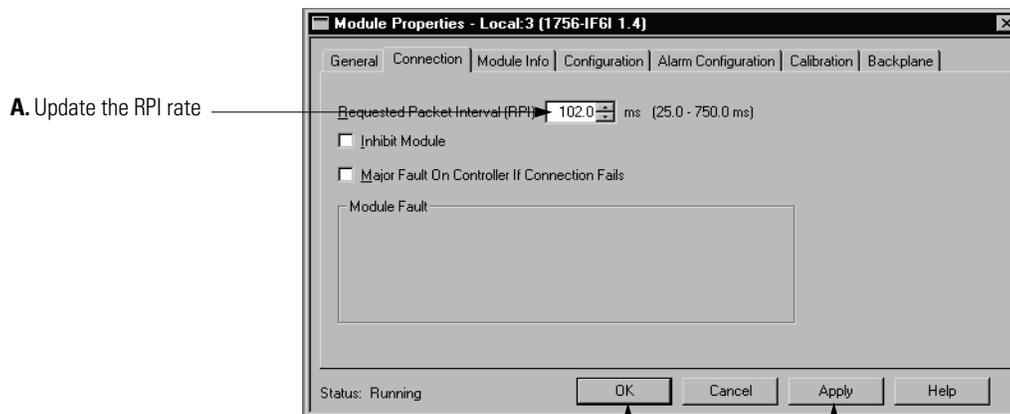
Reconfiguring Parameters in Program Mode

Change the module from Run Mode to Program Mode before changing configuration in the Program Mode.



Use this pull-down menu to switch to Program Mode

Make any necessary changes. For example, the RPI can only be changed in Program Mode.

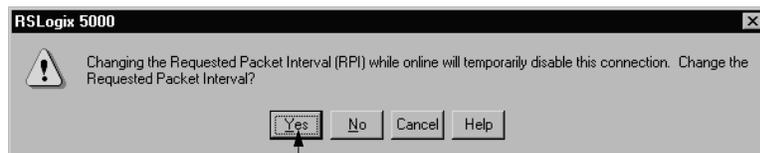


A. Update the RPI rate

B. Click here to transfer the new data and close the screen.

Click here to transfer the new data and keep the screen open.

Before the RPI rate is updated online, RSLogix 5000 verifies your desired change.



Click here to change the RPI

The RPI has been changed and the new configuration data has been transferred to the controller.

After you change your module's configuration in Program Mode, we recommend that you change the module back to Run Mode.

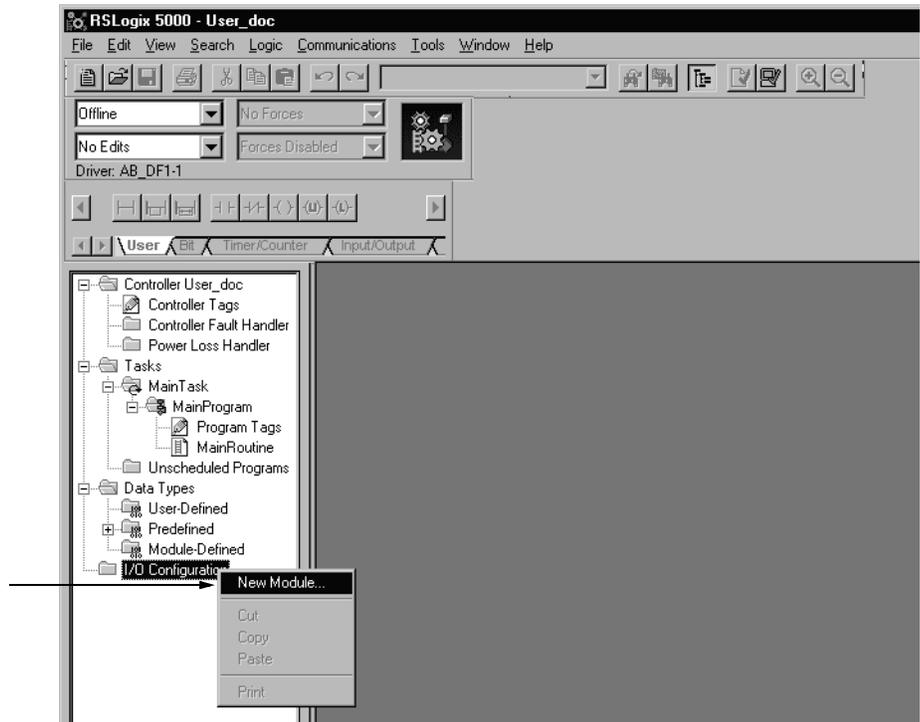
Configuring I/O Modules in a Remote Chassis

ControlLogix ControlNet Interface modules (1756-CNB or 1756-CNBR) or EtherNet/IP Bridge module (1756-ENBT) are required to communicate with I/O modules in a remote chassis.

You must configure the communications module in the local chassis and the remote chassis before adding new I/O modules to the program.

1. Configure a communications module for the local chassis. This module handles communications between the controller chassis and the remote chassis.

- A. Right-click on I/O Configuration.
- B. Select New Module.



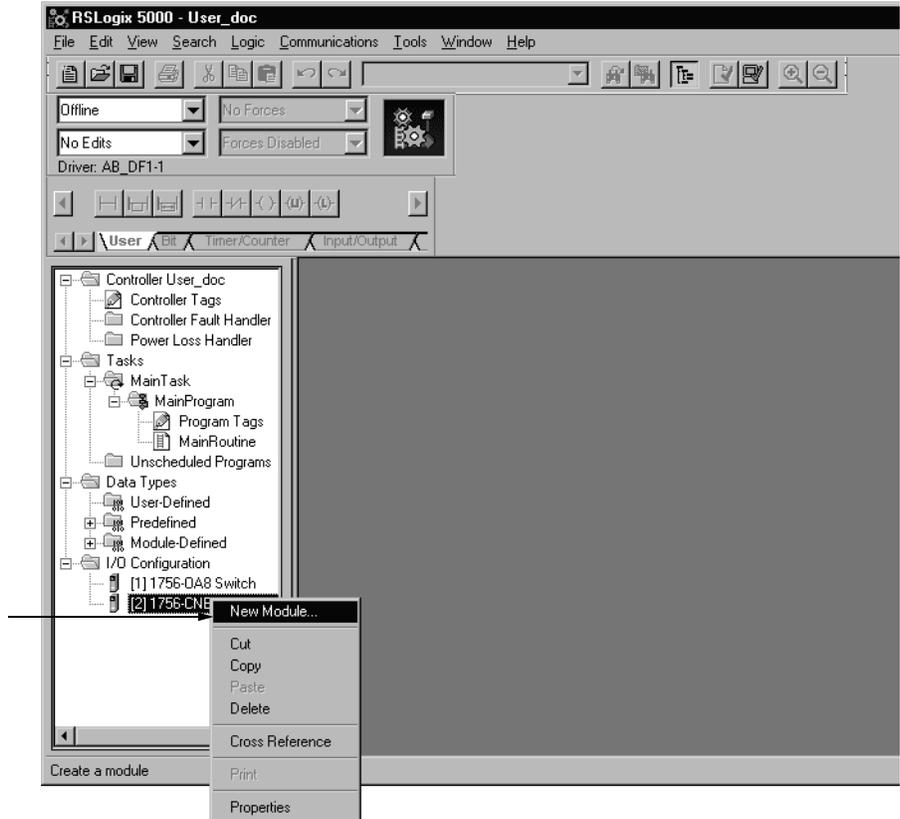
2. Choose a communications module and configure it.

For more information on the ControlLogix ControlNet Interface modules, see the ControlLogix ControlNet Interface user manual, publication 1756-6.5.3.

For more information on the ControlLogix EtherNet/IP Bridge module, see the ControlLogix EtherNet/IP Bridge module user manual, publication 1756-UM050.

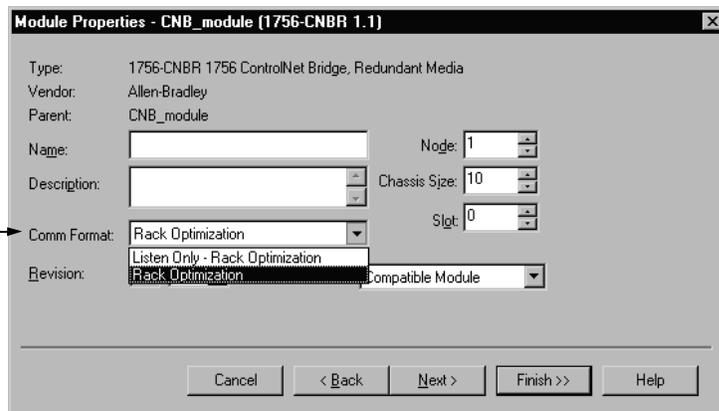
3. Configure a communications module for the remote chassis.

- A. Right-click on the local communications module.
- B. Select New Module.



4. Choose a communications module and configure it.

IMPORTANT: Be aware of the two Communications Format choices available for 1756-CNBR modules. For more information on the differences between Rack Optimization and Listen-Only Rack Optimization, see chapter 2 of the ControlLogix Digital I/O Modules User Manual, publication 1756-UM058.

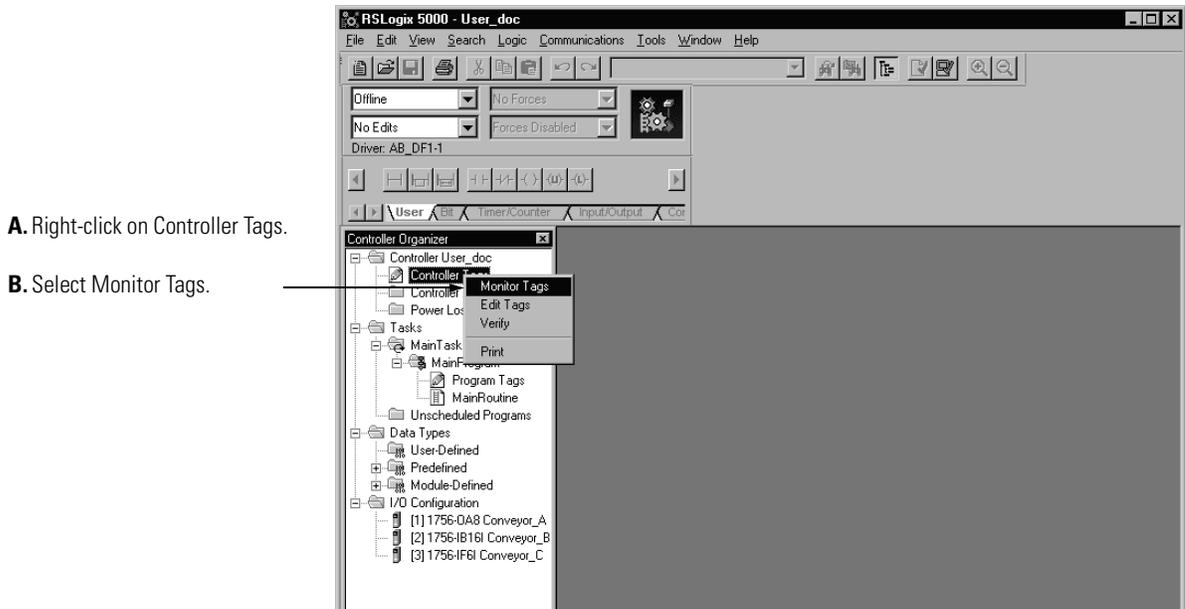


Now you can configure the remote I/O modules by adding them to the remote communications module. Follow the same procedures as you do for configuring local I/O modules as detailed earlier in this chapter.

Viewing and Changing Module Tags

When you create a module, you establish a series of tags in the ControlLogix system that can be viewed in the Tag Editor of RSLogix 5000. Each configurable feature on your module has a distinct tag that can be used in the processor's ladder logic.

You can access a module's tags through RSLogix 5000 as shown below.



You can view the tags from here.



Because the process of viewing and changing a module's configuration tags is broader in scope than can be addressed in this chapter.

For more information and sample tag collections, see Appendix B, Tag Definitions.

Chapter Summary and What's Next

In this chapter, you read about Configuring ControlLogix Analog I/O Modules.

Chapter 11 explains Calibrating the ControlLogix Analog I/O Modules.

Notes:

Calibrating the ControlLogix Analog I/O Modules

What This Chapter Contains This chapter describes how to calibrate ControlLogix analog modules.

For information about:	See page:
Difference Between Calibrating An Input Module and Calibrating An Output Module	11-2
Calibrating Input Modules	11-4
Calibrating Output Modules	11-22

Your ControlLogix analog I/O module comes from the factory with a default calibration. You may choose to recalibrate your module to increase its accuracy for your specific application.

You do not have to configure a module before you calibrate it. If you decide to calibrate your analog I/O modules first, you must add them to your program. To see how to add a new module to your program, see page 10-4.

IMPORTANT

Analog I/O modules can be calibrated on a channel by channel basis or with the channels grouped together. Regardless of which option you choose, we recommend you calibrate all channels on your module each time you calibrate. This will help you maintain consistent calibration readings and improve module accuracy.

Calibration is meant to correct any hardware inaccuracies that may be present on a particular channel. The calibration procedure compares a known standard, either input signal or recorded output, with the channel's performance and then calculating a linear correction factor between the measured and the ideal.

The linear calibration correction factor is applied on every input or output same to obtain maximum accuracy.

Difference Between Calibrating An Input Module and Calibrating An Output Module

Although the purpose of calibrating analog modules is the same for input and output modules, to improve the module's accuracy and repeatability, the procedures involved differs for each.

- When you calibrate input modules, you use current, voltage or ohms calibrators to send a signal to the module to calibrate it.
- When you calibrate output modules, you use a digital multimeter (DMM) to measure the signal the module is sending out.

To maintain your module's accuracy specifications, we recommend you use calibration instruments with specific ranges. Table 11.1 lists the recommended instruments for each module.

Table 11.1 Recommended Calibration Instruments for 1756 Analog I/O Modules

Modules:	Recommended instrument ranges:
1756-IF16 & 1756-IF8	0 to 10.25V source +/-150 μ V Voltage
1756-IF6CIS	1.00 to 20.00mA source +/-0.15 μ A Current
1756-IF6I	0 to 10.00V source +/-150 μ V Voltage 1.00 to 20.00mA source +/-0.15 μ A Current
1756-IR6I	1.0 and 487.0 Ω resistors ⁽¹⁾ +/-0.01%
1756-IT6I & 1756-IT6I2	-12mV to 78mV source +/-0.3 μ V
1756-OF4 1756-OF8	DMM better than 0.3mV or 0.6 μ A
1756-OF6VI	DMM with resolution better than 0.5mV
1756-OF6CI	DMM with resolution better than 1.0 μ A

⁽¹⁾ We suggest you use the following precision resistors:
KRL Electronics - 534A1-1R0T 1.0 Ohm 0.01% / 534A1-487R0T 487 Ohm 0.01%

A precision decade resistor box can also be used that meets or exceeds the required accuracy specifications. The user is responsible for assuring that the decade box maintains accuracy by periodic calibration as specified by the following vendors:

Electro Scientific Industries, Portland, OR – Series DB 42

IET Labs, Westbury, NY – HARS-X Series

Julie Research Labs, New York, NY – DR100 Series

IMPORTANT

If you calibrate your module with an instrument that is less accurate than those recommended in Table 11.1 (e.g. calibrate a 1756-IF16 module with a voltage calibrator of greater than $\pm 150\mu\text{V}$ accuracy), the following may occur:

- Calibration appears to occur normally but the module gives inaccurate data during operation.
- or
- A calibration fault occurs, forcing you to abort calibration.
 - The calibration fault bits are set for the channel you attempted to calibrate. The bits remain set until a valid calibration is completed.

In this case, you must recalibrate the module with an instrument as accurate as recommended in Table 11.1.

Calibrating in Either Program or Run Mode

You must be online to calibrate your analog I/O modules through RSLogix 5000. When you are online, you can choose either Program or Run Mode as the state of your program during calibration.

We recommend that your module be in Program Mode and not be actively controlling a process when you calibrate it.

IMPORTANT

The module freezes the state of each channel and does not update the controller with new data until after calibration ends. This could be hazardous if active control were attempted during calibration.

Calibrating Input Modules

Input calibration is a multi-step process that involves multiple services being sent to the module. This section has four parts. Each input module requires attention be paid to specific calibration ranges.

Table 11.2 lists the catalog numbers covered in this section:

Table 11.2

For information about:	See page:
Calibrating the 1756-IF16 or 1756-IF8 Modules	11-4
Calibrating the 1756-IF6CIS or 1756-IF6I Modules	11-9
Calibrating the 1756-IR6I	11-14
Calibrating the 1756-IT6I or 1756-IT6I2	11-18

Calibrating the 1756-IF16 or 1756-IF8 Modules

The 1756-IF16 or 1756-IF8 modules are used in applications requiring voltage or current. The modules offer 4 input ranges:

- -10 to 10V
- 0 to 5V
- 0 to 10V
- 0 to 20mA

However, you can only calibrate the modules using a voltage signal.

IMPORTANT

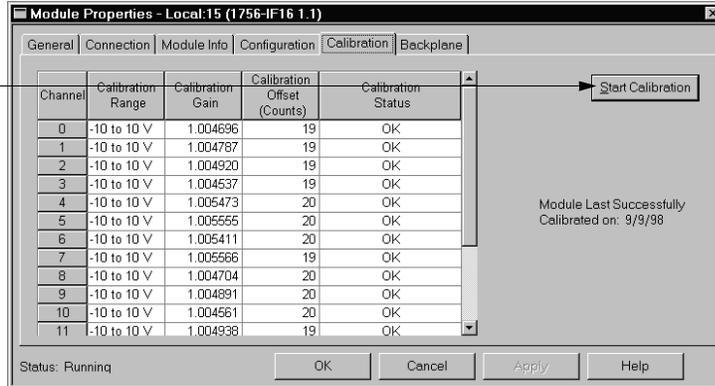
Regardless of what application range is selected prior to calibration, all calibration uses a +/-10V range.

While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

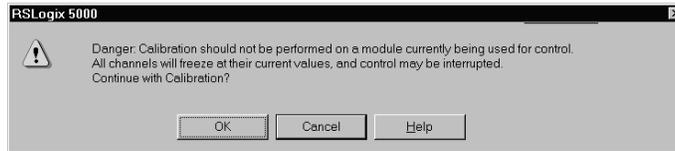
Follow these steps:

1. Connect your voltage calibrator to the module.
2. Go to the Calibration page. (Click on the tab for this page.)

Click here to start calibration



If your module is not in Program Mode, you see this warning. You must manually change the module to program mode before clicking on Yes.



3. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	-10 to 10 V	1.004696	19	OK
1	<input checked="" type="checkbox"/>	-10 to 10 V	1.004787	19	OK
2	<input checked="" type="checkbox"/>	-10 to 10 V	1.004920	19	OK
3	<input checked="" type="checkbox"/>	-10 to 10 V	1.004537	19	OK
4	<input checked="" type="checkbox"/>	-10 to 10 V	1.005473	20	OK
5	<input checked="" type="checkbox"/>	-10 to 10 V	1.005555	20	OK
6	<input checked="" type="checkbox"/>	-10 to 10 V	1.005411	20	OK
7	<input checked="" type="checkbox"/>	-10 to 10 V	1.005566	19	OK
8	<input checked="" type="checkbox"/>	-10 to 10 V	1.004704	20	OK
9	<input checked="" type="checkbox"/>	-10 to 10 V	1.004881	20	OK

C. Click here to continue

The low reference screen appears first.

This screen shows which channels will be calibrated for a low reference and the range of that calibration.

It also shows what reference signal is expected on the input.

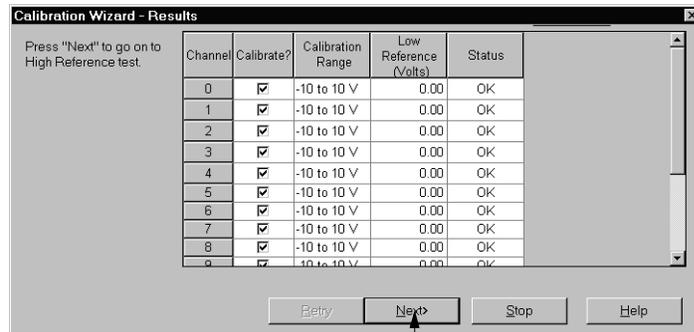
Channel	Calibrate?	Calibration Range	Low Reference (Volts)
0	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
1	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
2	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
3	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
4	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
5	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
6	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
7	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
8	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
9	<input checked="" type="checkbox"/>	-10 to 10 V	0.00

Click here to return to the last screen and make any necessary changes

Click here to calibrate the low reference

4. Set the calibrator for the low reference and apply it to the module.

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 4 until the status is OK.

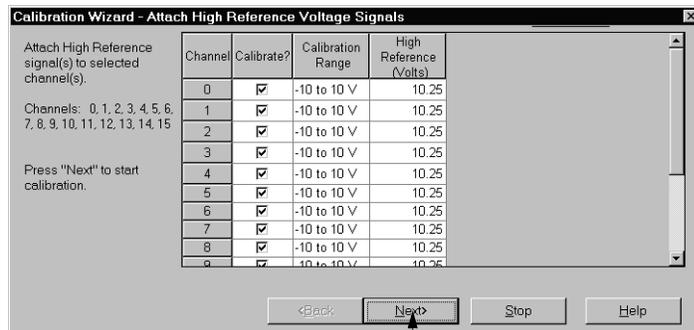


Click here to continue

5. Set the calibrator for the high reference and apply it to the module.

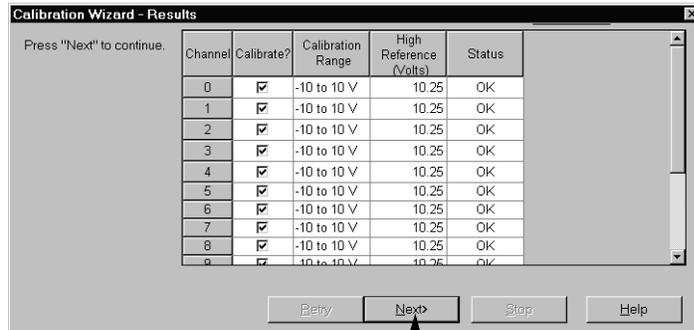
This screen shows which channels will be calibrated for a high reference and the range of that calibration.

It also shows what reference signal is expected at the input.



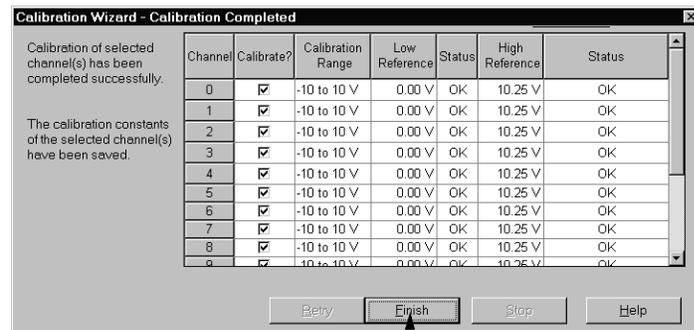
Click here to calibrate the high reference

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 5 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both.



Click here to return the module to normal operation

Calibrating the 1756-IF6CIS or 1756-IF6I Modules

The 1756-IF6CIS module can be used for applications that require current only. The 1756-IF6I module can be used for applications requiring voltage or current. Calibrate the modules for your specific application.

Calibrating the 1756-IF6I for Voltage Applications

During 1756-IF6I module calibration, 0.0V and +10.0V external references are applied consecutively to the module's terminals. The module records the deviation from these reference values (i.e. 0.0V and +10.0V) and stores it as calibration constants in the module's firmware. The internal calibration constants are then used in every subsequent signal conversion to compensate for circuit inaccuracies. The 0/10V user calibration compensates for all voltage ranges on the 1756-IF6I module (0-10V, +/-10V, and 0-5V) and compensates for inaccuracies of the module's entire analog circuitry, including input amplifier, resistors, and the A/D convertor.

The 1756-IF6I offers 3 input voltage ranges:

- -10 to 10V
- 0 to 5V
- 0 to 10V

IMPORTANT

Regardless of what voltage application range is selected prior to calibration, all voltage calibration uses a +/-10V range.

Calibrating the 1756-IF6CIS or 1756-IF6I for Current Applications

The 1756-IF6CIS and 1756-IF6I modules offer a 0 to 20mA current range. Calibrating the modules for current uses the same process as calibrating the 1756-IF6I for voltage except the change in input signal.

IMPORTANT

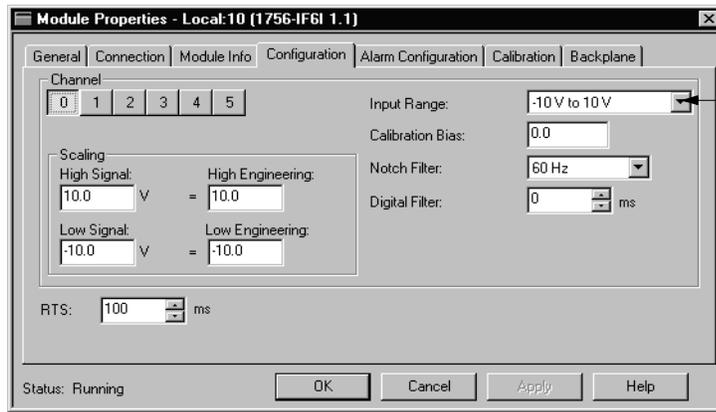
The following example shows how you can calibrate the 1756-IF6I module for voltage.

While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

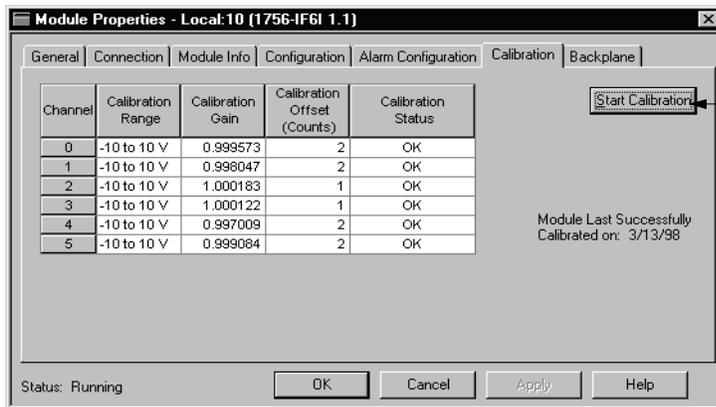
Follow these steps:

1. Connect your voltage calibrator to the module.
2. Go to the Configuration page.

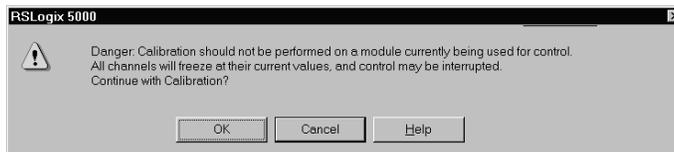
IMPORTANT: Make sure you choose the correct input range for each channel to be calibrated.



3. Go to the Calibration page. (Click on the tab for this page.)



If your module is not in Program Mode, you see this warning. You must manually change the module to program mode before clicking on Yes.



4. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

C. Click here to continue

Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	-10 to 10 V	0.999573	2	OK
1	<input checked="" type="checkbox"/>	-10 to 10 V	0.998047	2	OK
2	<input checked="" type="checkbox"/>	-10 to 10 V	1.000183	1	OK
3	<input checked="" type="checkbox"/>	-10 to 10 V	1.000122	1	OK
4	<input checked="" type="checkbox"/>	-10 to 10 V	0.997009	2	OK
5	<input checked="" type="checkbox"/>	-10 to 10 V	0.999084	2	OK

The low reference screen appears first.

5. Set the calibrator for the low reference and apply it to the module.

This screen shows which channels will be calibrated for a low reference and the range of that calibration.

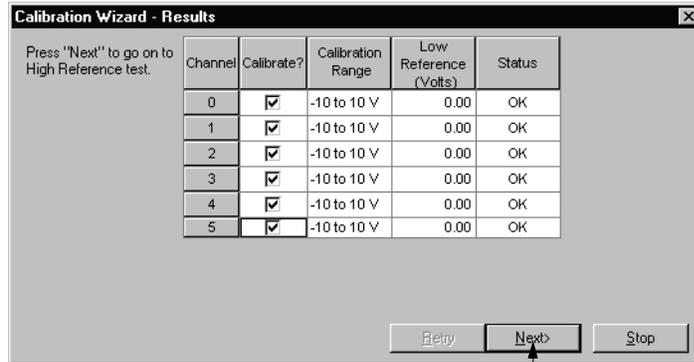
It also shows what reference signal is expected on the input.

Channel	Calibrate?	Calibration Range	Low Reference (Volts)
0	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
1	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
2	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
3	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
4	<input checked="" type="checkbox"/>	-10 to 10 V	0.00
5	<input checked="" type="checkbox"/>	-10 to 10 V	0.00

Click here to return to the last screen and make any necessary changes

Click here to calibrate the low reference

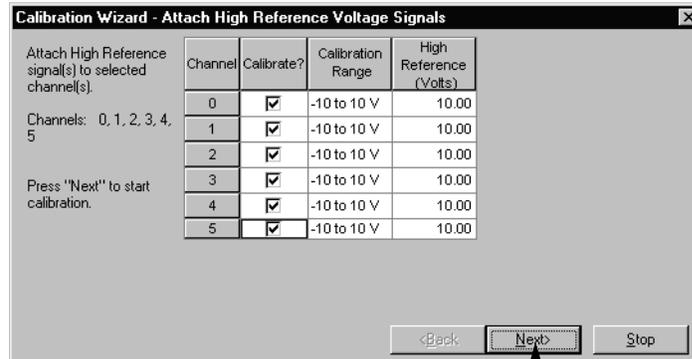
This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 5 until the status is OK.



Click here to continue

Now you must calibrate each channel for a high reference voltage.

6. Set the channels to be calibrated.

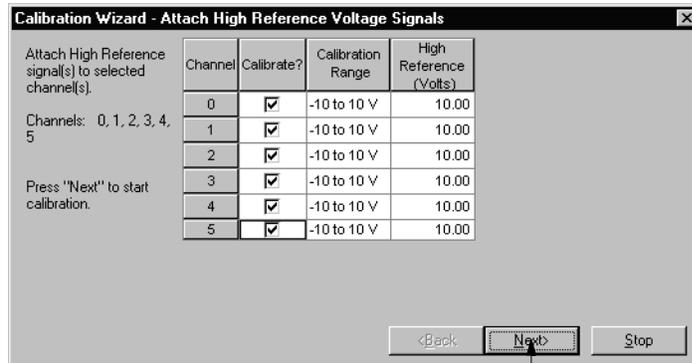


Click here to continue

7. Set the calibrator for the high reference and apply it to the module.

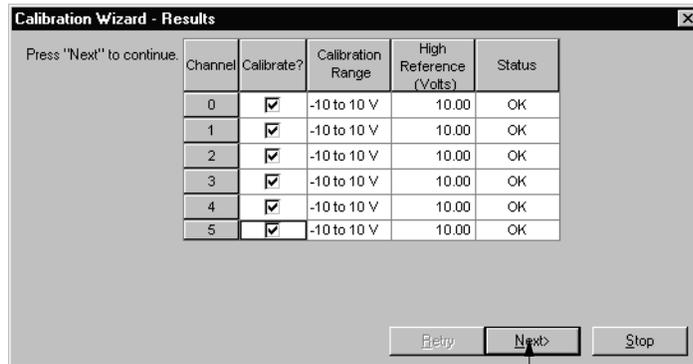
This screen shows which channels will be calibrated for a high reference and the range of that calibration.

It also shows what reference signal is expected at the input.



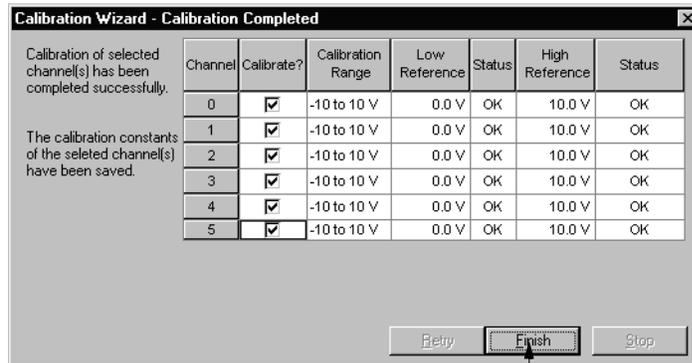
Click here to calibrate the high reference

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 7 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both.



Click here to finish calibration and return the module to normal operation

Calibrating the 1756-IR6I

This module does not calibrate for voltage or current. It uses two precision resistors to calibrate the channels in ohms. You must connect a 1Ω precision resistor for low reference calibration and a 487Ω precision resistor for high reference calibration. The 1756-IR6I only calibrates in the 1-487 Ω range.

IMPORTANT

When you are wiring precision resistors for calibration, follow the wiring example on page 6-20. Make sure terminals IN-x/B and RTN-x/C are shorted together at the RTB.

While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

Follow these steps:

1. Go to the Calibration page. (Click on the tab for this page.)

Channel	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	1 to 487 ohms	1.001282	6	OK
1	1 to 487 ohms	0.998718	-48	OK
2	1 to 487 ohms	1.000610	6	OK
3	1 to 487 ohms	0.998779	-53	OK
4	1 to 487 ohms	0.999756	1	OK
5	1 to 487 ohms	1.000244	13	OK

Module Last Successfully Calibrated on: 10/4/97

Status: Running

OK Cancel Apply Help

Click here to start calibration

IMPORTANT

Regardless of what ohms application range is selected prior to calibration, the 1756-IR6I only calibrates in the 1-487 Ω range.

2. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

C. Click here to continue

Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	1 to 487 ohms	1.001282	6	OK
1	<input checked="" type="checkbox"/>	1 to 487 ohms	0.998718	-48	OK
2	<input checked="" type="checkbox"/>	1 to 487 ohms	1.000610	6	OK
3	<input checked="" type="checkbox"/>	1 to 487 ohms	0.998779	-53	OK
4	<input checked="" type="checkbox"/>	1 to 487 ohms	0.999756	1	OK
5	<input checked="" type="checkbox"/>	1 to 487 ohms	1.000244	13	OK

The low reference screen appears first.

3. Connect a 1Ω resistor to each channel being calibrated.

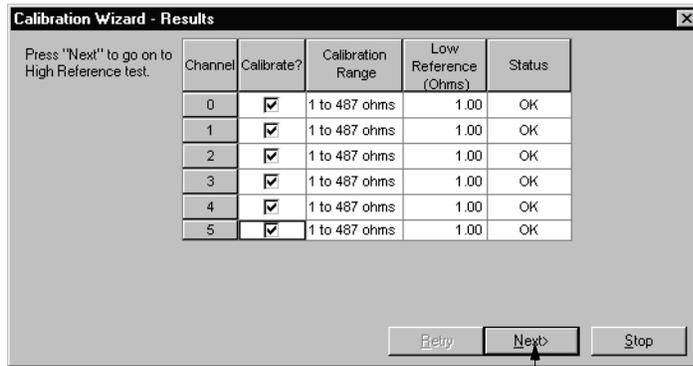
This screen shows which channels will be calibrated for a low reference and the range of that calibration.

It also shows what reference signal is expected on the input.

Click here to calibrate the low reference

Channel	Calibrate?	Calibration Range	Low Reference (Ohms)
0	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00
1	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00
2	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00
3	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00
4	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00
5	<input checked="" type="checkbox"/>	1 to 487 ohms	1.00

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 3 until the status is OK.



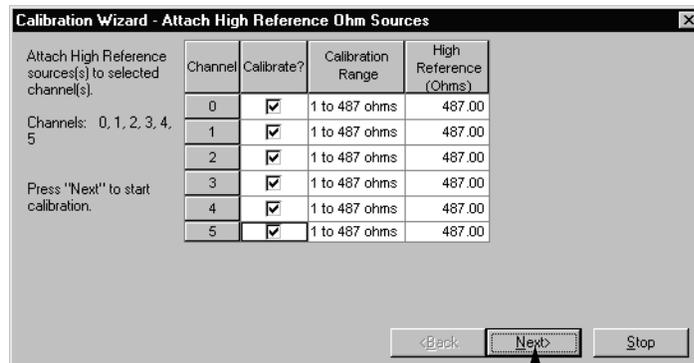
Click here to continue

Now you must calibrate each channel for a high reference.

4. Connect a 487Ω resistor to each channel being calibrated.

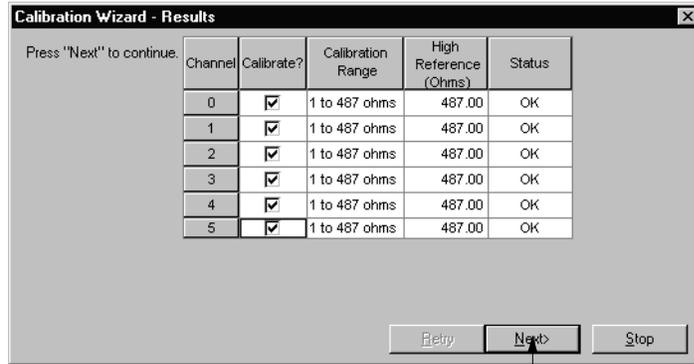
This screen shows which channels will be calibrated for a high reference and the range of that calibration.

It also shows what reference signal is expected on the input.



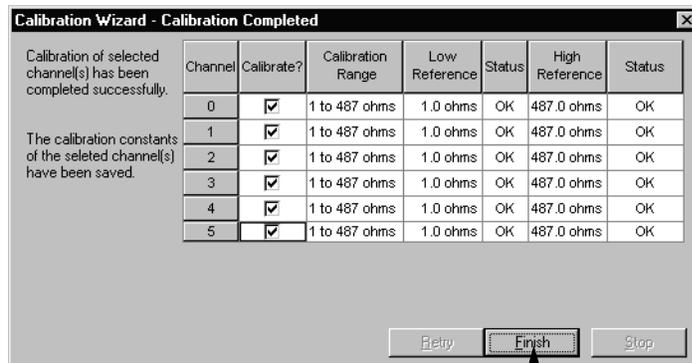
Click here to calibrate the high reference

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 4 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both and allows you to finish the calibration process and return to normal operation.



Click here to finish calibration and return the module to normal operation

Calibrating the 1756-IT6I or 1756-IT6I2

This module only calibrates in millivolts. You can calibrate the module to either a -12 to +30mV range or -12 to +78mV range, depending upon your specific application.

Calibrating the 1756-IT6I or 1756-IT6I2 for a -12mV to 30mV Range

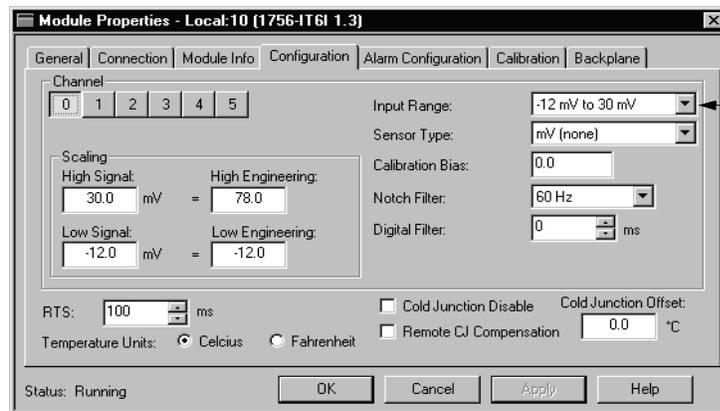
This example shows the steps for calibrating a 1756-IT6I module for a -12mV to 30mV range. Use the same steps to calibrate for a -12mV to 78mV range.

While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

Follow these steps:

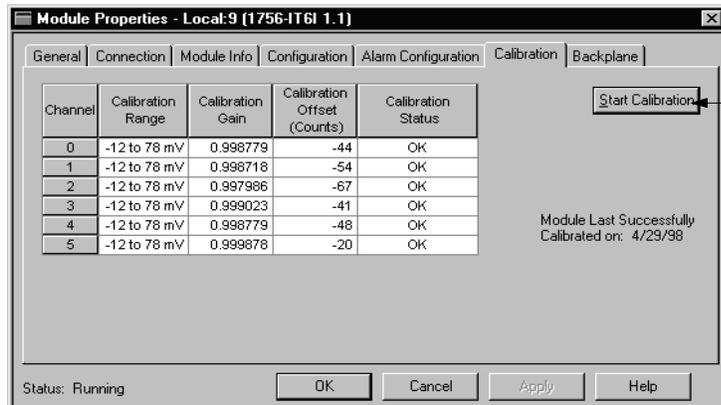
1. Connect your voltage calibrator to the module.
2. Go to the Configuration page.

IMPORTANT: The input range selected prior to calibration is the range in which the module will calibrate.



Use this pull-down menu to choose the Input Range

3. Go to the Calibration page. (Click on the tab for this page.)



Click here to start calibration

4. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

C. Click here to continue

Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	-12 to 78 mV	0.998779	-44	OK
1	<input checked="" type="checkbox"/>	-12 to 78 mV	0.998718	-54	OK
2	<input checked="" type="checkbox"/>	-12 to 78 mV	0.997986	-67	OK
3	<input checked="" type="checkbox"/>	-12 to 78 mV	0.999023	-41	OK
4	<input checked="" type="checkbox"/>	-12 to 78 mV	0.998779	-48	OK
5	<input checked="" type="checkbox"/>	-12 to 78 mV	0.998878	-20	OK

The low reference screen appears first.

5. Set the calibrator for the low reference and apply it to the module.

This screen shows which channels will be calibrated for a low reference and the range of that calibration.

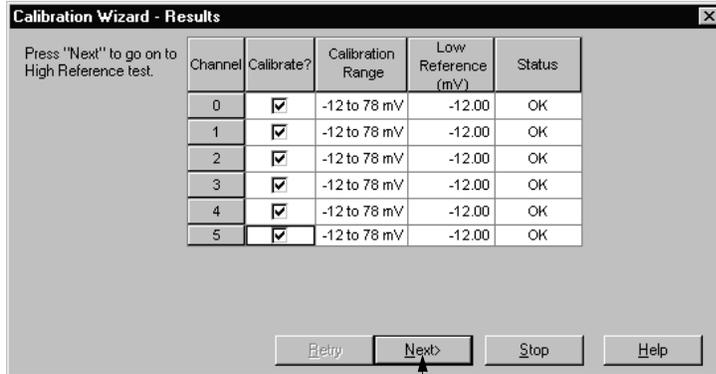
It also shows what reference signal is expected on the input.

Click here to return to the last screen and make any necessary changes

Click here to calibrate the low reference

Channel	Calibrate?	Calibration Range	Low Reference (mV)
0	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00
1	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00
2	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00
3	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00
4	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00
5	<input checked="" type="checkbox"/>	-12 to 78 mV	-12.00

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 5 until the status is OK.



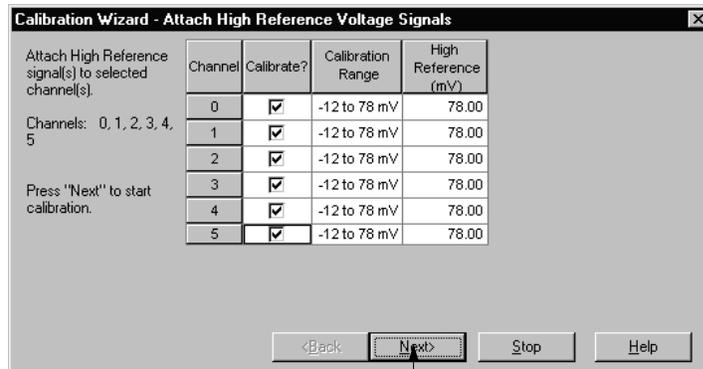
Click here to calibrate the high reference

Now you must calibrate each channel for a high reference voltage.

6. Set the calibrator for the high reference and apply it to the module.

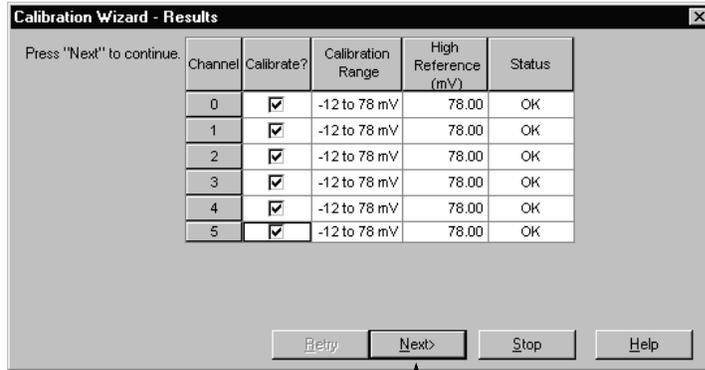
This screen shows which channels will be calibrated for a high reference and the range of that calibration.

It also shows what reference signal is expected on the input.



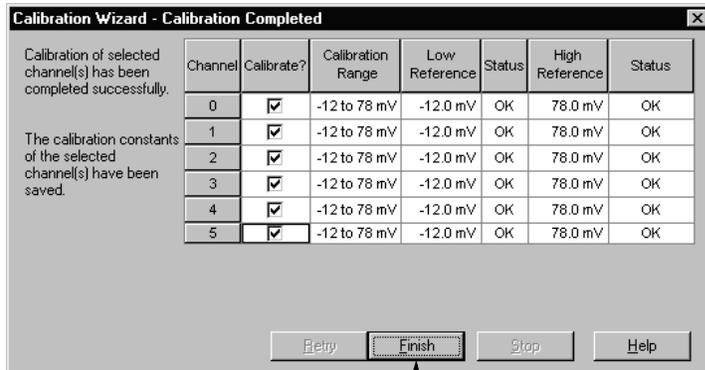
Click here to calibrate the high reference

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, retry step 6 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both and allows you to finish the calibration process and return to normal operation.



Click here to finish calibration

Calibrating Output Modules

Output calibration is a multi-step process that involves measuring a signal from the module. This section has three parts.

Table 11.3 lists the catalog numbers covered in this section:

Table 11.3

For information about:	See page:
Calibrating the 1756-OF4 or 1756-OF8 Modules	11-22
Calibrating the 1756-OF6CI	11-27
Calibrating the 1756-OF6VI	11-31

Calibrating the 1756-OF4 or 1756-OF8 Modules

The 1756-OF4 and 1756-OF8 modules can be used for current or voltage applications.

Current applications

RSLogix 5000 commands the module to output specific levels of current. You must measure the actual level and record the results. This measurement allows the module to account for any inaccuracies.

[Click here to start calibration](#)

Voltage applications

RSLogix 5000 commands the module to output specific levels of voltage. You must measure the actual level and record the results. This measurement allows the module to account for any inaccuracies.

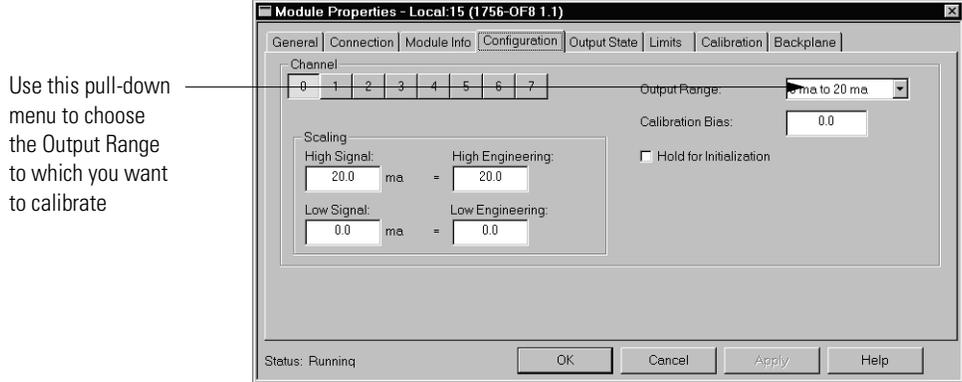
IMPORTANT

This example shows a module calibrated for a current application. Use the same steps to calibrate for voltage.

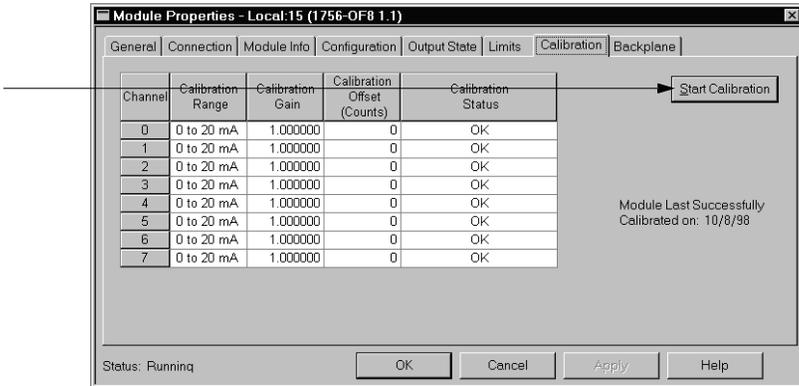
While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

Follow these steps:

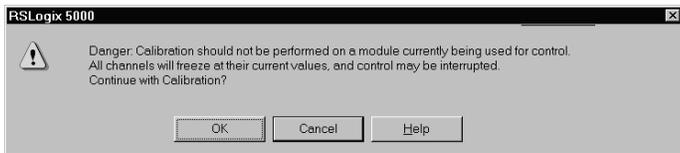
1. Connect your current meter to the module.
2. Go to the Configuration page. (Click on the tab for this page.)



3. Go to the Calibration page. (Click on the tab for this page.)



If your module is not in Program Mode, you see this warning. You must manually change the module to program mode before clicking on Yes.



4. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

C. Click here to continue

Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
1	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
2	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
3	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
4	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
5	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
6	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK
7	<input checked="" type="checkbox"/>	0 to 20 mA	1.000000	0	OK

The low reference screen appears first.

This screen shows which channels will be calibrated for a low reference and the range of that calibration

Click here to calibrate the low reference

Channel	Calibrate?	Calibration Range	Low Reference (mA)
0	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
1	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
2	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
3	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
4	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
5	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
6	<input checked="" type="checkbox"/>	0 to 20 mA	4.00
7	<input checked="" type="checkbox"/>	0 to 20 mA	4.00

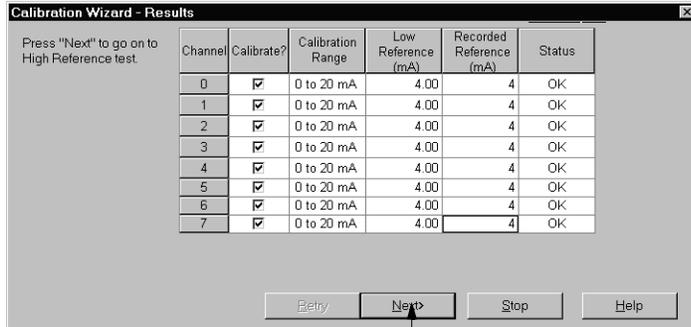
5. Record the results of your measurement.

Record measurement values here

Click here to continue

Channel	Calibrate?	Calibration Range	Low Reference (mA)	Recorded Reference (mA)
0	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
1	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
2	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
3	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
4	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
5	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
6	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4
7	<input checked="" type="checkbox"/>	0 to 20 mA	4.00	4

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 4 until the status is OK.

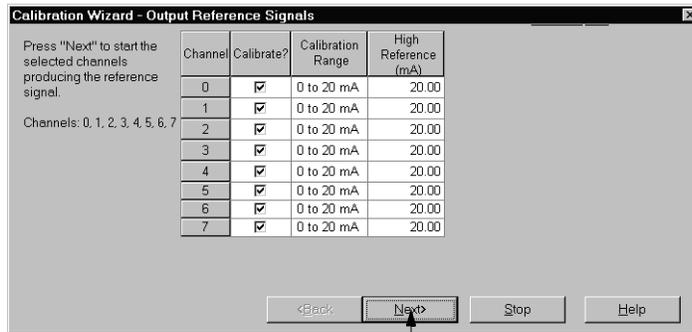


Click here to continue

Now you must calibrate each channel for a high reference voltage.

6. Set the channels to be calibrated.

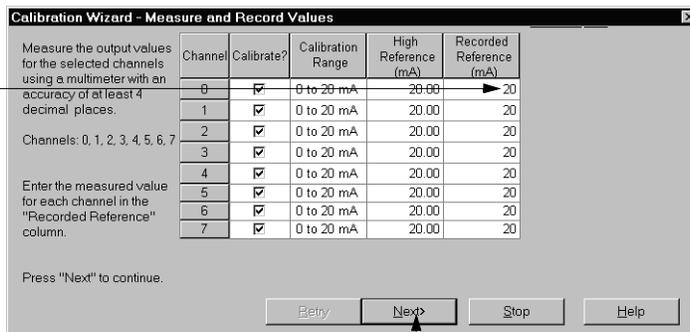
This screen shows which channels will be calibrated for a high reference and the range of that calibration



Click here to calibrate the high reference

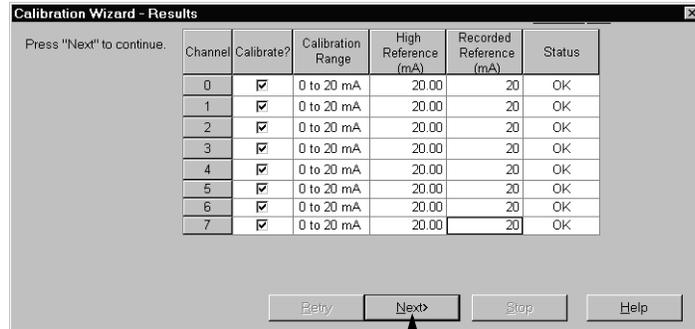
7. Record the measurement.

Record measurement values here



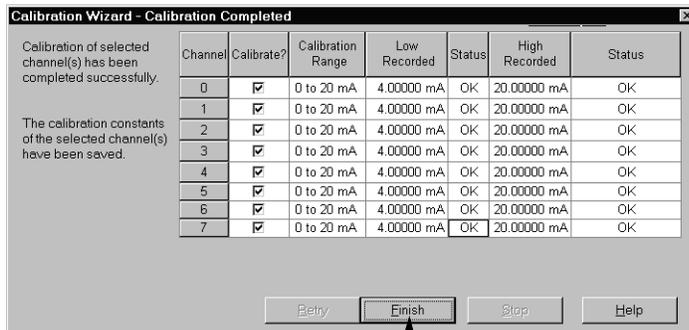
Click here to continue

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 6 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both and allows you to finish the calibration process and return to normal operation.



Click here to finish calibration and return the module to normal operation

Calibrating the 1756-OF6CI

This module must be calibrated for current. RSLogix 5000 commands the module to output specific levels of current. You must measure the actual level and record the results. This measurement allows the module to account for any inaccuracies.

While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

Follow these steps:

1. Connect your current meter to the module.
2. Go to the Calibration page. (Click on the tab for this page.)

Click here to start calibration

Channel	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	0 to 20 mA	0.992859	14	OK
1	0 to 20 mA	0.994080	11	OK
2	0 to 20 mA	0.993591	15	OK
3	0 to 20 mA	0.991028	22	OK
4	0 to 20 mA	0.992188	21	OK
5	0 to 20 mA	0.993958	16	OK

Module Last Successfully Calibrated on: 10/1/97

Status: Running

Buttons: OK, Cancel, Apply, Help

3. Set the channels to be calibrated.

A. Choose the channels you want to calibrate here

B. Choose whether you want to calibrate channels in groups or one at a time here

C. Click here to continue

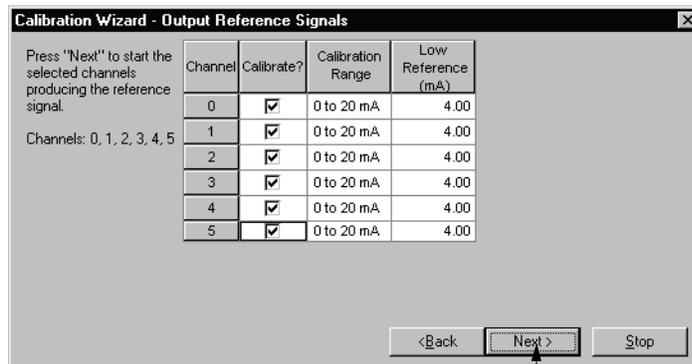
Channel	Calibrate?	Calibration Range	Calibration Gain	Calibration Offset (Counts)	Calibration Status
0	<input checked="" type="checkbox"/>	0 to 20 mA	0.992859	14	OK
1	<input checked="" type="checkbox"/>	0 to 20 mA	0.994080	11	OK
2	<input checked="" type="checkbox"/>	0 to 20 mA	0.993591	15	OK
3	<input checked="" type="checkbox"/>	0 to 20 mA	0.991028	22	OK
4	<input checked="" type="checkbox"/>	0 to 20 mA	0.992188	21	OK
5	<input checked="" type="checkbox"/>	0 to 20 mA	0.993958	16	OK

Press "Next" to continue.

Buttons: <Back, Next >, Stop

The low reference screen appears first.

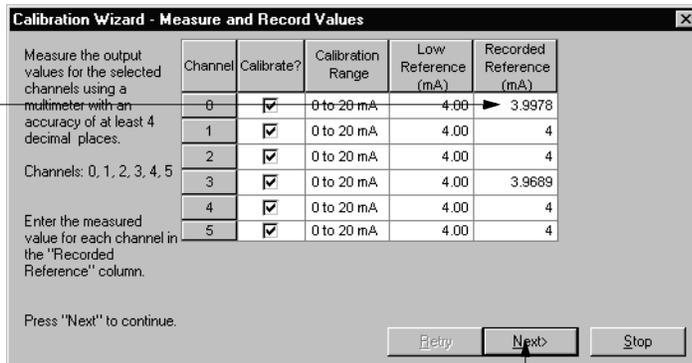
This screen shows which channels will be calibrated for a low reference and the range of that calibration



Click here to calibrate the low reference

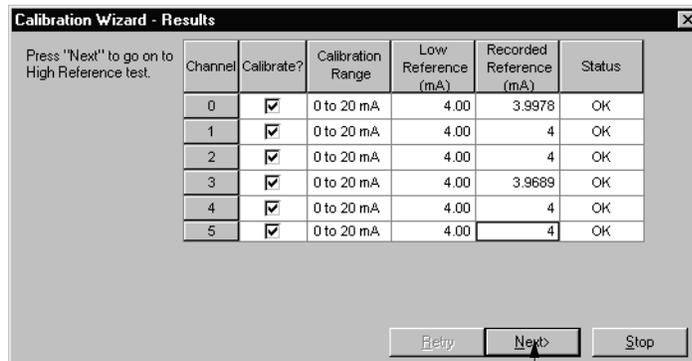
4. Record the results of your measurement.

Record measurement values here



Click here to continue

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 3 until the status is OK.

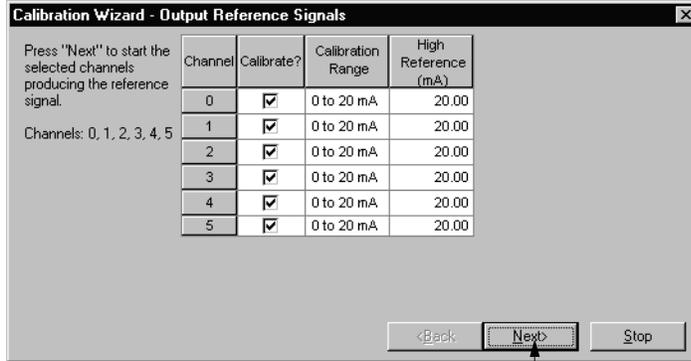


Click here to continue

Now you must calibrate each channel for a high reference voltage.

5. Set the channels to be calibrated.

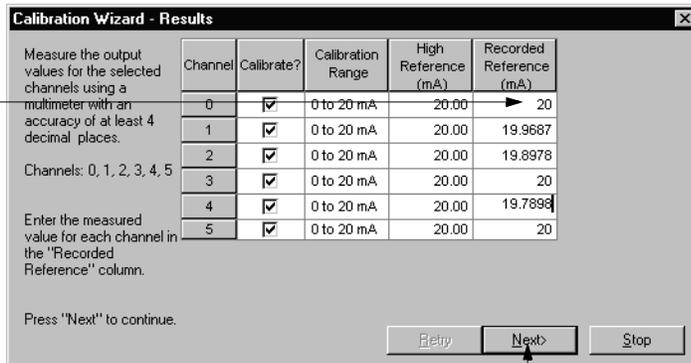
This screen shows which channels will be calibrated for a high reference and the range of that calibration



Click here to calibrate the high reference

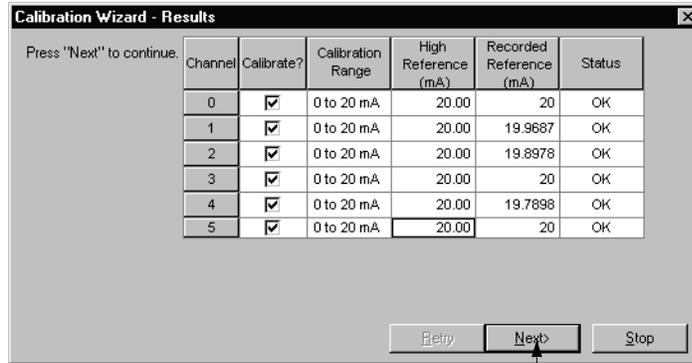
6. Record the measurement.

Record measurement values here



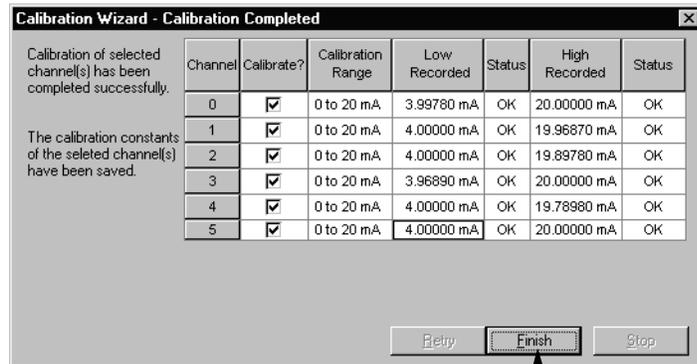
Click here to continue

This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 5 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both and allows you to finish the calibration process and return to normal operation.



Click here to finish calibration and return the module to normal operation

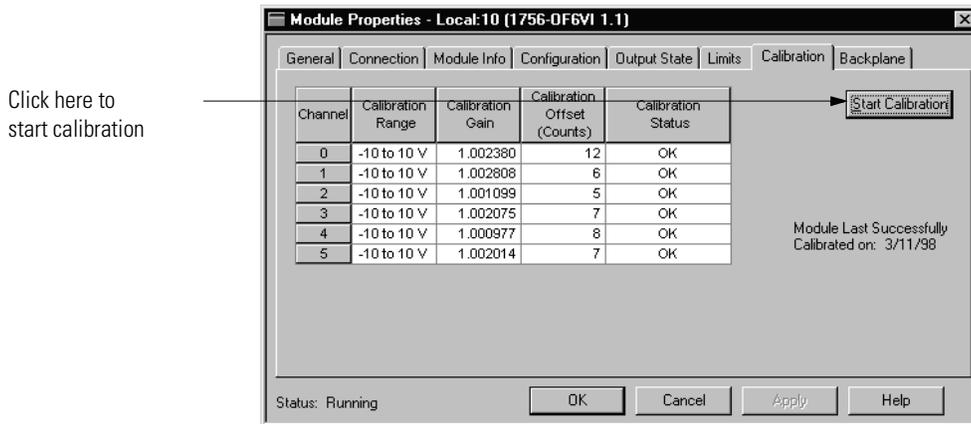
Calibrating the 1756-OF6VI

This module must be calibrated for voltage. RSLogix 5000 commands the module to output specific levels of voltage. You must measure the actual level and record the results. This measurement allows the module to account for any inaccuracies.

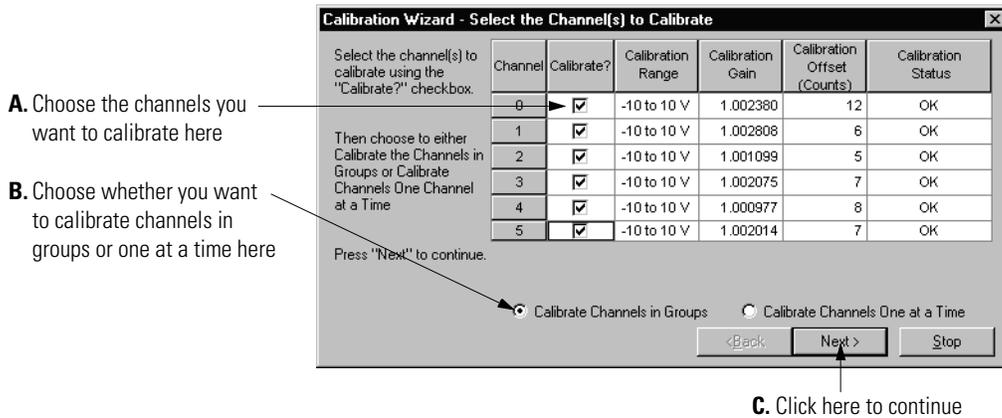
While you are online, you must access the modules' properties page. To see how to reach this page, see page 10-17.

Follow these steps:

1. Connect your voltage meter to the module.
2. Go to the Calibration page. (Click on the tab for this page.)

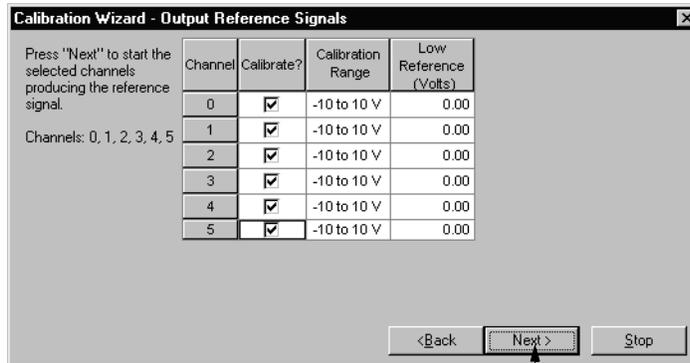


3. Set the channels to be calibrated.



The low reference screen appears first.

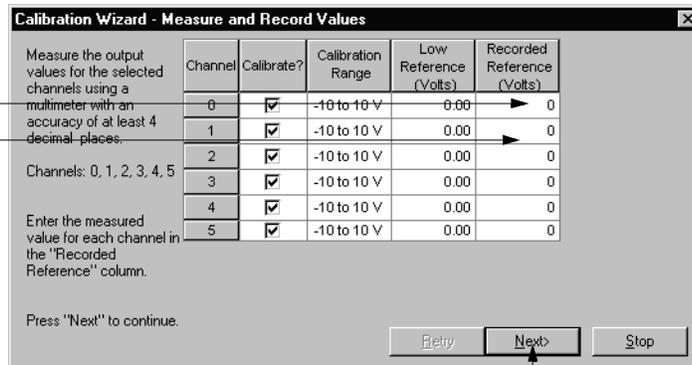
This screen shows which channels will be calibrated for a low reference and the range of that calibration



Click here to calibrate the low reference

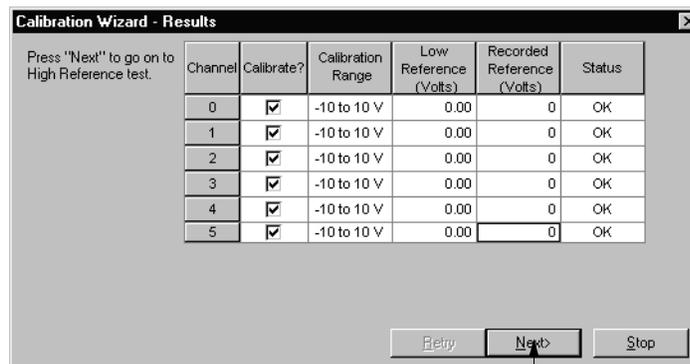
4. Record the results of your measurement.

Record measurement values here
Record measurement values here



Click here to continue

This screen displays the status of each channel after calibrating for a low reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 3 until the status is OK.

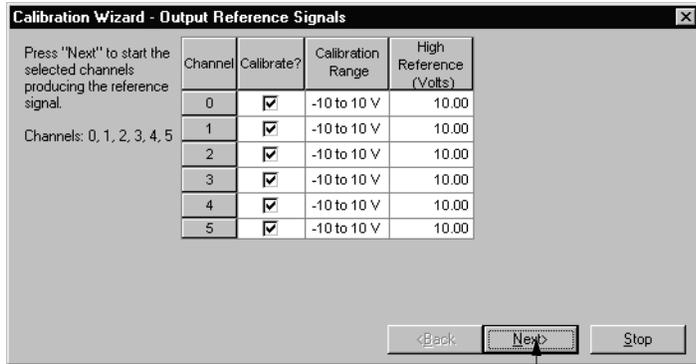


Click here to continue

Now you must calibrate each channel for a high reference voltage.

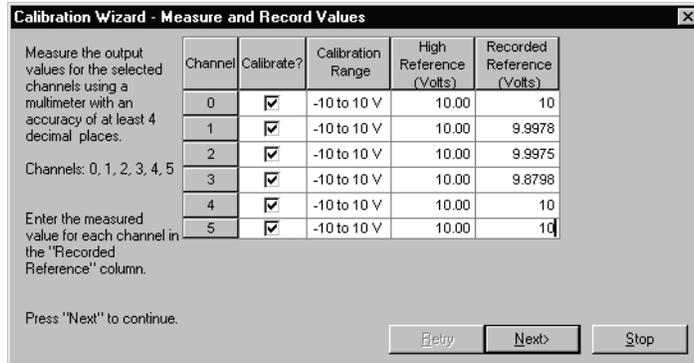
5. Set the channels to be calibrated.

This screen shows which channels will be calibrated for a high reference and the range of that calibration

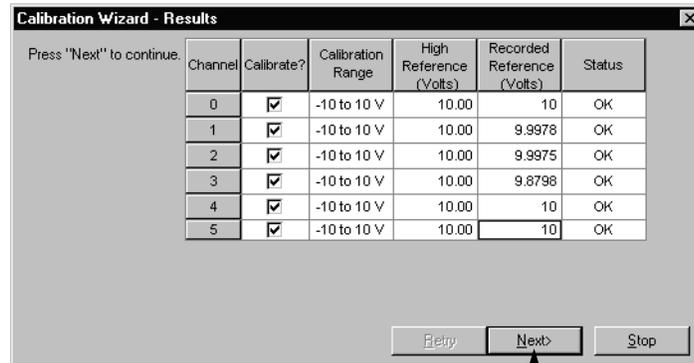


Click here to calibrate the high reference

6. Record the measurement.

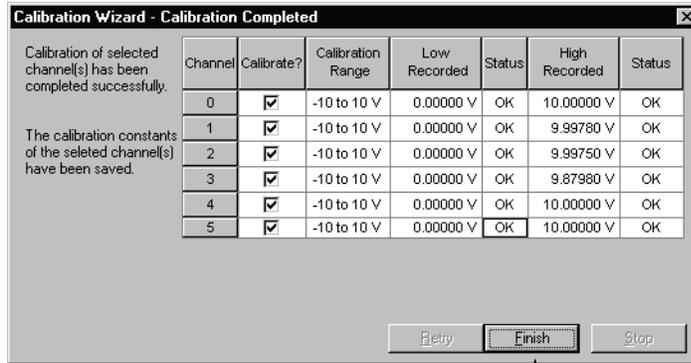


This screen displays the status of each channel after calibrating for a high reference. If all channels are OK, continue, as shown below. If any channels report an Error, return to step 5 until the status is OK.



Click here to continue

After you have completed both low and high reference calibration, this screen shows the status of both and allows you to finish the calibration process and return to normal operation.



Click here to finish calibration and return the module to normal operation

Chapter Summary and What's Next

In this chapter, you read about Calibrating the ControlLogix Analog I/O Modules.

Chapter 12 describes Troubleshooting Your ControlLogix Analog I/O Module.

Troubleshooting Your ControlLogix Analog I/O Module

Chapter Objectives

This chapter describes the indicators on ControlLogix analog I/O modules, and how to use them in troubleshooting.

For information about:	See page:
Using Module Indicators to Troubleshoot Your Module	12-1
Using RSLogix 5000 to Troubleshoot Your Module	12-3

Using Module Indicators to Troubleshoot Your Module

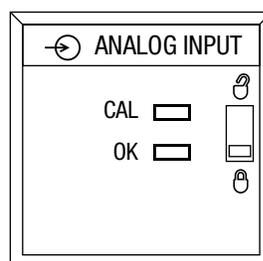
Each ControlLogix analog I/O module has indicators that display module status. Table 12.1 lists the indicators used on ControlLogix analog input modules:

Table 12.1 LED Indicators for Input Modules

LED indicators:	This display:	Means:	Take this action:
OK	Steady green light	The inputs are being multicast and in normal operating state.	None
OK	Flashing green light	The module has passed internal diagnostics but is not currently performing connected communication.	None
OK	Flashing red light	Previously established communication has timed out.	Check controller and chassis communication
OK	Steady red light	The module must be replaced.	Replace the module.
CAL	Flashing green light	The module is in calibration mode.	Finish calibration

Figure 12.1 shows the LED display used with input modules.

Figure 12.1



20962-M

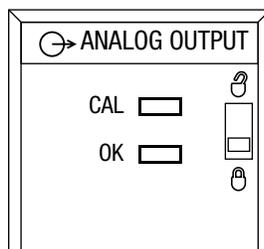
Table 12.2 lists the indicators used on ControlLogix analog output modules:

Table 12.2 LED Indicators for Output Modules

LED indicators:	This display:	Means:	Take this action:
OK	Steady green light	The outputs are in a normal operating state in Run Mode.	None
OK	Flashing green light	Either: <ul style="list-style-type: none"> • the module has passed internal diagnostics and is not actively controlled or <ul style="list-style-type: none"> • a connection is open and the controller is in program mode. 	None
OK	Flashing red light	Previously established communication has timed out.	Check controller and chassis communication
OK	Steady red light	The module must be replaced.	Replace the module.
CAL	Flashing green light	The module is in calibration mode.	Finish calibration

Figure 12.2 shows the LED display used with analog output modules.

Figure 12.2



20965-M

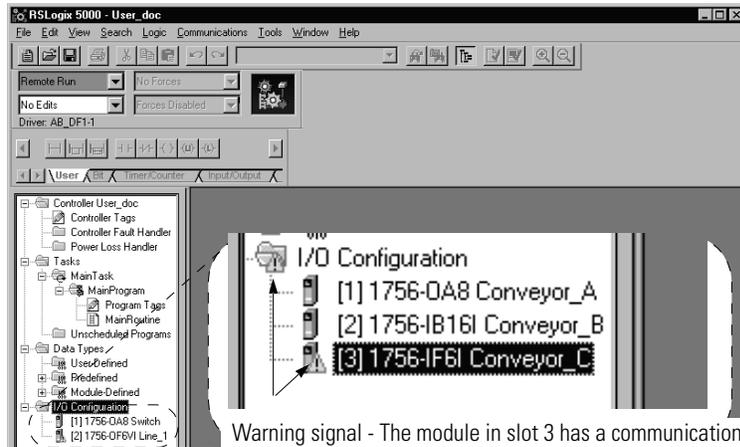
Using RSLogix 5000 to Troubleshoot Your Module

In addition to the LED display on the module, RSLogix 5000 alerts you to fault conditions. You will be alerted in one of three ways:

- Warning signal on the main screen next to the module-This occurs when the connection to the module is broken.

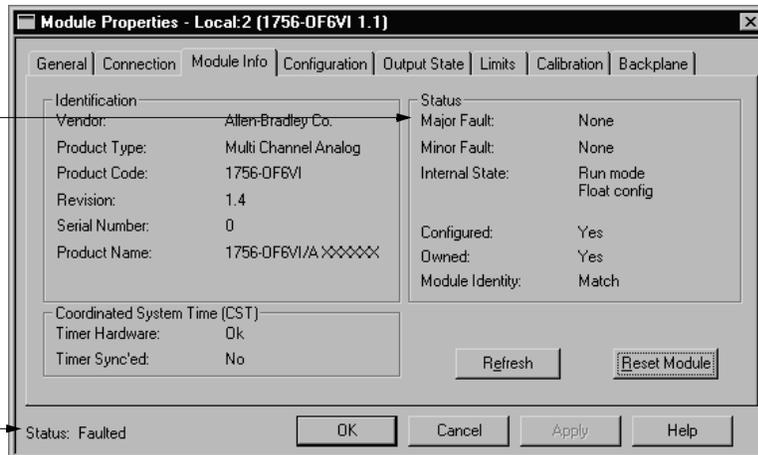


Warning icon when a communications fault occurs or if the module is inhibited



- Fault message in a screen's status line

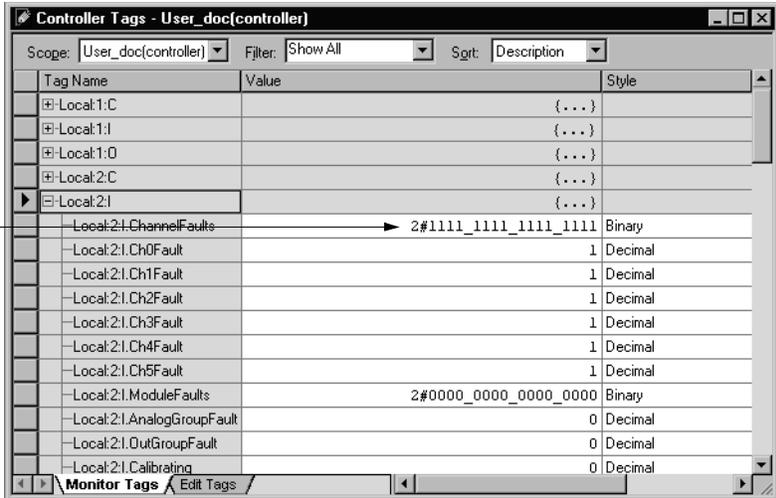
Status section lists Major and Minor Faults and the Internal State of the module



Status line provides information on the connection to the module

- Notification in the Tag Editor - General module faults are also reported in the Tag Editor. Diagnostic faults are only reported in the Tag Editor

A communication fault has occurred for any point that lists the number 1 in the Fault line

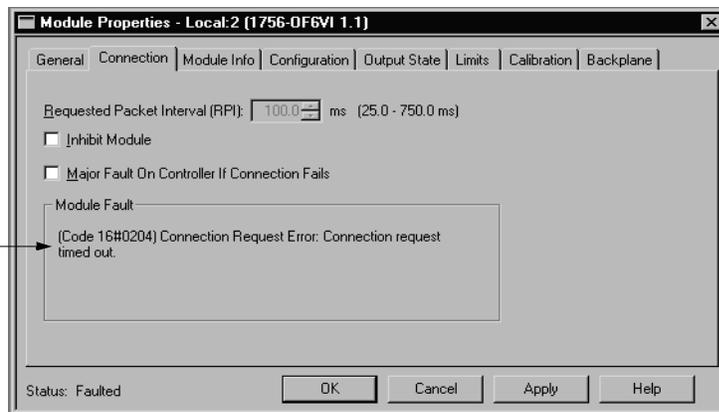


- Status on the Module Info Page

Determining Fault Type

When you are monitoring a module's configuration properties in RSLogix 5000 and receive a Communications fault message, the Connection page lists the type of fault.

The fault type is listed here



For a detailed listing of the possible faults, their causes and suggested solutions, see Module Faults in the online help.

Chapter Summary and What's Next

In this chapter you learned about troubleshooting the module.

Move on to Appendix A to see the Specifications for each module.

Specifications

Table A.1 lists where you can find specifications for the ControlLogix analog I/O modules.

Table A.1

For:	See page:
1756-IF16 Specifications	A-2
1756-IF6CIS Specifications	A-4
1756-IF6I Specifications	A-6
1756-IF8 Specifications	A-8
1756-IR6I Specifications	A-10
1756-IT6I Specifications	A-12
1756-IT6I2 Specifications	A-14
1756-OF4 Specifications	A-16
1756-OF6CI Specifications	A-18
1756-OF6VI Specifications	A-20
1756-OF8 Specifications	A-22

1756-IF16 Specifications

Number of Inputs	16 single ended, 8 differential or 4 differential (high speed)
Module Location	1756 ControlLogix Chassis
Backplane Current	150mA @ 5.1V dc & 65mA @ 24V dc
Backplane Power	2.33W
Power Dissipation within Module	2.3W – Voltage 3.9W – Current
Thermal Dissipation	7.84 BTU/hr. – Voltage 13.30 BTU/hr. – Current
Input Range and Resolution	+/-10.25V – 320 μ V/count (15 bits plus sign bipolar) 0-10.25V – 160 μ V/count (16 bits) 0-5.125V – 80 μ V/count (16 bits) 0-20.5mA – 0.32 μ A/count (16 bits)
Common Mode Voltage Range	+/- 10.25V (20.5V between any two input terminals)
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Input Impedance	>1meg Ω – Voltage 249 Ω – Current
Open Circuit Detection Time	Positive full scale reading within 5s – Differential Voltage Negative full scale reading within 5s – Single-ended/Differential Current Even numbered channels go to positive full scale reading within 5s, odd numbered channels go to negative full scale reading within 5s – Single-ended voltage
Overvoltage Protection	30V dc – Voltage 8V dc – Current
Normal Mode Noise Rejection ⁽¹⁾	>80dB at 50/60Hz
Common Mode Noise Rejection	>100dB at 50/60Hz
Calibrated Accuracy	Better than 0.05% of range – Voltage Better than 0.15% of range – Current
Calibration Interval	12 months
Input Offset Drift with Temperature	90 μ V/ $^{\circ}$ C
Gain Drift with Temperature	15 ppm/ $^{\circ}$ C – Voltage 307.5 μ V/ $^{\circ}$ C for +/-10.25V range; 153.8 μ V/ $^{\circ}$ C for 0-10.25V range; 76.9 μ V/ $^{\circ}$ C for 0-5.125V range 20 ppm/ $^{\circ}$ C – Current +/-0.41 μ A/ $^{\circ}$ C
Module Error over Full Temperature Range ⁽²⁾	0.1% of range – Voltage 0.3% of range – Current
Module Conversion Method	Sigma-Delta
Isolation Voltage User to system	250V 100% tested at 2550V dc for 1s
Module Scan Time for All Channels (Sample Rate Module Filter Dependent)	16-488ms – 16-point single ended 8-244ms – 8-point differential 5-122ms – 4-point differential -
RTB Screw Torque (Cage clamp)	4.4 inch-pounds (0.4Nm)
Module Keying (Backplane)	Electronic
RTB Keying	User defined
Field Wiring Arm and Housing	36 Position RTB (1756-TBCH or TBS6H) ⁽³⁾

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): Operating 30g Non-operating 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth (CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽²⁾ 3/64 inch (1.2mm) insulation maximum ^{2(4), (5)}
Screwdriver Width for RTB	1/8 inch (3.2mm) maximum
Certifications (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁶⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS 2064; Industrial Emissions EEx ⁽⁵⁾ European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n"

⁽¹⁾ This specification is module filter dependent.

⁽²⁾ For more information on this specification, see Appendix E.

⁽³⁾ Maximum wire size requires the extended housing - 1756-TBE.

⁽⁴⁾ Use this conductor category information for planning conductor routing as described in the system level installation manual.

⁽⁵⁾ Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

⁽⁶⁾ See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IF6CIS Specifications

Number of Inputs	6 points isolated
Module Location	ControlLogix Chassis
Backplane Current	250 mA @ 5.1V dc & 275 mA @ 24V dc
Backplane Power	7.9W
Module Power Dissipation	5.1W @ 60° C
Thermal Dissipation	17.4 BTU/hr.
Input Range	0-21mA (Over-range indication when exceeded)
Resolution 0-21mA	0.34 μ A/bit 16bit (15.9bits)
Data Format	Left justified, 2's complement – Integer Mode IEEE32 bit – Floating Point
Input Impedance	Approximately 215 ohm
Sourcing Voltage	20V dc minimum 30V dc maximum
Sourcing Current	Current limited to <30mA maximum
Open Circuit Detection Time	Zero reading within 5 seconds
Overvoltage Protection	30V AC/DC with PTC and Sense Resistor
Normal Mode Noise Rejection ⁽¹⁾	60dB at 60Hz
Common Mode Noise Rejection	120dB at 60Hz, 100 dB at 50Hz
Channel Bandwidth ⁽¹⁾	3-262Hz (-3dB)
Settling Time to % of Full Scale ⁽¹⁾	5% of FS: <80 milliseconds
Calibrated Accuracy ⁽²⁾ Typical Worst case	Better than 0.025% of range Better than 0.1% of range
Calibration Interval	12 months
Input Offset Drift with Temperature	200nA/°C
Gain Drift with Temperature ⁽²⁾ Typical Worst Case	17 ppm/°C 0.36 μ A/°C 35 ppm/°C 0.74 μ A/°C
Module Error over Full Temperature Range ⁽²⁾	0.2% of range
Module Scan Time for all Channels (Sample Rate)	25 milliseconds minimum – Floating Point Mode 10 milliseconds minimum – Integer Mode
Isolation Voltage Channel to channel User to system	Optically Isolated, Transformer Coupled 250V 100% tested at 1900V dc for 2 s 250V 100% tested at 1900V dc for 2 s
Module Conversion Method	Sigma-Delta
RTB Screw Torque (NEMA clamp)	7-9 inch-lbs (.8 to 1Nm)
Module Keying (Backplane)	Electronic
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽³⁾

Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽²⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽⁴⁾ , ⁽⁵⁾
Screwdriver Blade Width for RTB	5/16 inch (8mm) maximum
Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g
Non-operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 2000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications: (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁶⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions

⁽¹⁾ These specifications are notch filter dependant.

⁽²⁾ For more information on this specification, see Appendix E.

⁽³⁾ Maximum wire size will require extended housing - 1756-TBE.

⁽⁴⁾ Use this conductor category information for planning conductor routing as described in the system level installation manual.

⁽⁵⁾ Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

⁽⁶⁾ See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IF6I Specifications

Number of Inputs	6 individually isolated channels
Module Location	1756 ControlLogix Chassis
Backplane Current (No module external power requirements)	250mA @5.1V dc & 100mA @ 24V dc
Backplane Power	3.7W
Power Dissipation within Module	3.7W - Voltage 4.3W - Current
Thermal Dissipation	12.62 BTU/hr. - Voltage 14.32 BTU/hr. - Current
Input Range	+/-10.5V, 0-10.5V, 0-5.25V, 0-21mA (overrange indication when exceeded)
Resolution +/-10.5V range 0 to 10.5V range 0 to 5.25V range 0-21mA range	Approximately 16 bits across each range shown below 343 μ V/count 171 μ V/count 86 μ V/count 0.34 μ A/count
Data Format	2s complement – Integer mode IEEE 32 bit – Floating point mode
Input Impedance	>10M Ω – Voltage 249 Ω – Current
Open Circuit Detection Time	Positive full scale reading within 5s
Overvoltage Protection	120V ac/dc – Voltage 8V ac/dc with on-board current resistor – Current
Normal Mode Noise Rejection ⁽¹⁾	60dB at 60Hz
Common Mode Noise Rejection	120dB at 60Hz, 100dB at 50Hz
Channel Bandwidth ⁽¹⁾	15Hz (-3dB)
Settling Time to 5% of Full Scale ⁽¹⁾	<80ms
Calibrated Accuracy ⁽²⁾ Typical Worst case	Better than 0.05% of range Better than 0.1% of range
Calibration Interval	12 months
Input Offset Drift with Temperature	2 μ V/ $^{\circ}$ C
Gain Drift with Temperature ⁽²⁾ Typical Worst Case	35 ppm/ $^{\circ}$ C – Voltage 735 μ V/ $^{\circ}$ C for +/-10.5V range; 367.5 μ V/ $^{\circ}$ C for 0-10.5V range; 183.8 μ V/ $^{\circ}$ C for 0-5.25V range 45 ppm/ $^{\circ}$ C – Current +/-0.945 μ A/ $^{\circ}$ C 80 ppm/ $^{\circ}$ C – Voltage 1680 μ V/ $^{\circ}$ C for +/-10.5V range; 840 μ V/ $^{\circ}$ C for 0-10.5V range; 420 μ V/ $^{\circ}$ C for 0-5.25V range 90 ppm/ $^{\circ}$ C – Current +/-1.89 μ A/ $^{\circ}$ C
Module Error over Full Temperature Range ⁽²⁾	0.54% of range
Minimum Module Scan Time for all Channels (Sample Rate) ⁽¹⁾	25ms minimum – Floating Point Mode 10ms minimum – Integer Mode
Isolation Voltage Channel to channel User to system	Optoisolated, transformer isolated 100% tested at 1700V dc for 1s, based on 250V ac 100% tested at 1700V dc for 1s, based on 250V ac
Module Conversion Method	Sigma-Delta
Module Keying (Backplane)	Electronic
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽³⁾

Conductors Wire Size	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽³⁾ 3/64 inch (1.2mm) insulation maximum
Category	2 ⁽⁴⁾ , ⁽⁵⁾
Screwdriver Blade Width for RTB	5/16 inch (8mm) maximum
Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g
Non-operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 2000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications: (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁶⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions

(1) These specifications are module filter dependent.
(2) For more information on this specification, see Appendix E.
(3) Maximum wire size will require extended housing - 1756-TBE.
(4) Use this conductor category information for planning conductor routing as described in the system level installation manual.
(5) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.
(6) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IF8 Specifications

Number of Inputs	8 single ended, 4 differential or 2 differential (high speed)
Module Location	1756 ControlLogix Chassis
Backplane Current	150mA @ 5.1V dc & 40mA @ 24V dc
Backplane Power	2.33W
Power Dissipation within Module	1.73W – Voltage 2.53W – Current
Thermal Dissipation	5.9 BTU/hr. – Voltage 8.6 BTU/hr. – Current
Input Range and Resolution	+/-10.25V – 320 μ V/count (15 bits plus sign bipolar) 0-10.25V – 160 μ V/count (16 bits) 0-5.125V – 80 μ V/count (16 bits) 0-20.5mA – 0.32 μ A/count (16 bits)
Common Mode Voltage Range	+/- 10.25V (20.5V between any two input terminals)
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Input Impedance	>1meg Ω – Voltage 249 Ω – Current
Open Circuit Detection Time	Positive full scale reading within 5s – Differential Voltage Negative full scale reading within 5s – Single-ended/Differential Current Even numbered channels go to positive full scale reading within 5s, odd numbered channels go to negative full scale reading within 5s – Single-ended voltage
Overvoltage Protection	30V dc – Voltage 8V dc – Current
Normal Mode Noise Rejection ⁽¹⁾	>80dB at 50/60Hz
Common Mode Noise Rejection	>100dB at 50/60Hz
Calibrated Accuracy	Better than 0.05% of range – Voltage Better than 0.15% of range – Current
Calibration Interval	12 months
Input Offset Drift with Temperature	90 μ V/ $^{\circ}$ C
Gain Drift with Temperature	15 ppm/ $^{\circ}$ C – Voltage 307.5 μ V/ $^{\circ}$ C for +/-10.25V range; 153.8 μ V/ $^{\circ}$ C for 0-10.25V range; 76.9 μ V/ $^{\circ}$ C for 0-5.125V range 20 ppm/ $^{\circ}$ C – Current +/-0.41 μ A/ $^{\circ}$ C
Module Error over Full Temperature Range ⁽²⁾	0.1% of range – Voltage 0.3% of range – Current
Module Conversion Method	Sigma-Delta
Isolation Voltage User to system	250V 100% tested at 2550 dc for 1s
Module Scan Time for All Channels (Sample Rate Module Filter Dependent)	16 to 488ms – 8-point single ended 8 to 244ms – 4-point differential 5 to 122ms – 2-point differential -
RTB Screw Torque (Cage clamp)	4.4 inch-pounds (0.4Nm)
Module Keying (Backplane)	Electronic
RTB Keying	User defined
Field Wiring Arm and Housing	36 Position RTB (1756-TBCH or TBS6H) ⁽³⁾
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽²⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽⁴⁾ , 5 ⁽⁵⁾
Screwdriver Width for RTB	1/8 inch (3.2mm) maximum

Environmental Conditions																	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)																
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)																
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing																
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz																
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g																
Non-operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g																
Emissions	CISPR 11: Group 1, Class A																
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges																
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz																
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports																
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz																
Enclosure Type Rating	None (open-style)																
Certifications (when product is marked)	<table border="0"> <tr> <td>UL</td> <td>UL Listed Industrial Control Equipment</td> </tr> <tr> <td>CSA</td> <td>CSA Certified Process Control Equipment</td> </tr> <tr> <td>CSA</td> <td>CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations</td> </tr> <tr> <td>FM</td> <td>FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations</td> </tr> <tr> <td>CE⁽⁶⁾</td> <td>European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions</td> </tr> <tr> <td>C-Tick⁽⁶⁾</td> <td>Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions</td> </tr> <tr> <td>EEEx⁽⁶⁾</td> <td>European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)</td> </tr> <tr> <td>TUV</td> <td>TÜV Certified for Functional Safety 1oo2D (AK 1-6, SIL 1-3, according to DIN V 19250 and IEC 61508 respectively)</td> </tr> </table>	UL	UL Listed Industrial Control Equipment	CSA	CSA Certified Process Control Equipment	CSA	CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations	FM	FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations	CE ⁽⁶⁾	European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions	C-Tick ⁽⁶⁾	Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions	EEEx ⁽⁶⁾	European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)	TUV	TÜV Certified for Functional Safety 1oo2D (AK 1-6, SIL 1-3, according to DIN V 19250 and IEC 61508 respectively)
UL	UL Listed Industrial Control Equipment																
CSA	CSA Certified Process Control Equipment																
CSA	CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations																
FM	FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations																
CE ⁽⁶⁾	European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions																
C-Tick ⁽⁶⁾	Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions																
EEEx ⁽⁶⁾	European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)																
TUV	TÜV Certified for Functional Safety 1oo2D (AK 1-6, SIL 1-3, according to DIN V 19250 and IEC 61508 respectively)																

(1) This specification is module filter dependent.
(2) For more information on this specification, see Appendix E.
(3) Maximum wire size requires the extended housing - 1756-TBE.
(4) Use this conductor category information for planning conductor routing as described in the system level installation manual.
(5) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.
(6) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IR6I Specifications

Number of Inputs	6 individually isolated channels
Module Location	1756 ControlLogix Chassis
Backplane Current	250mA @ 5.1V dc & 125mA @ 24V dc
Backplane Power	4.25W
Power Dissipation within Module	4.3W
Thermal Dissipation	14.66 BTU/hr
Input Range	1-487 Ω , 2-1000 Ω , 4-2000 Ω , 8-4020 Ω
Resolution in Ranges 487 Ω (Actual range 0.86 - 507.9 Ω) 1000 Ω (Actual range 2.0 - 1016.5 Ω) 2000 Ω (Actual range 4.0 - 2033.9 Ω) 4020 Ω (Actual range 8.0 - 4068.4 Ω)	Approximately 16 bits across each input range 7.7m Ω /count 15m Ω /count 30m Ω /count 60m Ω /count
Sensors Supported	Resistance 4-4020 Ω 100, 200, 500, 1000 Ω Platinum, alpha=385 100, 200, 500, 1000 Ω Platinum, alpha=3916 120 Ω Nickel, alpha=672 100, 120, 200, 500 Ω Nickel, alpha=618 10 Ω Copper
RTD Excitation Current (All Ranges)	594 μ A
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Open Circuit Detection Time	Negative full scale reading within 5s with any combination of lost wires, except input terminal A alone. If input terminal A is lost by itself, the module reads a positive full scale reading within 5s.
Overvoltage Protection	24V ac/dc maximum
Normal Mode Noise Rejection ⁽¹⁾	60dB at 60Hz
Common Mode Noise Rejection	120dB at 60Hz, 100db at 50Hz
Channel Bandwidth ⁽¹⁾	15Hz
Settling Time to 5% of Full Scale ⁽¹⁾	<80ms
Calibrated Accuracy ⁽²⁾ Typical Worst case	Better than 0.05% of range Better than 0.1% of range
Calibration Interval	12 months
Input Offset Drift with Temperature	10m Ω /°C
Gain Drift with Temperature ⁽²⁾ Typical Worst Case	50 ppm/°C 90 ppm/°C
Module Error over Full Temperature Range ⁽²⁾	0.54% of range
Module Scan Time for all Channels ⁽¹⁾ (Sample Rate)	25ms minimum – Floating point mode (ohms) 50ms minimum – Floating point mode (temperature) 10ms minimum – Integer mode (ohms)
Module Conversion Method	Sigma-Delta
Isolation Voltage Channel to channel User to system	Optoisolated, transformer isolated 100% tested at 1700V dc for 1s, based on 250V ac 100% tested at 1700V dc for 1s, based on 250V ac
Module Keying (Backplane)	Electronic
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
RTB Keying	User defined mechanical keying
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽³⁾
Screwdriver Blade Width for RTB	5/16 inch (8mm) maximum
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽²⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽⁴⁾ , 5 ⁽⁵⁾

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g
Non-Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications: (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁶⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁶⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions EEEx ⁽⁶⁾ European Union 94/9/EC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (Zone 2) TÜV ⁽⁶⁾ TÜV Certified for Functional Safety 1oo2D (AK 1-6, SIL 1-3, according to DIN V 19250 and IEC 61508 respectively)

(1) These specifications are notch filter dependent.

(2) For more information on this specification, see Appendix E.

(3) Maximum wire size will require extended housing - 1756-TBE.

(4) Use this conductor category information for planning conductor routing as described in the system level installation manual.

(5) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

(6) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IT6I Specifications

Number of Inputs	6 individually isolated channels	
Module Location	1756 ControlLogix Chassis	
Backplane Current	250mA @ 5.1V dc & 125mA @ 24V dc	
Backplane Power	4.3W	
Power Dissipation within Module	4.3W	
Thermal Dissipation	14.66 BTU/hr.	
Input Ranges	-12mV to +78mV (1.4 μ V per bit) -12mV to +30mV (0.7 μ V per bit – high resolution range)	
Supported Thermocouple Types	B, E, J, K, R, S, T, N, C	
Thermocouple Linearization	ITS-90	
Resolution	16 bits 1.4 μ V/bit – Typical 0.7 μ V/bit – High resolution range	
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode	
Input Impedance	>10M Ω	
Open Circuit Detection Time	Positive full scale reading within 2s	
Overvoltage Protection	120V ac/dc maximum	
Normal Mode Noise Rejection ⁽¹⁾	60dB at 60Hz	
Common Mode Noise Rejection	120dB at 60Hz 100dB at 50Hz	
Channel Bandwidth ⁽¹⁾	15Hz	
Settling Time to 5% of Full Scale ⁽¹⁾	<80ms	
Module Conversion Method	Sigma-Delta	
Isolation Voltage	Optoisolated, transformer isolated	
Channel to channel	100% tested at 1700V dc for 1s, based on 250V ac	
User to system	100% tested at 1700V dc for 1s, based on 250V ac	
Thermocouple Temp. and Millivolt Input Range	<u>-12 to +78mV range</u>	<u>-12 to +30mV range</u>
Thermocouple Type B	300 to 1820°C (572 to 3308°F)	full range
Thermocouple Type C	0 to 2315°C (32 to 4199°F)	0 to 1725°C (32 to 3137°F)
Thermocouple Type E	-270 to 1000°C (-454 to 1832°F)	-270 to 415°C (-454 to 779°F)
Thermocouple Type J	-210 to 1200°C (-346 to 2192°F)	-210 to 550°C (-346 to 1022°F)
Thermocouple Type K	-270 to 1372°C (-454 to 2502°F)	-270 to 725°C (-454 to 1337°F)
Thermocouple Type N	-270 to 1300°C (-454 to 2372°F)	-270 to 840°C (-454 to 1544°F)
Thermocouple Type R	-50 to 1768°C (-58 to 3215°F)	full range
Thermocouple Type S	-50 to 1768°C (-58 to 3215°F)	full range
Thermocouple Type T	-270 to 400°C (-454 to 752°F)	full range
Thermocouple Resolution Over Nominal Temperature Range	<u>-12 to +78mV range</u>	<u>-12 to +30mV range</u>
Type B, R, S, C	Approx. 0.15°C (Approx. 0.28°F)	Approx. 0.08°C (Approx. 0.15°F)
Type E, J, K, T, N	Approx. 0.05°C (Approx. 0.09°F)	Approx. 0.03°C (Approx. 0.05°F)
Calibrated Accuracy ⁽²⁾	0.05% of full range at 25°C	
Typical	Better than 0.1% of full range at 25°C	
Worst case		
Calibration Interval	12 months	
Accuracy (Cold Junction Sensor)		
Local CJS (RTB)	+/-0.3°C up to +/-3.2°C	
Remote CJS (IFM)	+/-0.3°C	
Input Offset Drift with Temperature	0.5 μ V/°C	
Gain Drift with Temperature ⁽²⁾		
Typical	65 ppm/°C (5.9 μ V/°C for -12 to +78mV range; 2.7 μ V/°C for -12 to +30mV range)	
Worst case	80 ppm/°C (7.2 μ V/°C for -12 to +78mV range; 3.4 μ V/°C for -12 to +30mV range)	
Module Error over Full Temperature Range ⁽²⁾	0.5% of temperature range	
Module Scan Time for all Channels (Sample Rate) ⁽¹⁾	25ms minimum – Floating point mode (millivolt) 50ms minimum – Floating point mode (temperature linearization) 10ms minimum – Integer (millivolt)	
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)	
Module Keying (Backplane)	Electronic	

RTB Keying	User defined
Field Wiring Arm and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽³⁾
Conductors	
Wire Size	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽³⁾ 3/64 inch (1.2mm) insulation maximum
Category	2 ^{(4), (5)}
Screwdriver Width for RTB	5/16 inch (8mm) maximum
Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g
Non-Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900MHz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications: (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁶⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁶⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions EEEx ⁽⁶⁾ European Union 94/9/EC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (Zone 2) TÜV ⁽⁶⁾ TÜV Certified for Functional Safety 1oo2D (AK 1-6, SIL 1-3, according to DIN V 19250 and IEC 61508 respectively)

⁽¹⁾ These specifications are notch filter dependent. Values listed represent 60Hz setting.

⁽²⁾ For more information on this specification, see Appendix E.

⁽³⁾ Maximum wire size requires extended housing – 1756-TBE.

⁽⁴⁾ Use this conductor category information for planning conductor routing as described in the system level installation manual.

⁽⁵⁾ Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

⁽⁶⁾ See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-IT6I2 Specifications

Number of Inputs	6 individually isolated channels	
Module Location	1756 ControlLogix Chassis	
Backplane Current	250mA @ 5.1V dc & 125mA @ 24V dc	
Backplane Power	4.3W	
Power Dissipation within Module	4.3W	
Thermal Dissipation	14.66 BTU/hr.	
Input Ranges	-12mV to +78mV (1.4µV per bit) -12mV to +30mV (0.7µV per bit – high resolution range)	
Supported Thermocouple Types	B, E, J, K, R, S, T, N, C, D, L	
Thermocouple Linearization	ITS-90	
Resolution	16 bits (1.4µV/bit – Typical; 0.7µV/bit – High resolution range)	
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode	
Input Impedance	>10MΩ	
Open Circuit Detection Time	Positive full scale reading within 2s	
Overvoltage Protection	120V ac/dc maximum	
Normal Mode Noise Rejection ⁽¹⁾	60dB at 60Hz	
Common Mode Noise Rejection ⁽²⁾	160dB minimum, tested at 600V ac 60Hz applied with 100 ohms differential resistance	
Channel Bandwidth ⁽¹⁾	15Hz	
Settling Time to 5% of Full Scale ⁽¹⁾	<80ms	
Module Conversion Method	Sigma-Delta	
Isolation Voltage	Optoisolated, transformer isolated	
Channel to channel and User to system	250 V 100% tested at 1900V dc for 2s	
Thermocouple Temp. and Millivolt Input Range	<u>-12 to +78mV range</u>	<u>-12 to +30mV range</u>
Thermocouple Type B	300 to 1820°C (572 to 3308°F)	full range
Thermocouple Type C	0 to 2315°C (32 to 4199°F)	0 to 1725°C (32 to 3137°F)
Thermocouple Type E	-270 to 1000°C (-454 to 1832°F)	-270 to 415°C (-454 to 779°F)
Thermocouple Type J	-210 to 1200°C (-346 to 2192°F)	-210 to 550°C (-346 to 1022°F)
Thermocouple Type K	-270 to 1372°C (-454 to 2502°F)	-270 to 725°C (-454 to 1337°F)
Thermocouple Type N	-270 to 1300°C (-454 to 2372°F)	-270 to 840°C (-454 to 1544°F)
Thermocouple Type R	-50 to 1768°C (-58 to 3215°F)	full range
Thermocouple Type S	-50 to 1768°C (-58 to 3215°F)	full range
Thermocouple Type T	-270 to 400°C (-454 to 752°F)	full range
Thermocouple Type D	0 to 2320°C (32 to 4208°F)	0 to 1718°C (32 to 3124°F)
Thermocouple Type TXK/XK (L)	-200 to 800°C (-328 to 1472°F)	200 to 399°C (392 to 750°F)
Thermocouple Resolution Over Nominal Temperature Range	<u>-12 to +78mV range</u>	<u>-12 to +30mV range</u>
Type B, R, S, C	Approx. 0.15°C (Approx. 0.28°F)	Approx. 0.08°C (Approx. 0.15°F)
Type E, J, K, T, N	Approx. 0.05°C (Approx. 0.09°F)	Approx. 0.03°C (Approx. 0.05°F)
Type D	Approx. 0.07°C (Approx. 0.13°F)	Approx. 0.03°C (Approx. 0.05°F)
Type TXK/XK (L)	Approx. 0.02°C (Approx. 0.04°F)	Approx. 0.01°C (Approx. 0.02°F)
Calibrated Accuracy ⁽³⁾	0.05% of full range at 25°C	
Typical	Better than 0.1% of full range at 25°C	
Worst case		
Calibration Interval	12 months	
Accuracy (Cold Junction Sensor)		
Local or Remote CJC (RTB or IFM)	+/-0.3°C	
Input Offset Drift with Temperature	0.5µV/°C	
Gain Drift with Temperature	25 ppm/°C (2.3µV/°C for -12 to +78mV range; 1.1µV/°C for -12 to +30mV range)	
Module Error over Full Temperature Range ⁽³⁾	0.15% of temperature range	
Module Scan Time for all Channels (Sample Rate) ⁽¹⁾	50ms minimum – Floating point mode (temperature linearization) 10ms minimum – Integer (millivolt)	
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)	

Module Keying (Backplane)	Electronic
RTB Keying	User defined
Field Wiring Arm and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽⁴⁾
Conductors	
Wire Size	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽³⁾ 3/64 inch (1.2mm) insulation maximum
Category	2 ^{(5), (6)}
Screwdriver Width for RTB	5/16 inch (8mm) maximum
Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 30g
Non-Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged Shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 80MHz to 2000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900MHz 10V/m with 200Hz 50% Pulse 100%AM at 1890MHz
EFT/B Immunity	IEC 61000-4-4: +/-2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth(CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Certifications: (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁷⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁷⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions

(1) These specifications are notch filter dependent. Values listed represent 60Hz setting.

(2) 140dB minimum, tested at 600V ac 60Hz applied with 1000 ohms differential resistance.

(3) For more information on this specification, see Appendix E.

(4) Maximum wire size requires extended housing – 1756-TBE.

(5) Use this conductor category information for planning conductor routing as described in the system level installation manual.

(6) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

(7) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-OF4 Specifications

Number of Outputs	4 voltage or current outputs
Module Location	1756 ControlLogix Chassis
Backplane Current	150mA @ 5.1V dc & 120mA @ 24V dc
Backplane Power	5.8W
Power Dissipation within Module	3.2W – 4 channel current
Thermal Dissipation	10.91 BTU/hr.
Output Range	+/- 10.4V 0 to 21mA
Resolution	15 bits across 10.4V - 320 μ V/bit – Voltage 15 bits across 21mA - 650nA/bit – Current
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Open Circuit Detection	Current output only (Output must be set to >0.1mA)
Output Overvoltage Protection	24V dc
Output Short Circuit Protection	Electronically current limited to 21mA or less
Drive Capability	>2000 Ω – Voltage 0-750 Ω – Current
Output Settling Time	<2ms to 95% of final value with resistive loads
Calibrated Accuracy	Better than 0.05% of range from 4mA to 21mA, -10.4V to 10.4V
Calibration Interval	Twelve months
Output Offset Drift with Temperature	50 μ V/ $^{\circ}$ C 100nA/ $^{\circ}$ C
Gain Drift with Temperature	25 ppm/ $^{\circ}$ C – Voltage 520 μ V/ $^{\circ}$ C 50 ppm/ $^{\circ}$ C – Current 1.05 μ A/ $^{\circ}$ C
Module Error over Full Temperature Range ⁽¹⁾	0.15% of range – Voltage 0.3% of range – Current
Module Scan Time for all Channels	12ms minimum – Floating point mode 8ms minimum – Integer
Isolation Voltage User to system	250V 100% tested at 2550V dc for 1 second
Module Conversion Method	R-Ladder DAC, monotonicity with no missing codes
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
Module Keying (Backplane)	Electronic
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽²⁾
Conductors Wire Size	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽¹⁾
Category	3/64 inch (1.2mm) insulation maximum 2 ⁽³⁾ , ⁽⁴⁾
Screwdriver Width for RTB	5/16 inch (8mm) maximum

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): 30g
Non-operating Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth (CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁵⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions EEx ⁽⁵⁾ European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)

(1) For more information on this specification, see Appendix E.

(2) Maximum wire size requires extended housing - 1756-TBE.

(3) Use this conductor category information for planning conductor routing as described in the system level installation manual.

(4) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

(5) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-OF6CI Specifications

Number of Outputs	6 individually isolated channels
Module Location	1756 ControlLogix Chassis
Backplane Current 0-550Ω loads 551-1000Ω loads	250mA @ 5.1V dc & 225mA @ 24V dc (load terminated on OUTs and RTNs) 250mA @ 5.1V dc & 300mA @ 24V dc (load terminated on OUTs and ALTs)
Backplane Power 0-550Ω loads 551-1000Ω loads	6.7W 8.5W
Power Dissipation within Module 0-550Ω loads 551-1000Ω loads	5.5W 6.1W
Thermal Dissipation 0-550Ω loads 551-1000Ω loads	18.76 BTU/hr. 20.80 BTU/hr.
Output Current Range	0 to 21mA
Current Resolution	13 bits across 21mA (2.7μA)
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Open Circuit Detection	None
Output Overvoltage Protection	24V ac/dc maximum
Output Short Circuit Protection	Electronically current limited to 21mA or less
Drive Capability	0-1000Ω Separate field terminations for ranges 0-550Ω or 551-1000Ω
Output Settling Time	<2ms to 95% of final value with resistive loads
Calibrated Accuracy	Better than 0.1% of range from 4mA to 21mA
Calibration Interval	12 months
Output Offset Drift with Temperature	1 μA/°C
Gain Drift with Temperature ⁽¹⁾ Typical Worst case	60 ppm/°C 1.26μA/°C 100 ppm/°C 2.10μA/°C
Module Error over Full Temperature Range ⁽¹⁾	0.6% of range
Minimum Module Scan Time for All Channels	25ms minimum – Floating point mode 10ms minimum – Integer mode
Isolation Voltage Channel to channel User to system	Optoisolated, transformer isolated 100% tested at 1700V dc for 1s, based on 250V ac 100% tested at 1700V dc for 1s, based on 250V ac
Module Conversion Method	R-Ladder DAC, monotonicity with no missing codes
Inductive Load	<1 mH
Module Keying (Backplane)	Electronic
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽²⁾
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽¹⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽³⁾ , 4 ⁽⁴⁾
Screwdriver Width for RTB	5/16 inch (8mm) maximum

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Operating Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): 30g
Non-Operating Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth (CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁵⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions EEx ⁽⁵⁾ European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)

(1) For more information on this specification, see Appendix E.

(2) Maximum wire size will require extended housing - 1756-TBE.

(3) Use this conductor category information for planning conductor routing as described in the system level installation manual.

(4) Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

(5) See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-OF6VI Specifications

Number of Outputs	6 individually isolated channels
Module Location	1756 ControlLogix Chassis
Backplane Current	250mA @ 5.1V dc & 175mA @ 24V dc
Backplane Power	5.5W
Power Dissipation within Module	4.85W
Thermal Dissipation	16.54 BTU/hr
Output Voltage Range	+/- 10.5V maximum
Voltage Resolution	14 bits across 21V (1.3mV) (13 bits across 10.5V +sign bit)
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Output Impedance	<1 Ω
Open Circuit Detection	None
Output Overvoltage Protection	24V ac/dc maximum
Output Short Circuit Protection	Electronically current limited
Drive Capability	$\geq 1000\Omega$ loads, 10mA maximum
Output Settling Time	<2ms to 95% of final value with resistive loads
Calibrated Accuracy ⁽¹⁾	Better than 0.1% of range
Calibration Interval	12 months
Output Offset Drift with Temperature	60 $\mu\text{V}/^\circ\text{C}$
Gain Drift with Temperature ⁽¹⁾ Typical Worst case	50 ppm/ $^\circ\text{C}$ 1.05mV/ $^\circ\text{C}$ 80 ppm/ $^\circ\text{C}$ 1.68mV/ $^\circ\text{C}$
Module Error over Full Temperature Range ⁽¹⁾	0.5% of range
Minimum Module Scan Time for all Channels	25ms minimum – Floating point mode 10ms minimum – Integer mode
Isolation Voltage Channel to channel User to system	Optoisolated, transformer isolated 100% tested at 1700V dc for 1s, based on 250V ac 100% tested at 1700V dc for 1s, based on 250V ac
Module Conversion Method	R-Ladder DAC, monotonicity with no missing codes
Capacitive Load	<1 μF
Module Keying (Backplane)	Electronic
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽²⁾
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽¹⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽³⁾ , (4)
Screwdriver Width for RTB	5/16 inch (8mm) maximum

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC 60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Shock	IEC 60068-2-27 (Test Ea, Unpackaged shock): 30g
Non-Operating Shock	IEC 60068-2-27 (Test Ea, Unpackaged shock): 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth (CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Certifications (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁵⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁵⁾ Australian Radiocommunications Act, compliant with: AS/NZS CISPR 11; Industrial Emissions EEx ⁽⁵⁾ European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n" (zone 2)

⁽¹⁾ For more information on this specification, see Appendix E.

⁽²⁾ Maximum wire size will require extended housing - 1756-TBE.

⁽³⁾ Use this conductor category information for planning conductor routing as described in the system level installation manual.

⁽⁴⁾ Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

⁽⁵⁾ See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

1756-OF8 Specifications

Number of Outputs	8 voltage or current outputs
Module Location	1756 ControlLogix Chassis
Backplane Current	150mA @ 5.1V dc & 210mA @ 24V dc
Backplane Power	5.8W
Power Dissipation within Module	4.92W - 8 channel current
Thermal Dissipation	16.78 BTU/hr.
Output Range	+/- 10.4V 0 to 21mA
Resolution	15 bits across 10.4V - 320 μ V/bit – Voltage 15 bits across 21mA - 650nA/bit – Current
Data Format	Left justified, 2s complement – Integer mode IEEE 32 bit – Floating point mode
Open Circuit Detection	Current output only (Output must be set to >0.1mA)
Output Overvoltage Protection	24V dc
Output Short Circuit Protection	Electronically current limited to 21mA or less
Drive Capability	>2000 Ω – Voltage 0-750 Ω – Current
Output Settling Time	<2ms to 95% of final value with resistive loads
Calibrated Accuracy ⁽¹⁾	Better than 0.05% of range from 4mA to 21mA, -10.4V to 10.4V
Calibration Interval	Twelve months – Typical
Output Offset Drift with Temperature	50 μ V/ $^{\circ}$ C – Voltage 100nA/ $^{\circ}$ C – Current
Gain Drift with Temperature	25 ppm/ $^{\circ}$ C – Voltage 520 μ V/ $^{\circ}$ C 50 ppm/ $^{\circ}$ C – Current 1.05 μ A/ $^{\circ}$ C
Module Error over Full Temperature Range ⁽¹⁾	0.15% of range – Voltage 0.3% of range – Current
Module Scan Time for all Channels	12ms minimum – Floating point mode 8ms minimum – Integer
Isolation Voltage User to system	250V 100% tested at 2550V dc for 1 second
Module Conversion Method	R-Ladder DAC, monotonicity with no missing codes
RTB Screw Torque (NEMA)	7-9 inch-pounds (0.8-1Nm)
Module Keying (Backplane)	Electronic
RTB Keying	User defined
RTB and Housing	20 Position RTB (1756-TBNH or TBSH) ⁽²⁾

Environmental Conditions	
Operating Temperature	IEC 60068-2-1 (Test Ad, Operating Cold), IEC 60068-2-2 (Test Bd, Operating Dry Heat), IEC 60068-2-14 (Test Nb, Operating Thermal Shock): 0 to 60°C (32 to 140°F)
Storage Temperature	IEC 60068-2-1 (Test Ab, Un-packaged Non-operating Cold), IEC 60068-2-2 (Test Bb, Un-packaged Non-operating Dry Heat), IEC 60068-2-14 (Test Na, Un-packaged Non-operating Thermal Shock): -40 to 85°C (-40 to 185°F)
Relative Humidity	IEC 60068-2-30 (Test Db, Un-packaged Non-operating Damp Heat): 5 to 95% non-condensing
Vibration	IEC60068-2-6 (Test Fc, Operating): 2g @ 10-500Hz
Shock	IEC60068-2-27 (Test Ea, Unpackaged shock): Operating 30g Non-operating 50g
Emissions	CISPR 11: Group 1, Class A
ESD Immunity	IEC 61000-4-2: 6kV contact discharges 8kV air discharges
Radiated RF Immunity	IEC 61000-4-3: 10V/m with 1kHz sine-wave 80%AM from 30MHz to 1000MHz 10V/m with 200Hz 50% Pulse 100%AM at 900Mhz
EFT/B Immunity	IEC 61000-4-4: ±2kV at 5kHz on signal ports
Surge Transient Immunity	IEC 61000-4-5: ±2kV line-earth (CM) on shielded ports
Conducted RF Immunity	IEC 61000-4-6: 10Vrms with 1kHz sine-wave 80%AM from 150kHz to 80MHz
Enclosure Type Rating	None (open-style)
Conductors Wire Size Category	#22 to #14 AWG (0.324 to 2.08 sq. mm) stranded ⁽¹⁾ 3/64 inch (1.2mm) insulation maximum 2 ⁽³⁾ , 4 ⁽⁴⁾
Screwdriver Width for RTB	5/16 inch (8mm) maximum
Certifications (when product is marked)	UL UL Listed Industrial Control Equipment CSA CSA Certified Process Control Equipment CSA CSA Certified Process Control Equipment for Class I, Division 2 Group A,B,C,D Hazardous Locations FM FM Approved Equipment for use in Class I Division 2 Group A,B,C,D Hazardous Locations CE ⁽⁵⁾ European Union 89/336/EEC EMC Directive, compliant with: EN 50082-2; Industrial Immunity EN 61326; Meas./Control/Lab., Industrial Requirements EN 61000-6-2; Industrial Immunity EN 61000-6-4; Industrial Emissions C-Tick ⁽⁴⁾ Australian Radiocommunications Act, compliant with: AS/NZS 2064; Industrial Emissions EEx ⁽⁴⁾ European Union 94/9/EEC ATEX Directive, compliant with: EN 50021; Potentially Explosive Atmospheres, Protection "n"

⁽¹⁾ For more information on this specification, see Appendix E.

⁽²⁾ Maximum wire size requires extended housing - 1756-TBE.

⁽³⁾ Use this conductor category information for planning conductor routing as described in the system level installation manual.

⁽⁴⁾ Refer to publication 1770-4.1 *Industrial Automation Wiring and Grounding Guidelines*.

⁽⁵⁾ See the Product Certification link at www.ab.com for Declarations of Conformity, Certificates, and other certification details.

Notes:

Tag Definitions

Communications Mode Tag Names and Definitions

The set of tags associated with any module depends on the module type and the communications format. For each operational mode, integer or floating point, there are three sets of tags:

- input
- output
- configuration.

Integer Mode Tags

Table B.1, Table B.2 and Table B.3 list the tags that are available on ControlLogix analog modules operating in integer mode.

IMPORTANT

Each application's series of tags varies but no input module application contains any tags that are not listed here.

Integer Input Tags

Table B.1 Integer Input Tags

Tag Name	Data Type	Applicable Modules	Definition:
ChannelFaults	INT	All	Collection of individual channel fault bits in one word. Can address individual channel fault via bit notation: ex. ChannelFaults 3 for channel 3
Ch0Fault	BOOL	All	Individual channel fault status bit. Indicates a "hard" fault has occurred on the channel which means: calibration is ongoing; or if an input, an overrange or underrange condition is present; or if an output, a low or high clamp condition is occurring. These bits are also set by the controller if communications are lost with the I/O module.
ModuleFaults	INT	All	Collection of all module level fault bits
AnalogGroupFault	BOOL	All	Indicates if a channel fault has occurred on any channel
InGroupFault	BOOL	All inputs	Indicates if a channel fault has occurred on any input channel
Calibrating	BOOL	All	Indicates if a calibration is currently in progress on any channel
CalFault	BOOL	All	Status bit indicating if any channel has a "bad" calibration. "Bad" calibration means the last attempt to calibrate the channel failed with an error
CJUnderrange	BOOL	1756-IT6I and 1756-IT6I2	Status bit to indicate if the Cold Junction reading is currently beneath the lowest detectable temperature of 0.0 degrees Celsius

Table B.1 Integer Input Tags

Tag Name	Data Type	Applicable Modules	Definition:
CJOvrerrange	BOOL	1756-IT6I and 1756-IT6I2	Status bit to indicate if the Cold Junction reading is currently above the highest detectable temperature of 86.0 degrees Celsius
ChannelStatus	INT	All	Collection of individual channel status bits
Ch0Underrange	BOOL	All inputs	Alarm bits indicating the channel's input is less than the minimum detectable input signal
Ch0Ovrerrange	BOOL	All inputs	Alarms bit indicating the channel's input is greater than the maximum detectable input signal
Ch0Data	INT	All inputs	The channel input signal represented in counts where -32,768 counts is the minimum detectable input signal and 32,767 counts is the maximum detectable
CJData	INT	1756-IT6I and 1756-IT6I2	The cold junction sensor temperature in counts where -32,768 counts is 0 degree Celsius and 32,767 counts is 86 degrees Celsius
CSTTimestamp	Array of DINT	All (if the CST connection is selected)	Timestamp taken at time the input data was sampled, or if an output when the output was applied, and placed in terms of Coordinated System Time which is a 64 bit quantity in microseconds coordinated across the rack. Must be addressed in 32 bit chunks as an array
RollingTimestamp	INT	All	Timestamp taken at time the input data was sampled, or if an output when the output was applied, which is in terms of milliseconds relative solely to the individual module

*Integer Output Tags.***Table B.2 Integer Output Tags**

Tag Name	Data Type	Applicable Modules	Definition:
Ch0Data	INT	All outputs	The value the channel is to output in counts where the minimum producible output is -32,768 counts and 32,767 counts is the maximum producible
Ch0DataEcho	INT	All outputs	The value the channel is currently outputting in counts where -32,768 counts is the minimum producible output signal and 32,767 counts is the maximum producible
OutGroupFault	BOOL	All outputs	Indicates if a channel fault has occurred on any output channel
Ch0InHold	BOOL	All outputs	Bit which indicates if the output channel is currently holding until the Output value sent to the module (O tag Ch0Data) matches the current output value (I tag Ch0Data) within 0.1% of the channel's full scale

*Integer Configuration Tags***Table B.3 Integer Configuration Tags**

Tag Name	Data Type	Applicable Modules	Definition
CJDisable	BOOL	All inputs (only used for the 1756-IT6I and 1756-IT6I2)	Disables the cold junction sensor which turns off cold junction compensation when linearizing thermocouple inputs
RealTimeSample	INT	All input	Determines how often the input signal is to be sampled in terms of milliseconds
ChORangeNotch	SINT	1756-IF6CIS, 1756-IF6I, 1756-IR6I, 1756-IT6I and 1756-IT6I2	<p>Configures the channel's input range and notch filter settings. The input range is the upper nibble (bits 4-7) and determines the signal range the input channel can detect. Input range values are as follows:</p> <p>0 = -10 to 10V (1756-IF6I) 1 = 0 to 5V (1756-IF6I) 2 = 0 to 10V (1756-IF6I) 3 = 0 to 20mA (1756-IF6CIS and 1756-IF6I) 4 = -12 to 78mV (1756-IT6I and 1756-IT6I2) 5 = -12 to 30mV (1756-IT6I and 1756-IT6I2) 6 = 1 to 487Ω (1756-IR6I) 7 = 2 to 1,000Ω (1756-IR6I) 8 = 4 to 2,000Ω (1756-IR6I) 9 = 8 to 4,020Ω (1756-IR6I)</p> <p>The notch filter provides superior frequency filtering at the selected value and its harmonics. The notch filter is the lowest nibble (bits 0-3)</p> <p>0 = 10Hz 1 = 50Hz 2 = 60Hz 3 = 100Hz 4 = 250Hz 5 = 1,000Hz</p>
ProgToFaultEn	BOOL	All outputs	The program to fault enable bit determines how the outputs should behave if a communications fault were to occur while the output module is in the program mode. When set the bit will cause the outputs to transition to their programmed fault state if a communications fault occurs while in the program state. If not set, outputs will remain in their configured program state despite a communications fault occurring
ChOConfig	SINT	All outputs	Contains all individual configuration bits for channel

Table B.3 Integer Configuration Tags

Tag Name	Data Type	Applicable Modules	Definition
Ch0HoldForInit	BOOL	All outputs	When set configures the channel to hold, or not change, until initialized with a value within 0.1% of full scale of its current value when one of the following conditions occurs: 1 = Module initial connection (power up) 2 = Module transition from Program mode back to Run mode 3 = Module reestablishes communications after fault
Ch0Fault Mode	BOOL	All outputs	Selects the behavior the output channel should take if a communications fault were to occur. Either hold last state (0) or go to a user defined value (1). Ch0FaultValue defines the value to go to on fault if the bit is set
Ch0ProgMode	BOOL	All outputs	Selects the behavior the output channel when transitioned into Program mode. Either hold last state (0) or go to a user defined value (1). Ch0ProgValue defines the value to go to on fault if the bit is set
Ch0RampToProg	BOOL	All outputs	Enables ramping of the output value to a user defined program value, Ch0ProgValue, when set. Ramping defines the maximum rate the output is allowed to transition at based upon the configured Ch0RampRate
Ch0RampToFault	BOOL	All outputs	Enables ramping of the output value to a user defined fault value, Ch0FaultValue, when set. Ramping defines the maximum rate the output is allowed to transition at based upon the configured Ch0RampRate
Ch0FaultValue	INT	All outputs	Defines the value, in counts, the output should take on if a communications fault occurs when the Ch0FaultMode bit is set
Ch0ProgValue	INT	All outputs	Defines the value, in counts, the output should take on when the connection transitions to Program mode if the Ch0ProgMode bit is set
Ch0RampRate	INT	All outputs	Configures the maximum rate at which the output value may change when transitioning to either the Ch0FaultValue or Ch0ProgValue if either the Ch0RampToFault or Ch0RampToProg bits are set respectively. In terms of percent full-scale per second

Floating Point Mode Tags

Table B.4, Table B.5 and Table B.3 list the tags that are available on ControlLogix analog modules operating in floating point mode.

IMPORTANT

Each application's series of tags varies but no input module application contains any tags that are not listed here.

Floating Point Input Tags

Table B.4 Floating Point Input Tags

Tag Name	Data Type	Applicable Modules	Definition:
ChannelFaults	INT	All	Collection of individual channel fault bits in one word. Can address individual channel fault via bit notation: ex. ChannelFaults 3 for channel 3
Ch0Fault	BOOL	All	Individual channel fault status bit. Indicates a "hard" fault has occurred on the channel which means: calibration is ongoing; or if an input, an overrange or underrange condition is present; or if an output, a low or high clamp condition is occurring. These bits are also set by the controller if communications are lost with the I/O module.
ModuleFaults	INT	All	Collection of all module level fault bits
AnalogGroupFault	BOOL	All	Indicates if a channel fault has occurred on any channel
InGroupFault	BOOL	All inputs	Indicates if a channel fault has occurred on any input channel
Calibrating	BOOL	All	Indicates if a calibration is currently in progress on any channel
CalFault	BOOL	All	Status bit indicating if any channel has a "bad" calibration. "Bad" calibration means the last attempt to calibrate the channel failed with an error and was aborted
CJUnderrange	BOOL	1756-IT6I and 1756-IT6I2	Status bit to indicate if the Cold Junction reading is currently beneath the lowest detectable temperature of 0.0 degrees Celsius
CJOverrange	BOOL	1756-IT6I and 1756-IT6I2	Status bit to indicate if the Cold Junction reading is currently above the highest detectable temperature of 86.0 degrees Celsius
Ch0Status	INT	All	Collection of individual channel status bits
Ch0CalFault	BOOL	All inputs	Status bit indicating if the channel has a "bad" calibration. "Bad" calibration means the last attempt to calibrate the channel failed with an error and was aborted
Ch0Underrange	BOOL	All inputs	Alarm bits indicating the channel's input is less than the minimum detectable input signal

Table B.4 Floating Point Input Tags

Tag Name	Data Type	Applicable Modules	Definition:
Ch0Ovrerrange	BOOL	All inputs	Alarms bit indicating the channel's input is greater than the maximum detectable input signal
Ch0RateAlarm	BOOL	All inputs	Alarm bit which sets when the input channel's rate of change exceeds the configured Ch0ConfigRateAlarmLimit. Remains set until the rate change drops below the configured limit unless latched via Ch0ConfigRateAlarmLatch in the configuration
Ch0LAlarm	BOOL	All inputs	Low alarm bits which sets when the input signal moves beneath the configured low alarm trigger point, Ch0ConfigLAlarmLimit. Remains set until the input signal moves above the trigger point, unless latched via Ch0ConfigProcAlarmLatch or the input is still within the configured alarm deadband, Ch0ConfigAlmDeadband, of the low alarm trigger point
Ch0HAlarm	BOOL	All inputs	High alarm bit which sets when the input signal moves above the configured high alarm trigger point, Ch0ConfigHAlarmLimit. Remains set until the input signal moves below the trigger point, unless latched via Ch0ConfigProcAlarmLatch or the input is still within the configured alarm deadband, Ch0ConfigAlmDeadband, of the high alarm trigger point
Ch0LLAlarm	BOOL	All inputs	Low low alarm bit which sets when the input signal moves beneath the configured low low alarm trigger point, Ch0ConfigLLAlarmLimit. Remains set until the input signal moves above the trigger point, unless latched via Ch0ConfigProcAlarmLatch or the input is still within the configured alarm deadband, Ch0ConfigAlmDeadband, of the low low alarm trigger point
Ch0HHAAlarm	BOOL	All inputs	High high alarm bit which sets when the input signal moves above the configured high high alarm trigger point, Ch0ConfigProcAlarmLimit. Remains set until the input signal moves below the trigger point, unless latched via Ch0ConfigAlmDeadband, of the high high alarm trigger point
Ch0Data	REAL	All inputs	The channel input signal represented in engineering units. The input signal is measured and then scaled based on the user configuration
CJData	REAL	1756-IT6I and 1756-IT6I2	The cold junction sensor temperature in degrees Celsius or Fahrenheit
CSTTimestamp	Array of DINT	All (if the CST connection is selected)	Timestamp taken at time the input data was sampled, or if an output when the output was applied, and placed in terms of Coordinated System Time which is a 64 bit quantity in microseconds coordinated across the rack. Must be addressed in 32 bit chunks as an array
RollingTimestamp	INT	All inputs	Timestamp taken at time the input data was sampled, or if an output when the output was applied, which is in terms of milliseconds relative solely to the individual module

*Floating Point Output Tags***Table B.5 Floating Point Output Tags**

Tag Name	Data Type	Applicable Modules	Definition:
Ch0Data	REAL	All outputs	The value the channel is set to output in engineering units based upon the configured scaling for the channel
Ch0DataEcho	REAL	All outputs	The value the channel is currently outputting in engineering units based upon the configured user scaling. Will match the requested output value, 0 tag Ch0Data, unless: in Program mode, calibrating, beneath Low Limit, above High Limit, currently ramping or In Hold
OutGroupFault	BOOL	All outputs	Indicates if a channel fault has occurred on any output channel
Ch0NotANumber	BOOL	All outputs	Bit indicating the received output value from the controller, 0 tag Ch0Data, was an invalid IEEE floating point value. When an invalid value is received, the output value holds its last known valid state
Ch0InHold	BOOL	All outputs	Bit which indicates if the output channel is currently holding until the Output value sent to the module (0 tag Ch0Data) matches the current output value (1 tag Ch0Data) within 0.1% of the channel's full scale
Ch0RampAlarm	BOOL	All outputs	Alarm bit which sets when the requested output value, Ch0ConfigRampToRun set, and the difference between the new output value requested and the current output exceeds the configured ramp limit, Ch0ConfigMaxRampRate. The bit will remain set until ramping ceases unless the alarm is latched via Ch0ConfigRampAlarmLatch
Ch0LLimitAlarm	BOOL	All outputs	Alarm bit which sets when the requested output value, Ch0Data, is below the configured low limit, Ch0ConfigLowLimit, in which case the output will stop at the configured low limit which the echo will reflect. Remains set until the requested output moves above the low limit unless latched by Ch0ConfigLimitAlarmLatch
Ch0HLimitAlarm	BOOL	All outputs	Alarm bit which sets when the requested output value, Ch0Data, is above the configured high limit, Ch0ConfigHighLimit, in which case the output will stop at the configured high limit which the echo will reflect. Remains set until the requested output moves below the high limit unless latched by Ch0ConfigLimitAlarmLatch

Floating Point Configuration Tags

Table B.6 Floating Point Configuration Tags

Tag Name	Data Type	Applicable Modules	Definition
RemoteTermination	BOOL	1756-IT6I and 1756-IT6I2	Indicates if the cold junction sensor is mounted on a remote termination block when set, rather than on the local terminal block. Needed for proper cold junction compensation when linearizing thermocouples
CJDisable	BOOL	1756-IT6I and 1756-IT6I2	Disables the cold junction sensor which turns off cold junction compensation when linearizing thermocouple inputs
TempMode	BOOL	1756-IR6I, 1756-IT6I and 1756-IT6I2	Controls the temperature scale to use on the module: 0 = Celsius 1 = Fahrenheit
ProgToFaultEn	BOOL	All outputs	The program to fault enable bit determines how the outputs should behave if a communications fault were to occur while the output module is in the program mode. When set, the bit will cause the outputs to transition to their programmed fault state if a communications fault occurs while in the program state. If not set, outputs will remain in their configured program state despite a communications fault occurring
RealTimeSample	INT	All input	Determines how often the input signal is to be sampled in terms of milliseconds
CJOffset	REAL	1756-IT6I and 1756-IT6I2	Provides a user selected offset to add into the read cold junction sensor value. Allows a sensor with a built in bias to be compensated for
Ch0Config	Struct	All	Master structure beneath which the channel's configuration parameters are set.

Table B.6 Floating Point Configuration Tags

Tag Name	Data Type	Applicable Modules	Definition
Ch0ConfigRangeTypeNotch	INT	1756-IF6CIS, 1756-IF6I, 1756-IR6I, 1756-IT6I and 1756-IT6I2	<p>Configures the channel's input range, sensor type and notch filter settings. The input range is bits 8-11 and determines the signal range the input channel can detect. Input range values are as follows:</p> <p>0 = -10 to 10V (1756-IF6I) 1 = 0 to 5V (1756-IF6I) 2 = 0 to 10V (1756-IF6I) 3 = 0 to 20mA (1756-IF6CIS and 1756-IF6I) 4 = -12 to 78mV (1756-IT6I and 1756-IT6I2) 5 = -12 to 30mV (1756-IT6I and 1756-IT6I2) 6 = 1 to 487Ω (1756-IR6I) 7 = 2 to 1,000Ω (1756-IR6I) 8 = 4 to 2,000Ω (1756-IR6I) 9 = 8 to 4,020Ω (1756-IR6I)</p> <p>Sensor type is bits 4-7 and selects the sensor type to use for linearization on the 1756-IR6I, IT6I. Sensor types values are as follows:</p> <p>0 = no linearization, Ω (1756-IR6I), mV (1756-IT6I and 1756-IT6I2) 1 = 100Ω Platinum 385 (1756-IR6I) B (1756-IT6I and 1756-IT6I2) 2 = 200Ω Platinum 385 (1756-IR6I), C (1756-IT6I and 1756-IT6I2) 3 = 500Ω Platinum 385 (1756-IR6I), E (1756-IT6I and 1756-IT6I2) 4 = 1000Ω Platinum 385 (1756-IR6I), J (1756-IT6I and 1756-IT6I2) 5 = 100Ω Platinum 3916 (1756-IR6I), K (1756-IT6I and 1756-IT6I2) 6 = 200Ω Platinum 3916 (1756-IR6I), N (1756-IT6I and 1756-IT6I2) 7 = 500Ω Platinum 3916 (1756-IR6I), R (1756-IT6I and 1756-IT6I2) 8 = 1000Ω Platinum 3916 (1756-IR6I), S (1756-IT6I and 1756-IT6I2) 9 = 10Ω Copper 427 (1756-IR6I), T (1756-IT6I and 1756-IT6I2) 10 = 120Ω Nickel 672 (1756-IR6I), TXK/XK (L) (1756-IT6I2) 11 = 100Ω Nickel 618 (1756-IR6I), D (1756-IT6I2) 12 = 120Ω Nickel 618 (1756-IR6I) 13 = 200Ω Nickel 618 (1756-IR6I) 14 = 500Ω Nickel 618 (1756-IR6I)</p> <p>The notch filter provides superior frequency filtering at the selected value and its harmonics. The notch filter is the lower nibble (bits 0-3)</p> <p>0 = 10Hz 1 = 50Hz 2 = 60Hz 3 = 100Hz 4 = 250Hz 5 = 1,000Hz</p>
Ch0ConfigAlarmDisable	BOOL	All	Disables all alarms for the channel
Ch0ConfigProcessAlarmLatch	BOOL	All inputs	Enables latching for all four process alarms: low, low low, high and high high. Latching causes the process alarm to remain set until an unlatch service is explicitly sent to the channel or alarm
Ch0ConfigRateAlarmLatch	BOOL	All inputs	Enables latching for the rate alarm. Latching causes the rate alarm to remain set until an unlatch service is explicitly sent to the channel or alarm
Ch0ConfigDigitalFilter	INT	All inputs	A non-zero value enables the filter, providing a time constant in milliseconds used in a first order lag filter to smooth the input signal

Table B.6 Floating Point Configuration Tags

Tag Name	Data Type	Applicable Modules	Definition
Ch0ConfigTenOhm Offset	INT	1756-IR6I	A value from -100 to 100 which represents -1.00 to 1.00Ω and is an offset used when linearizing a 10Ω copper sensor type's input
Ch0ConfigRate AlarmLimit	INT	All inputs	The trigger point for the rate alarm status bit which will set if the input signal changes at a rate faster than the configured rate alarm. Configured in percent full scale per second
Ch0ConfigLow Signal	REAL	All	One of four points used in scaling. The low signal is in terms of the inputs signal units and corresponds to the low engineering term when scaled. The scaling equation is as follows: $\text{Data} = \frac{(\text{Signal} - \text{Low Signal}) \times (\text{High Engineering} - \text{Low Engineering})}{(\text{High Signal} - \text{Low Signal})} + \text{LowEngineering}$
Ch0ConfigHigh Signal	REAL	All	One of four points used in scaling. The high signal is in terms of the inputs signal units and corresponds to the high engineering term when scaled. The scaling equation is as follows: $\text{Data} = \frac{(\text{Signal} - \text{Low Signal}) \times (\text{High Engineering} - \text{Low Engineering})}{(\text{High Signal} - \text{Low Signal})} + \text{LowEngineering}$
Ch0ConfigLow Engineering	REAL	All	One of four points used in scaling. The low engineering helps determine the engineering units the signal values scale into. The low engineering term corresponds to the low signal value. The scaling equation used is: $\text{Data} = \frac{(\text{Signal} - \text{Low Signal}) \times (\text{High Engineering} - \text{Low Engineering})}{(\text{High Signal} - \text{Low Signal})} + \text{LowEngineering}$
COConfigHigh Engineering	REAL	All	One of four points used in scaling. The high engineering helps determine the engineering units the signal values scale into. The high engineering term corresponds to the high signal value. The scaling equation used is: $\text{Data} = \frac{(\text{Signal} - \text{Low Signal}) \times (\text{High Engineering} - \text{Low Engineering})}{(\text{High Signal} - \text{Low Signal})} + \text{LowEngineering}$
Ch0ConfigLAlarm Limit	REAL	All inputs	The low alarm trigger point. Causes the Ch0LAlarm to trigger when the input signal moves beneath the configured trigger point. In terms of engineering units
Ch0ConfigHAlarm Limit	REAL	All inputs	The high alarm trigger point. Causes the Ch0HAlarm to trigger when the input signal moves above the configured trigger point. In terms of engineering units
Ch0ConfigLLAlarm Limit	REAL	All inputs	The low low alarm trigger point. Causes the Ch0LLAlarm to trigger when the input signal moves beneath the configured trigger point. In terms of engineering units
Ch0ConfigHH AlarmLimit	REAL	All inputs	The high high alarm trigger point. Causes the Ch0HHAAlarm to trigger when the input signal moves above the configured trigger point. In terms of engineering units
Ch0ConfigAlarm Deadband	REAL	All inputs	Forms a deadband around the process alarms which causes the corresponding process alarm status bit to remain set until the input moves beyond the trigger point by greater than the amount of the alarm deadband
Ch0ConfigCalBias	REAL	All inputs	A user configurable offset added directly into the data, Ch0Data. used to compensate for inherent sensor offset
Ch0ConfigConfig Bits	INT	All outputs	Collection of channel's individual configuration bits

Table B.6 Floating Point Configuration Tags

Tag Name	Data Type	Applicable Modules	Definition
Ch0ConfigHoldForInit	BOOL	All outputs	When set configures the channel to hold, or not change, until initialized with a value within 0.1% of full scale of its current value when one of the following conditions occurs: 1 = Module initial connection (power up) 2 = Module transition from Program mode back to Run mode 3 = Module reestablishes communications after fault
Ch0ConfigRamp AlarmLatch	BOOL	All outputs	Enables latching for the rate alarm. Latching causes the rate alarm to remain set until an unlatch service is explicitly sent to the channel or alarm
Ch0ConfigLimit AlarmLatch	BOOL	All outputs	Enables latching for the clamp limit alarms. Latching causes the limit alarms to remain set until an unlatch service is explicitly sent to the channel or alarm
Ch0ConfigFault Mode	BOOL	All outputs	Selects the behavior the output channel should take if a communications fault were to occur. Either hold last state (0) or go to a user defined value (1). Ch0ConfigFaultValue defines the value to go to on fault if the bit is set
Ch0ConfigProg Mode	BOOL	All outputs	Selects the behavior the output channel when transitioned into Program mode. Either hold last state (0) or go to a user defined value (1). Ch0ConfigProgValue defines the value to go to on program if the bit is set
Ch0ConfigRampTo Run	BOOL	All outputs	Enables ramping of the output value during Run mode between the current output level and a newly requested output. Ramping defines the maximum rate the output is allowed to transition at based upon the configured Ch0ConfigRampRate
Ch0ConfigRampToProg	BOOL	All outputs	Enables ramping of the output value to a user defined program value, Ch0ConfigProgValue, when set. Ramping defines the maximum rate the output is allowed to transition at based upon the configured Ch0ConfigRampRate
Ch0ConfigRampToFault	BOOL	All outputs	Enables ramping of the output value to a user defined fault value, Ch0FaultValue, when set. Ramping defines the maximum rate the output is allowed to transition at based upon the configured Ch0ConfigRampRate
Ch0ConfigMax RampRate	INT	All outputs	Configures the maximum rate at which the output value may change when transitioning to either the Ch0ConfigFaultValue or Ch0ConfigProgValue if either the Ch0ConfigRampToFault or Ch0ConfigRampToProg bits are set respectively, or in Run mode if Ch0ConfigRampToRun is set. In terms of percent full-scale per second
Ch0ConfigFault Value	REAL	All outputs	Defines the value, in engineering terms, the output should take on if a communications fault occurs when the Ch0ConfigFaultMode bit is set
Ch0ConfigProg Value	REAL	All outputs	Defines the value, in engineering units, the output should take on when the connection transitions to Program mode if the Ch0ConfigProgMode bit is set
Ch0ConfigLow Limit	REAL	All outputs	Defines the minimum value the output is allowed to take on within the process. If an output beneath the low limit is requested, the Ch0LLimit alarm is set and the output signal will remain at the configured low limit
Ch0ConfigHigh Limit	REAL	All outputs	Defines the maximum value the output is allowed to take on within the process. If an output above the high limit is requested, the Ch0HLimit alarm is set and the output signal will remain at the configured high limit

Notes:

Using Ladder Logic To Perform Run Time Services and Reconfiguration

You can use ladder logic to perform run time services on your module. For example, page 10-10 shows how to unlatch alarms on the 1756-IF6I module using RSLogix 5000. This appendix provides an example of how to unlatch those same alarms **without using RSLogix 5000**.

In addition to performing run time services, you can use ladder logic to change configuration. Chapter 10 explained how to use the RSLogix 5000 software to set configuration parameters in your ControlLogix analog I/O module. Some of those parameters may also be changed through ladder logic.

Using Message Instructions

In ladder logic, you can use message instructions to send occasional services to any ControlLogix I/O module. Message instructions send an explicit service to the module, causing specific behavior to occur, for example, unlatching a high alarm.

Message instructions maintain the following characteristics:

- messages use unscheduled portions of system communications bandwidth
- one service is performed per instruction
- performing module services does not impede module functionality, such as sampling inputs or applying new outputs

Processing Real-Time Control and Module Services

Services sent via message instructions are not as time critical as the module behavior defined during configuration and maintained by a real-time connection. Therefore, the module processes messaging services only after the needs of the I/O connection have been met.

For example, you may want to unlatch all process alarms on the module, but real-time control of your process is still occurring using the input value from that same channel. Because the input value is critical to your application, the module prioritizes the sampling of inputs ahead of the unlatch service request.

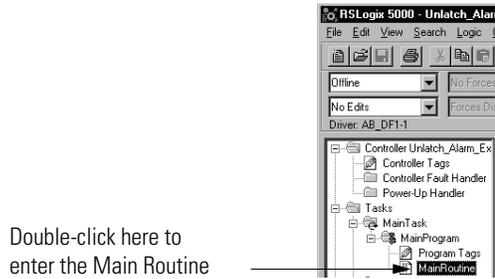
This prioritization allows input channels to be sampled at the same frequency and the process alarms to be unlatched in the time between sampling and producing the real-time input data.

One Service Performed Per Instruction

Message instructions will only cause a module service to be performed once per execution. For example, if a message instruction sends a service to the module to unlatch the high high alarm on a particular channel, that channel's high high alarm will unlatch, but may be set on a subsequent channel sample. The message instruction must then be reexecuted to unlatch the alarm a second time.

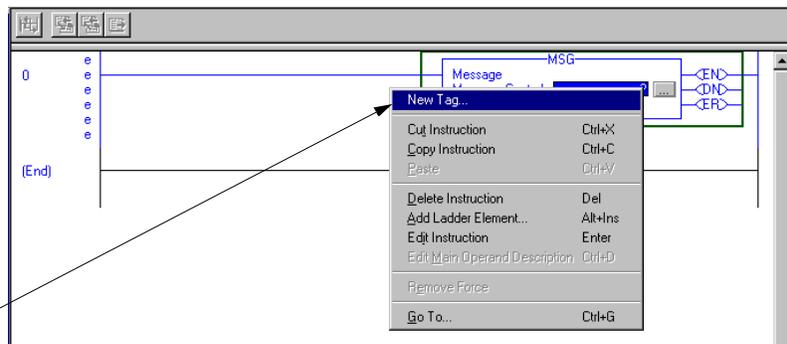
Creating a New Tag

This ladder logic is written in the Main Routine.



After adding a message instruction to a rung, you must create a tag for the message instruction

- A. Right-click on the question mark (?) to see this pull-down menu.
- B. Click on New Tag.

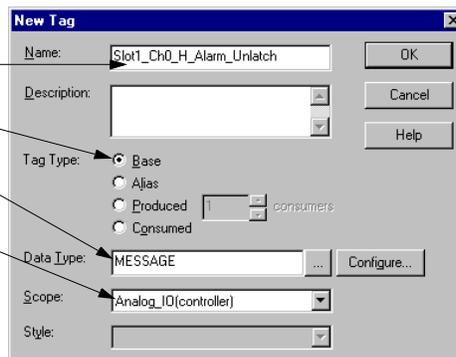


You must fill in the following information on the New Tag pop-up:

IMPORTANT

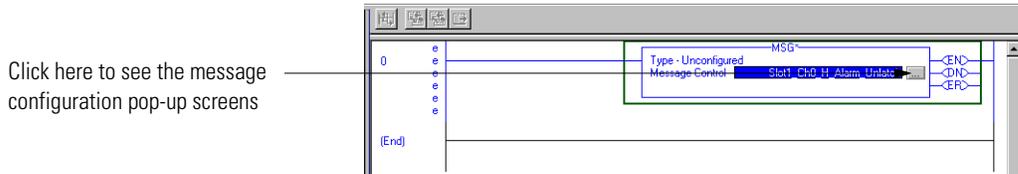
We suggest you name the tag to indicate what module service is sent by the message instruction. For example, the message instruction below is used to unlatch a high alarm, and the tag is named to reflect this.

- A. Name the tag.
 - B. Choose the Base tag type.
 - C. Choose the Message data type.
 - D. Choose the Controller scope.
- IMPORTANT:** Message tags can only be created with the Controller Scope.



Enter Message Configuration

After creating a new tag, you must enter message configuration.



Enter message configuration on the following screens:

- Configuration pop-up screen
- Communications pop-up screen

A description of the purpose and set-up of each screen follows.

IMPORTANT

In RSLogix 5000, version 10 and greater, the message configuration screens changed significantly to make it easier for you to configure your messages.

For example, **in version 9 and earlier**, depending on the Message Type, you are required to configure some combination of the following:

- Service Code
- Object Type
- Object ID
- Object Attribute
- Source
- Number of Elements
- Destination

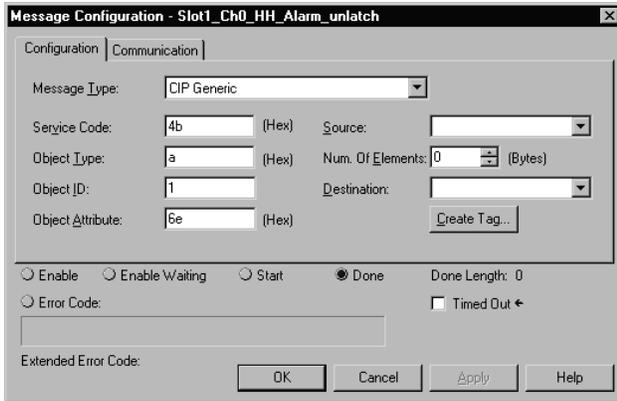
In **version 10 and greater**, however, you are only required to choose a Service Type. RSLogix 5000 fills in most of the fields listed above. You are only required to configure the Instance field; Instance represents the module channel on which the service is performed, if appropriate

The following sections show how to configure messages with RSLogix 5000, versions 9 and earlier and RSLogix 5000, versions 10 and greater.

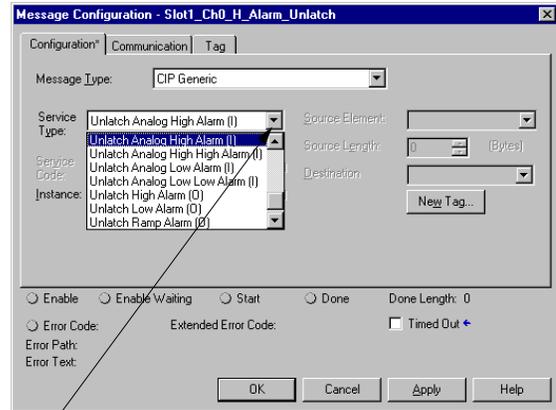
Configuration Pop-Up Screen

This pop-up screen provides information on what module service to perform and where to perform it. For example, you must use this screen to unlatch high high alarms (module service) on channel 0 of a 1756-IF6I module (where to perform service).

RSLogix 5000, version 9 and earlier



RSLogix 5000, version 10 and greater



In the newer versions of RSLogix 5000, you can use a pull-down menu to choose the Service Type. The list of available services includes multiple services to unlatch high high, high, low low, low, ramp and rate alarms.

Table C.1 contains required configuration pop-up screen information to perform input module services. This information is only necessary if you are configuring the message with **RSLogix 5000, versions 9 or earlier**:

Table C.1 Analog Input Modules Configuration Pop-Up Screen Information

Enter the following:	To unlatch the high high alarm:	To unlatch the high alarm:	To unlatch the low alarm:	To unlatch the low low alarm:	To unlatch the rate alarm:
Service Code	4B	4B	4B	4B	4B
Object Type	0A	0A	0A	0A	0A
Object ID ⁽¹⁾ (Channel Number)	1-6 or 1-8	1-6 or 1-8	1-6 or 1-8	1-6 or 1-8	1-6 or 1-8
Object Attribute	6E	6C	6B	6D	6F
Number of Elements	0 bytes	0 bytes	0 bytes	0 bytes	0 bytes

⁽¹⁾ The 1756-IF16 module does not have any unlatchable features in the 16 channel mode.

IMPORTANT

For input or output modules, the Object Attribute determines which alarm feature for the selected channel to unlatch. If this field is left blank, **all alarms for the selected channel** will be unlatched.

You must send separate message instructions to control specific alarms on each channel of the module.

Also, Object ID represents channel number. For the 1756-IF6I, 1756-IR6I and 1756-IT6I modules, channels 0-5 are represented by Object ID 1-6. For the 1756-IF16 (in differential mode only) and 1756-IF8 modules, channels 0-7 are represented by Object ID 1-8.

Table C.2 contains required configuration pop-up screen information to perform output module services. This information is only necessary if you are configuring the message with **RSLogix 5000, versions 9 or earlier**:

Table C.2 Analog Output Modules Configuration Pop-Up Screen Information

Enter the following:	To unlatch the high alarm:	To unlatch the low alarm:	To unlatch the ramp alarm:
Service Code	4B	4B	4B
Object Type	0B	0B	0B
Object ID (Channel Number)	1-6 or 1-8	1-6 or 1-8	1-6 or 1-8
Object Attribute	6F	6E	70
Number of Elements	0 bytes	0 bytes	0 bytes

Communications Pop-Up Screen

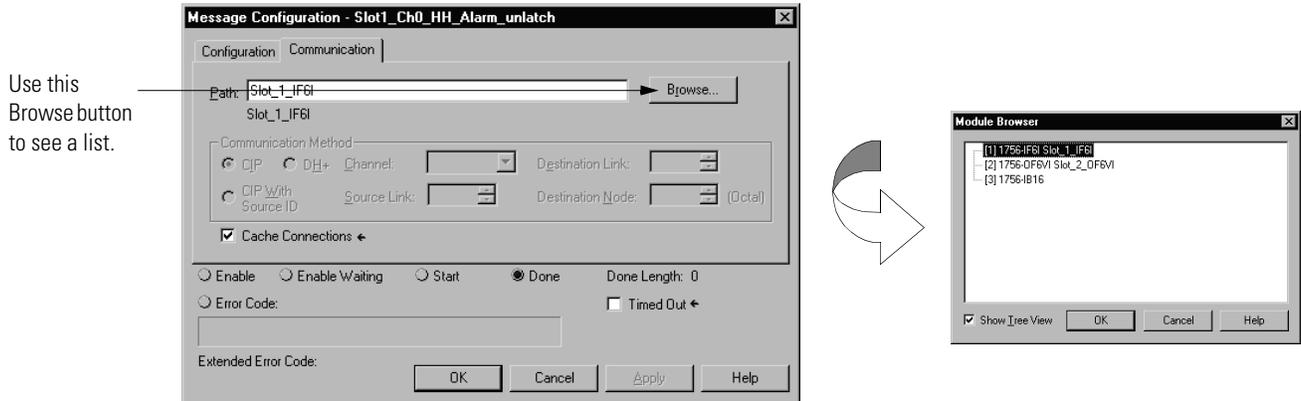
This pop-up screen provides information on the path of the message instruction. For example, the slot number of a 1756-IF6I distinguishes exactly which module a message is designated for.

IMPORTANT

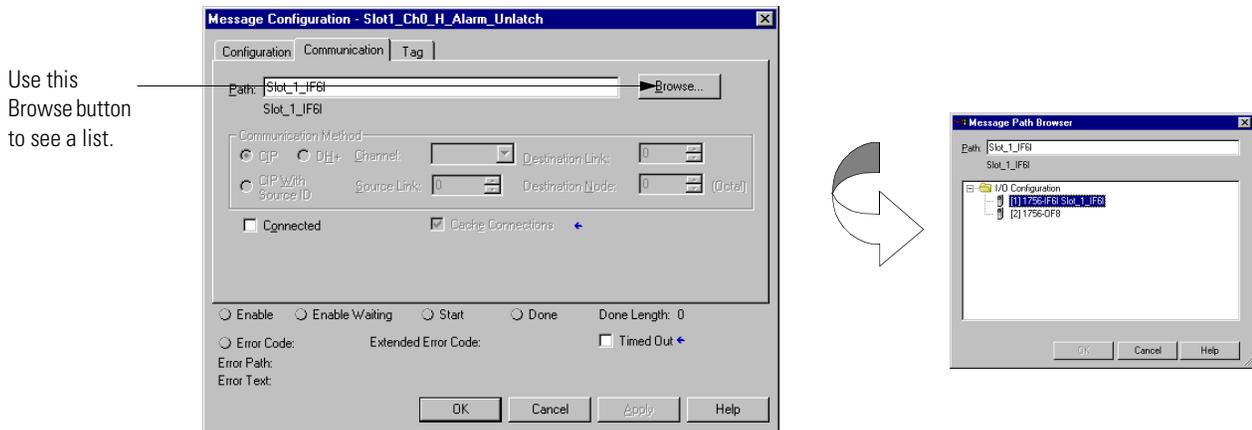
Use the Browse button to see a list of the I/O modules in the system. You choose a path when you choose a module from the list.

You must name an I/O module during initial module configuration to choose a path for your message instruction.

RSLogix 5000, version 9 and earlier



RSLogix 5000, version 10 and greater



Unlatch Alarms in the 1756-IF6I

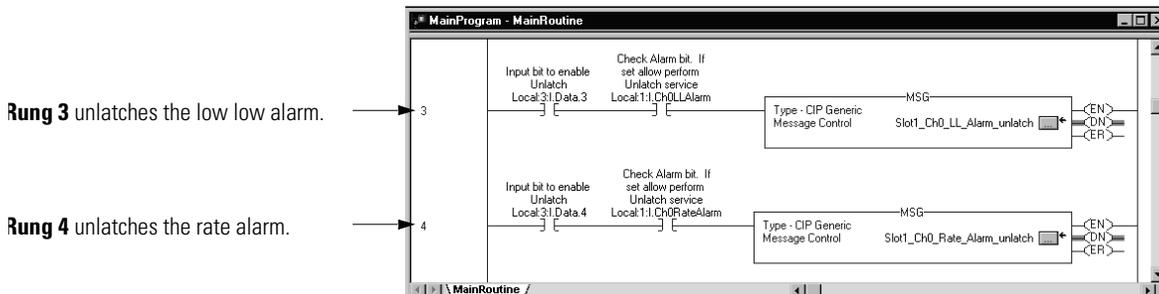
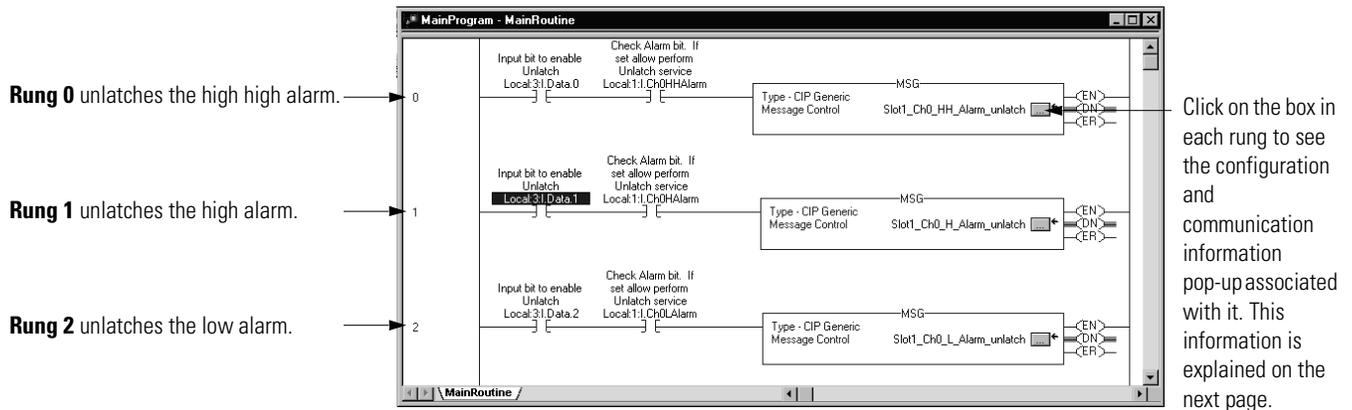
Example Rungs 0-4 show how to unlatch the following alarms in a 1756-IF6I module, named *Slot_1_IF6I*:

- Channel 0 High high alarm - Rung 0
- Channel 0 High alarm - Rung 1
- Channel 0 Low alarm - Rung 2
- Channel 0 Low low alarm - Rung 3
- Channel 0 Rate alarm - Rung 4

IMPORTANT

An I/O module must be configured to latch alarms, see pages 10-9 & 10-13, before you can perform unlatch services using ladder logic. If an unlatch service is received by a module not configured to latch alarms, the message instruction will error.

Also, all alarms for channel 0 can be unlatched simultaneously with a single message instruction by leaving the object attribute field blank.



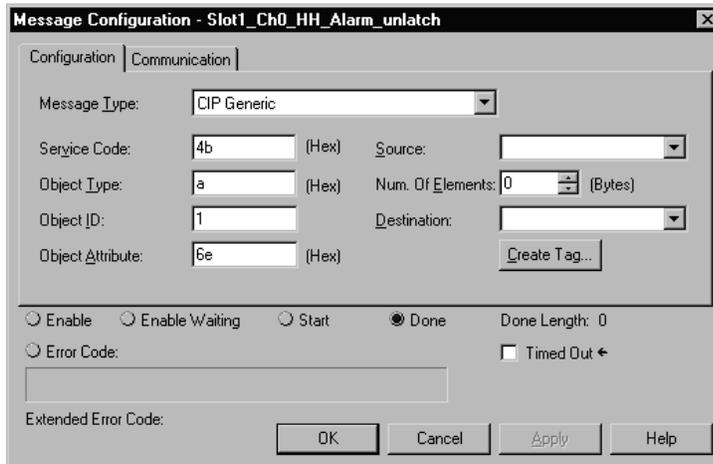
Configuration Pop-Up Screens

The screen below shows the Configuration pop-up for Rung 0.

RSLogix 5000, version 9 and earlier

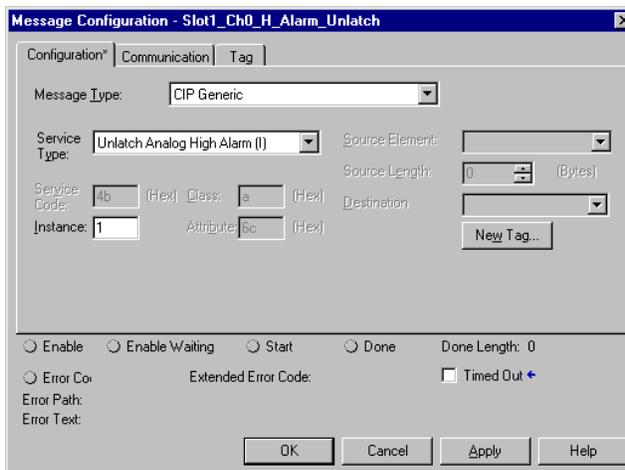
This pop-up screen contains the same information for each rung, except for the Object Attribute field. The information in this field is as follows:

- Rung 0 - 6e
- Rung 1 - 6c
- Rung 2 - 6b
- Rung 3 - 6d
- Rung 4 - 6f



RSLogix 5000, version 10 and greater

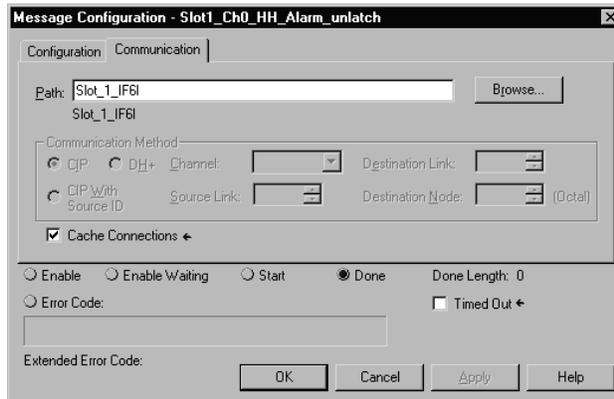
With the newer RSLogix 5000 versions, you are only required to choose a service type and configure the instance.



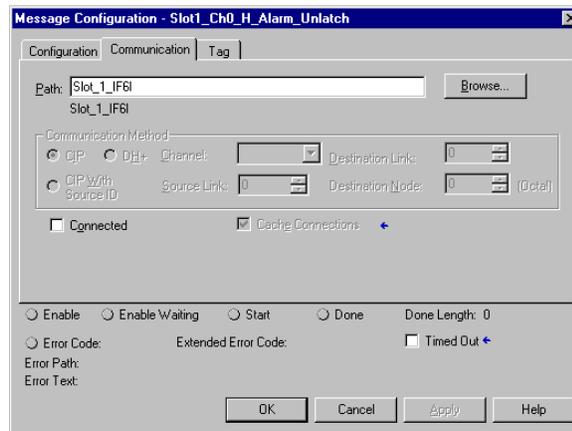
Communications Pop-Up Screens

The screen below shows the Communications pop-up for Rung 0. This pop-up screen is the same for each rung of this example.

RSLogix 5000, version 9 and earlier



RSLogix 5000, version 10 and greater



IMPORTANT

You must name an I/O module to set the message path under that module's communication tab.

Unlatch Alarms in the 1756-OF6VI

Example Rungs 5-7 show how to unlatch the following alarms in a 1756-OF6VI module:

- High limit alarm - Rung 5
- Low limit alarm - Rung 6
- Ramp alarm - Rung 7

Rung 5 unlatches the high limit alarm.

Rung 6 unlatches the low limit alarm.

Rung 7 unlatches the ramp alarm.

Click on the box in each rung to see the configuration and communication information pop-up associated with it. This information is explained below.

Configuration Pop-Up Screens

The screen below shows the Configuration pop-up for Rung 5.

RSLogix 5000, version 9 and earlier

This pop-up screen contains the same information for each rung, except for the Object Attribute field. The information in this field is as follows:
 Rung 5 - 6f
 Rung 6 - 6e
 Rung 7 - 70

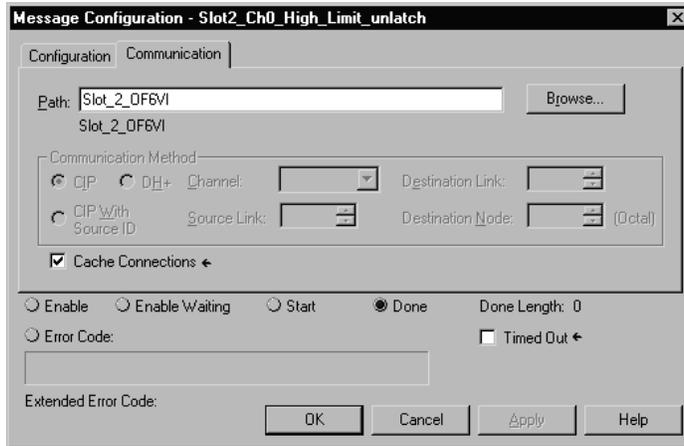
RSLogix 5000, version 10 and greater

With the newer RSLogix 5000 versions, you are only required to choose a service type and configure the instance.

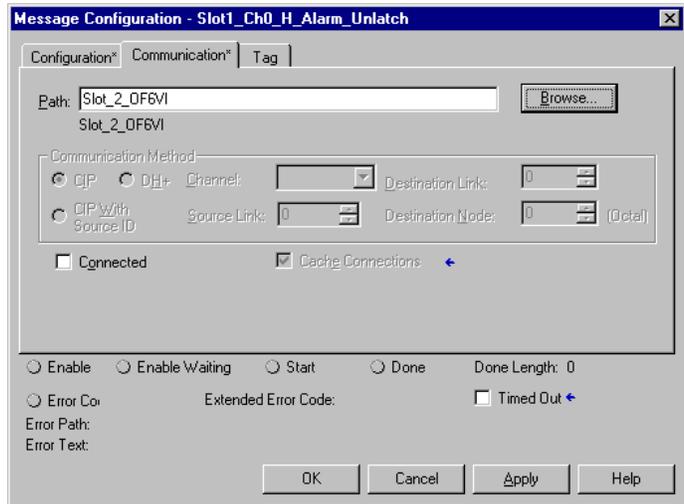
Communications Pop-Up Screens

The screen below shows the Communications pop-up for Rung 5. This pop-up is the same for each rung in this example.

RSLogix 5000, version 9 and earlier



RSLogix 5000, version 10 and greater



IMPORTANT

You must name an I/O module to set the message path under that module's communication tab.

Reconfiguring a 1756-IR6I Module

It is sometimes advantageous to change the functional operation of a module in the ControlLogix system automatically via the user program rather than using RSLogix5000 software to reconfigure it. This way, changes in the process can dictate when the reconfiguration should take place rather than the user performing that function manually.

The following steps are used in this example when reconfiguring a module via ladder are:

1. Move new configuration parameters to the Configuration portion of the Tag Structure associated with the module.
2. If you are using RSLogix 5000, **version 10 or greater**, use a message instruction to send a Reconfigure Module service to the same module.

If you are using RSLogix 5000, **version 9 or earlier**, use a message instruction to send a Reset Module service to the same module to trigger sending the configuration data.

Before the new configuration parameters are sent to the module, the user must make sure that their relationship to each other is in a format the module will accept (see tables below).

IMPORTANT

Reconfiguring analog modules via ladder should be limited to functions that involve **the changing of values only**. We do not recommend that enabling or disabling features be done via ladder. Use RSLogix 5000 to enable or disable these features.

Table C.3 and Table C.4 list module parameters that may be changed via ladder logic:

Table C.3 Permissible Analog Input Module Parameters to Change Via Ladder Logic

Feature:	Restriction:
High Engineering Value	Must not be equal to low engineering value
Low Engineering Value	Must not be equal to high engineering value
High-High Alarm Value	Must be greater than or equal to high alarm value
High Alarm Value	Must be greater than low alarm value
Low Alarm Value	Must be less than high alarm value
Low-Low Alarm Value	Must be less than or equal to low alarm value
Deadband	Must be less than half of high alarm minus low alarm

Table C.4 Permissible Analog Output Module Parameters to Change Via Ladder Logic

Feature:	Restriction:
High Clamp Value ⁽¹⁾	Must be greater than low clamp value
Low Clamp Value ⁽¹⁾	Must be less than high clamp value

⁽¹⁾ The values for user-defined state at Fault or Program (set during initial configuration) must fall within the range of the High and Low Clamp values.

Considerations With This Ladder Logic Example

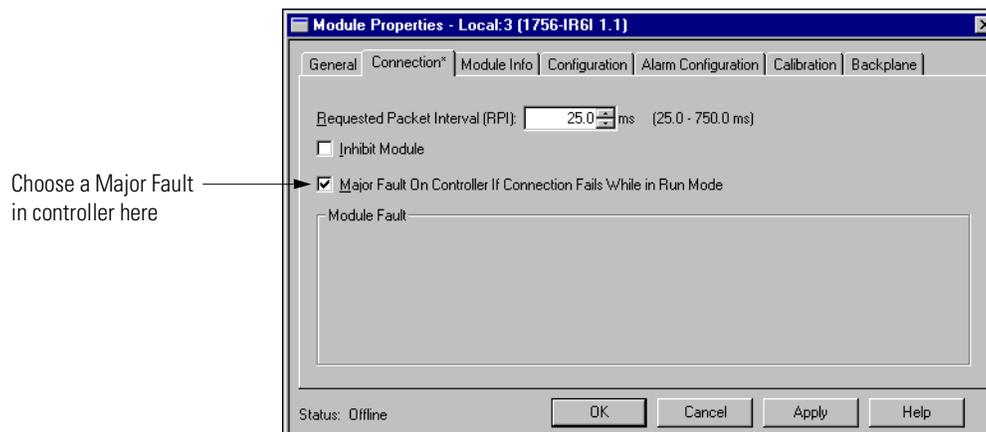
IMPORTANT

The considerations listed in this section only apply if you are using RSLogix 5000, version 9 or earlier.

If you are using RSLogix 5000, **version 10 or greater, none of these considerations apply.**

Remember the following when using this method of module reconfiguration using the reset service:

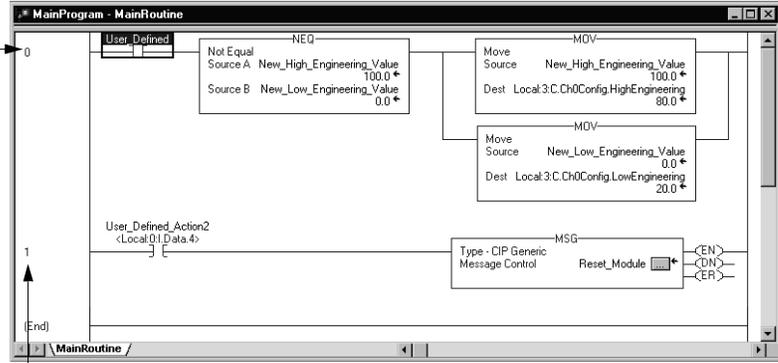
- When this method of reconfiguration is used on Output modules, ALL module outputs will be reset to Zero for at least three seconds
- This method of reconfiguration will cause a Major Fault in the controller if the module was initially configured to do so on the following screen:



- All Listen-Only controllers will lose their connections to the module for a minimum of three seconds after the Reset is performed.
- If the Reconfiguration is performed on an Input module with multiple owners, then all owners will lose their connections simultaneously after the Reset is performed. In order to re-establish all their connections, all owners must change their configuration to the same values BEFORE the Reset is performed.

The following ladder example shows how to change the High and Low Engineering Values (Scaling Parameters) for an Analog Output module in Slot 3 of the Local Chassis:

Rung 0
 This rung moves new Channel 0 scaling parameters to the configuration portion of the structure associated with an analog output module in Slot 3 of the local chassis.
 The new values move at the user's discretion (represented by the user defined XIC instruction) after making sure the desired new high value is not equal to the desired new low value. This rung only moves the data to the configuration portion of the structure but does not send it to the module.



Rung 1
 This rung sends the Reset Module service to the analog output module. Upon receipt, the module will initiate a hardware reset on itself, behaving as though it has just been inserted into the system. A connection is established and the new configuration parameters are sent.

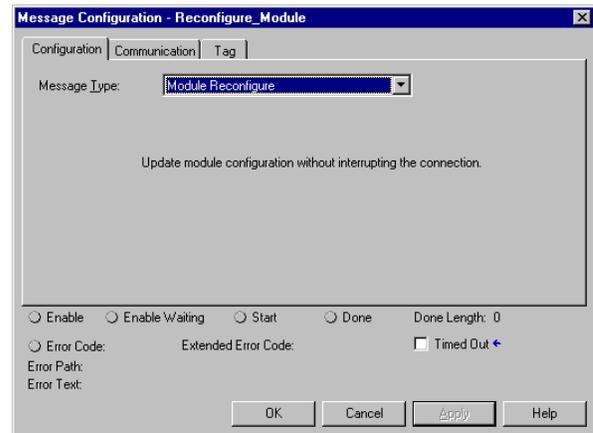
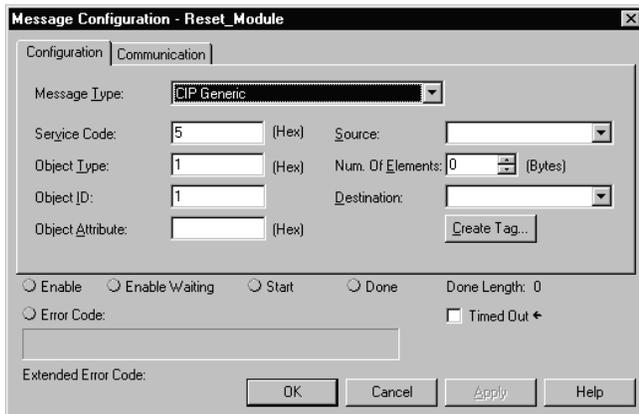
Perform Module Reset Service

The following configuration and communication pop-up screens show the **message instruction to perform the Reset service** and its path:

The screen below shows the Configuration pop-up.

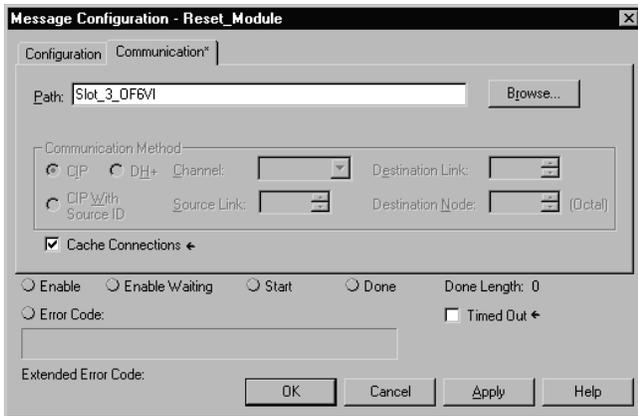
RSLogix 5000, version 9 and earlier

RSLogix 5000, version 10 and greater

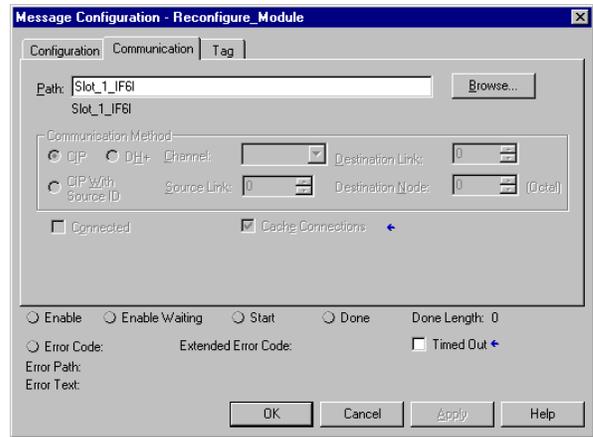


The screen below shows the Configuration pop-up.

RSLogix 5000, version 9 and earlier



RSLogix 5000, version 10 and greater



Notes:

Power Supply Sizing Chart

Use Table D.1 to check the power your ControlLogix chassis is using.

Table D.1

Slot number	Module Catalog Number	Current @ 5.1 VDC (mA)		Power @ 5.1 VDC (Watts)	Current @ 24 VDC (mA)		Power @ 24 VDC (Watts)	Current @ 3.3 VDC (mA)		Power @ 3.3 VDC (Watts)
0			x 5.1V =			x 24V =			x 3.3V =	
1			x 5.1V =			x 24V =			x 3.3V =	
2			x 5.1V =			x 24V =			x 3.3V =	
3			x 5.1V =			x 24V =			x 3.3V =	
4			x 5.1V =			x 24V =			x 3.3V =	
5			x 5.1V =			x 24V =			x 3.3V =	
6			x 5.1V =			x 24V =			x 3.3V =	
7			x 5.1V =			x 24V =			x 3.3V =	
8			x 5.1V =			x 24V =			x 3.3V =	
9			x 5.1V =			x 24V =			x 3.3V =	
10			x 5.1V =			x 24V =			x 3.3V =	
11			x 5.1V =			x 24V =			x 3.3V =	
12			x 5.1V =			x 24V =			x 3.3V =	
13			x 5.1V =			x 24V =			x 3.3V =	
14			x 5.1V =			x 24V =			x 3.3V =	
15			x 5.1V =			x 24V =			x 3.3V =	
16			x 5.1V =			x 24V =			x 3.3V =	
	TOTALS	mA		W	mA		W	mA		W
		This number cannot exceed 10000mA			This number cannot exceed 2800mA			This number cannot exceed 4000mA		
				These three numbers added together cannot exceed:						
				70W @40°C						
				55W @ 60°C						

IMPORTANT

We recommend that you copy this worksheet for use in checking the power supply of each ControlLogix chassis used.

Notes:

Additional Specification Information

This appendix offers additional calibration information that may assist you in using the ControlLogix analog I/O module.

For more information on:	See page:
Analog to Digital (A/D) Converter Accuracy	E-1
Calibrated Accuracy	E-2
Error Calculated Over Hardware Range	E-3
How Operating Temperature Changes Affect Module Accuracy	E-3
RTD Error	E-5
Thermocouple Error	E-6
Thermocouple Resolution	E-14

Analog to Digital (A/D) Converter Accuracy

There are two types of calibration that occur on a ControlLogix analog I/O module.

- The user-directed and user-performed calibration process described in Chapter 11. This type of calibration occurs only when you determine it is necessary and involves an external calibration instrument like those listed in Table 11.1 on page 11-2.
- A self-calibration process that takes place internally on ControlLogix analog I/O modules when either of the following events occurs:
 - Module power is cycled
 - You begin the user calibration described in Chapter 11.

The "A/D self-calibration" feature maintains the accuracy of the A/D convertor found on all 1756 isolated analog modules. This feature executes each time the module cycles power or when a self-calibration cycle is initiated.

The self-calibration compensates for inaccuracies of the on-board reference signal and the A/D convertor only. In other words, the self-calibration feature makes sure that the A/D convertor itself is accurate with respect to its on-board voltage reference that is used for a conversion of the input signal. Together with user calibration, the module's total accuracy is maintained.

Calibrated Accuracy

The *Calibrated Accuracy* specification represents the module's accuracy when its ambient (i.e. operating) temperature is the same as the temperature at which the module was calibrated.

Immediately following a calibration, a ControlLogix analog I/O module is most accurate. Because the module was calibrated at its zero and span, the inaccuracy is largely non-linearity between zero and span. Assuming the module is operating at the exact temperature when it was calibrated and uses the same voltage source to check the post-calibration accuracy, a module may be as accurate as 0.01% to 0.05% of range.

Once the module begins operation, its accuracy lessens as components change over time. However, this change (in components or accuracy) is different from the Gain Drift With Temperature specification described on page E-3.

Other than non-linearity, the *Calibrated Accuracy @ 25°C* specification represents a time drift/aging specification between calibrations. A module with a calibration accuracy of 0.01% of range immediately following calibration is estimated to be better than 0.1% of range @ 25°C for one year (i.e. the calibration cycle).

The reason for the difference between 0.01% and 0.1% of range is that the *Calibrated Accuracy @ 25°C* specification must capture the effect of component aging until the next time the module is calibrated. Primarily, the module's operating conditions, such as temperature, humidity, and power cycling, affect component aging.

Because ControlLogix analog I/O modules operate in different conditions, the specific accuracy deviation from 0.01% of range cannot be measured. Typically, however, a module's *Calibrated Accuracy @ 25°C* is closer to 0.05% of range than 0.1% of range as the 0.1% of range is determined by the worst case scenario operating conditions.

Error Calculated Over Hardware Range

A ControlLogix analog I/O module's calibration accuracy at 25°C is calculated over the full hardware range of the module and is not dependent on the application's use of the range. The error is the same if you are measuring it across a 10% or 100% portion of a given range.

However, a module's accuracy at 25°C is dependent on the hardware range in which the module operates.

EXAMPLE

The 1756-IT6I module offers two input ranges, -12 to 30mV and -12 to 78mV. Because module error at 25°C depends on the input range used, the module error is as follows when using 0.1% of range accuracy:

- +/- 42µV for the -12 to 30mV range
- +/- 90µV for the -12 to 78mV range

These error values are the same whether you use 10% or 100% of the chosen range.

How Operating Temperature Changes Affect Module Accuracy

The following specifications take into account how the module's operating temperature changes can affect a module's accuracy:

- Gain Drift With Temperature
- Module Error Over Full Temperature Range

Gain Drift With Temperature

The *Gain Drift with Temperature* specification represents the calibration inaccuracy that occurs as a module's ambient (i.e. operating) temperature drifts from the temperature at which it was calibrated.

You can use the *Gain Drift with Temperature* specification (varies for each catalog number) to determine the module's calibration inaccuracy for each degree between calibration and operating temperature. The *Gain Drift with Temperature* specification represents a percentage of the full operating range that the module's calibration is inaccurate to for each degree difference. The specification is determined with the following formula:

$$\text{Gain Drift with Temperature} = (\text{PPM}/^{\circ}\text{C}) \times \text{Module's Full Range}$$

Because the specifications listed in Appendix A include a typical and worst case PPM/°C for each module, you can determine multiple Gain Drift with Temperature values for each module.

EXAMPLE

For example, the 1756-IT6I module has a maximum *Gain Drift with Temperature* specification of 80ppm/°C. The 80ppm represents 0.008% of the module's full operating temperature.

If the module was calibrated to operate in the -12mV to 78mV input range, then following formula is used:

$$(0.008/^\circ\text{C}) \times 90\text{mV} = +/-7.2\mu\text{V}/^\circ\text{C}$$

For every degree C that the module's operating temperature moves from the calibration temperature, the maximum calibration accuracy deviation is +/-7.2μV.

Module Error Over Full Temperature Range

The *Module Error Over Full Temperature Range* specification represents the error that occurs if the module's ambient temperature changes a total of 60°C (i.e. from 0 to 60°C or 60 to 0°C). While this temperature change is extremely unlikely, it represents the worst case scenario.

This specification is determined by multiplying the temperature change by the maximum *Gain Drift with Temperature* for the given module. In other words, we determine Module Error Over Full Temperature Range with the following formula:

$$\text{Module Error Over Full Temperature} = \text{Full Temperature Range} \times \text{Gain Drift with Temperature}$$

EXAMPLE

The 1756-IT6I module has a maximum *Gain Drift with Temperature* specification = 80 ppm/°C.

Module Error over Full Temperature Range = 60°C (full temperature range) X 80 ppm/°C (gain drift).
The result is 4800 ppm or 0.48%.

RTD and Thermocouple Error Calculations

When you using the temperature-measuring modules (1756-IR6I, 1756-IT6I and 1756-IT6I2), error calculations are achieved in the following two-step process:

1. Calculate the module's error in ohms or volts
2. Convert the ohm/volt error to temperature for the specific sensor and at the correct application temperature

RTD Error

Module error on the 1756-IR6I module is defined in ohms and is calculated across the entire input range selected, not the available range of a sensor used with the module. For example, if the 1 ohm to 487 ohm input range is used, the module error is calculated across 507 ohms (actual range = 0.86 ohms to 507.86 ohms).

The error in ohms translates to temperature, but that translation varies because the relationship is non-linear. The most effective way to check 1756-IR6I module error is to calculate the error in ohms and use that value in a linearization table to check the temperature error.

If the module is calibrated at operating temperature and the operating temperature remains relatively stable, calibration accuracy is better than 0.1% of the full range for the first year after calibration. This 0.1% value is a worst case value. In other words, with the 1 ohm to 487 ohms input range selected, the worst case module error is 0.507 ohms.

Finally, you must check an RTD linearization table to determine the temperature error to which an error of 0.507 ohms translates. For example, if the 1756-IR6I has a 0.1% (or 0.507 ohms) error and is operating at 0°C, the temperature error is -1.25°C to +1.2°C—when the Platinum 385 sensor type is used. However, this same ohms error calculated in an operating temperature of 200°C translates to a temperature error of -1.4°C to +1.4°C.

Thermocouple Error

Thermocouple error at 25°C indicates the module's accuracy in measuring temperature. This accuracy varies depending on the following factors:

- Input range used, either:
 - -12 to 30mV
 - -12 to 78mV
- Thermocouple type, any of the following:
 - B, R, S, E, J, K, N, T, L or D (L and D types can be used with the 1756-IT6I2 only)
- Application temperature (i.e. the temperature of the physical location where the thermocouple is being used)

EXAMPLE

For example, when the 1756-IT6I module is operating in the following conditions:

- -12 to 30mV input range
- connected to a type S thermocouple
- application temperature of 1200°C

the module error at 25°C is +/-1.75 degrees.

In other words, the difference between the temperature the module reports and the actual application temperature can be +/- 1.75 degrees.

The module may report an application temperature of 1200° celsius in this case when the actual temperature can be in the range from 1196.26 to 1203.74° celsius.

IMPORTANT

When determining the thermocouple error, we used a typical error of 0.05% of temperature range. The error calculations are listed for each range (i.e. -12 to 30mv and -12 to 78mV) in the rest of this section.

However, keep in mind that if cold junction compensation is performed on the thermocouple modules, the cold junction sensor error values must be added to the +/-1.75 degrees value in the example above and the numbers listed in the rest of this section.

Module Error at 25°C (-12 to 30mV Range)

Table E.1 lists the ControlLogix thermocouple modules' error at 25°C when used in the -12 to 30mV input range.

Table E.1

Application Temperature	Module Error (in degrees) at 25°C When Connected to This Thermocouple Type:							
	B	R	S	E ⁽¹⁾	J ⁽²⁾	K ⁽³⁾	N ⁽⁴⁾	T
-200°C				0.836	0.96	1.376	2.115	1.334
0°C				0.358	0.42	0.532	0.803	0.542
200°C		2.37	2.48	0.284	0.38	0.525	0.637	0.395
400°C		2.02	2.19	0.262	0.38	0.497	0.566	0.340
600°C	3.53	1.85	2.06			0.494	0.539	
800°C	2.75	1.71	1.93				0.535	
1000°C	2.30	1.59	1.82					
1200°C	2.03	1.51	1.75					
1400°C	1.86	1.49	1.73					
1600°C	1.80	1.51	1.77					
1800°C	1.83	1.71	2.04					

- (1) Type E thermocouples can only be used in applications up to 400°C.
- (2) Type J thermocouples can only be used in applications up to 550°C.
- (3) Type K thermocouples can only be used in applications up to 700°C.
- (4) Type N thermocouples can only be used in applications up to 800°C.

The information represented in Table E.1 is shown graphically in Figure E.1 through Figure E.8.

Figure E.1 Thermocouple Module Error at 25° - Type B Thermocouple Connection in a -12 to 30mV Input Range

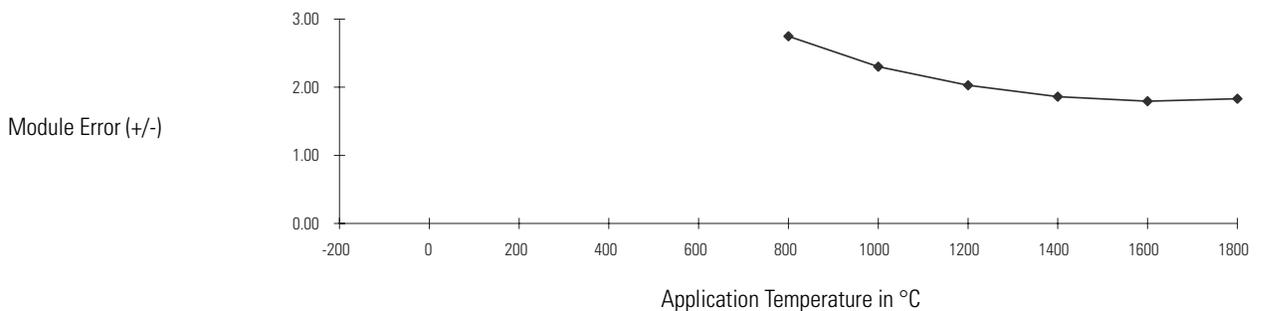


Figure E.2 Thermocouple Module Error at 25° - Type R Thermocouple Connection in a -12 to 30mV Input Range

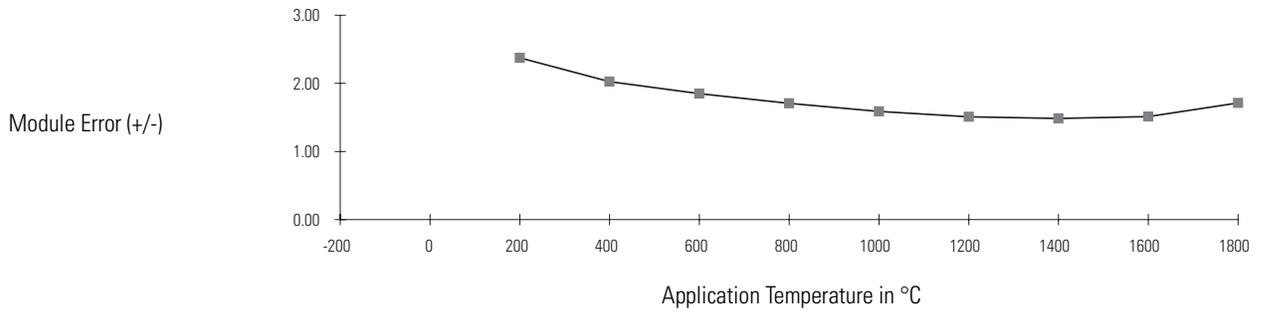


Figure E.3 Thermocouple Module Error at 25° - Type S Thermocouple Connection in a -12 to 30mV Input Range

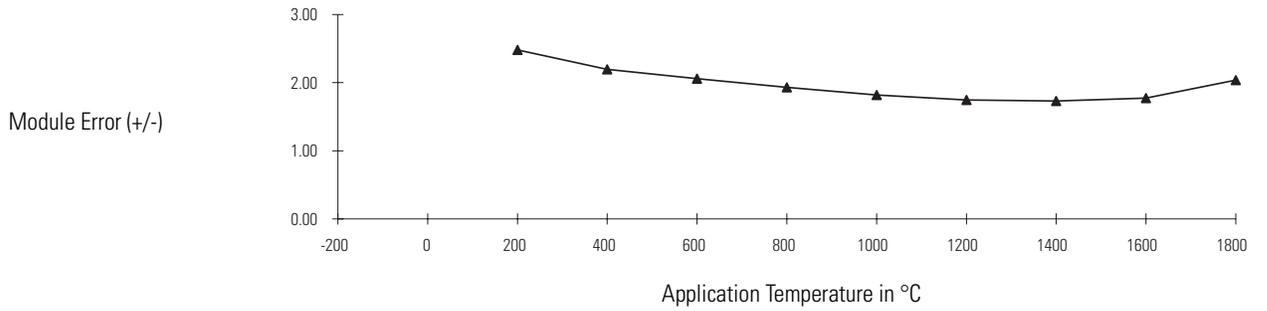


Figure E.4 Thermocouple Module Error at 25° - Type E Thermocouple Connection in a -12 to 30mV Input Range

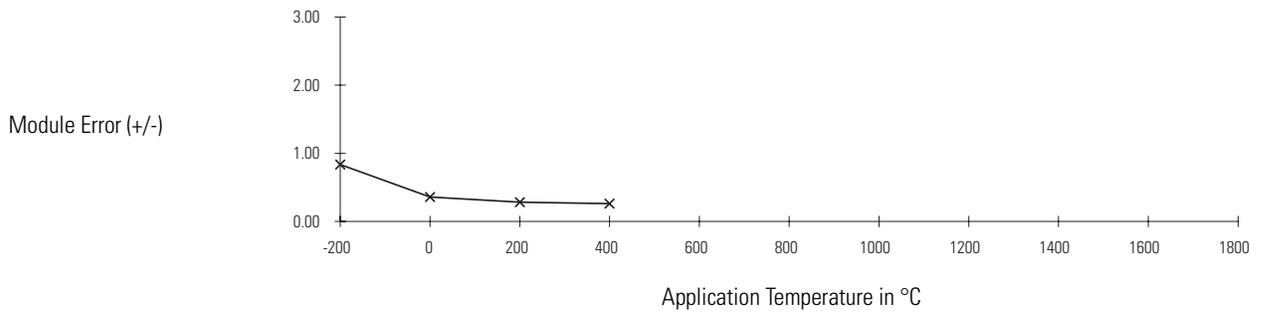


Figure E.5 Thermocouple Module Error at 25° - Type J Thermocouple Connection in a -12 to 30mV Input Range

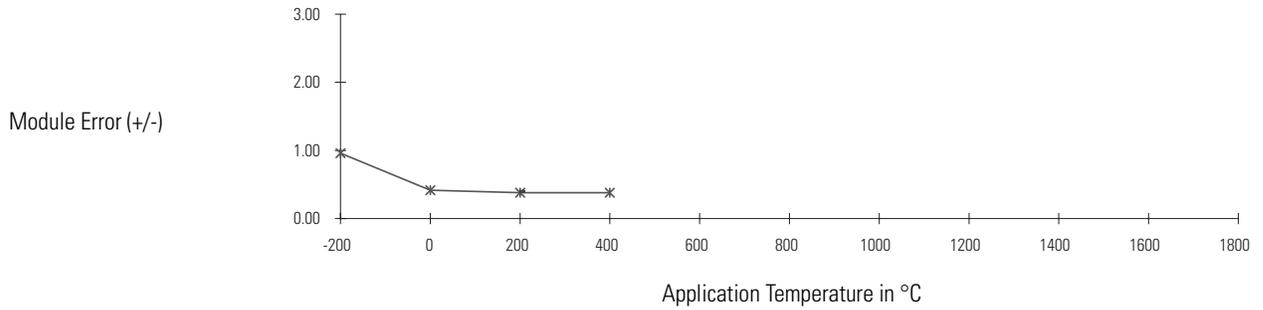


Figure E.6 Thermocouple Module Error at 25° - Type K Thermocouple Connection in a -12 to 30mV Input Range

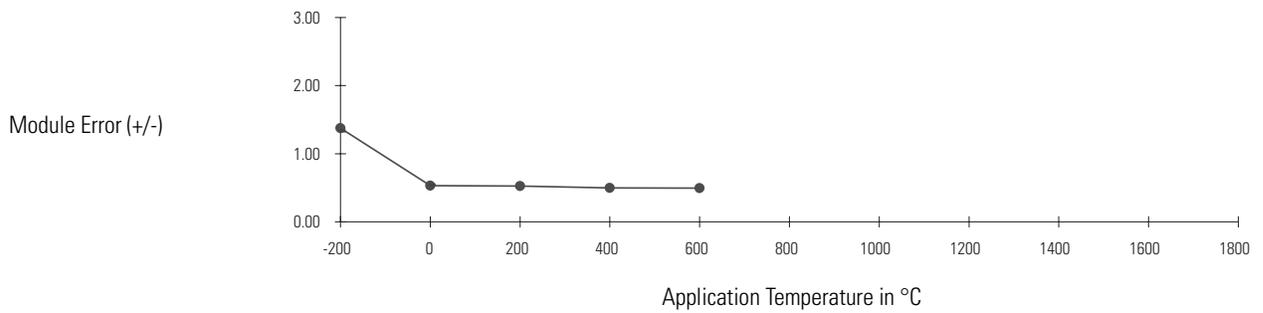


Figure E.7 Thermocouple Module Error at 25° - Type N Thermocouple Connection in a -12 to 30mV Input Range

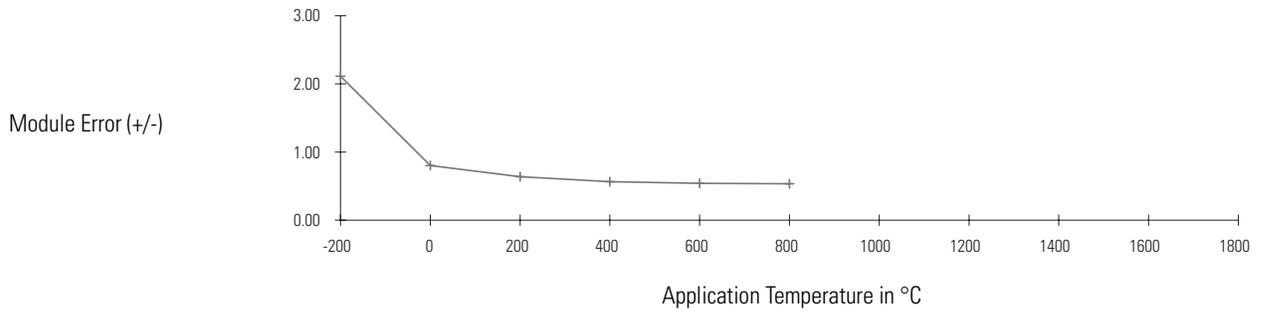
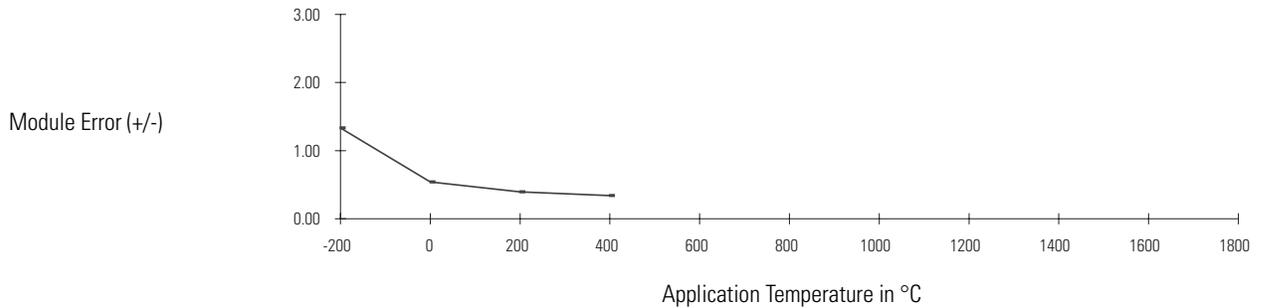


Figure E.8 Thermocouple Module Error at 25° - Type T Thermocouple Connection in a -12 to 30mV Input Range



Module Error at 25°C (-12 to 78mV Range)

Table E.2 lists the ControlLogix thermocouple modules' error at 25°C when used in the -12 to 78mV input range.

Table E.2

Application Temperature in °C:	Module Error (in degrees) at 25°C When Connected to This Thermocouple Type:							
	B	R	S	E	J	K	N	T
-200°C				1.791	2.06	2.949	4.532	2.859
0°C				0.767	0.89	1.141	1.720	1.161
200°C		5.09	5.32	0.608	0.81	1.126	1.364	0.847
400°C		4.34	4.70	0.562	0.82	1.065	1.212	0.728
600°C	7.56	3.96	4.41	0.558	0.77	1.059	1.155	
800°C	5.89	3.65	4.14	0.574	0.70	1.098	1.146	
1000°C	4.93	3.40	3.90	0.599	0.76	1.154	1.165	
1200°C	4.35	3.23	3.74		0.79	1.233	1.210	
1400°C	3.99	3.18	3.71			1.328		
1600°C	3.85	3.24	3.80					
1800°C	3.92	3.67	4.36					

The information represented in Table E.2 is shown graphically in Figure E.9 through Figure E.16.

Figure E.9 Thermocouple Module Error at 25° - Type B Thermocouple Connection in a -12 to 78mV Input Range

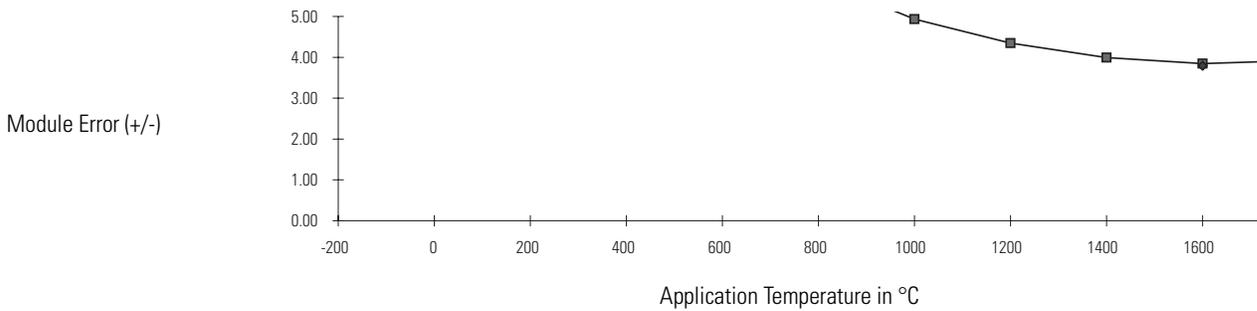


Figure E.10 Thermocouple Module Error at 25° - Type R Thermocouple Connection in a -12 to 78mV Input Range

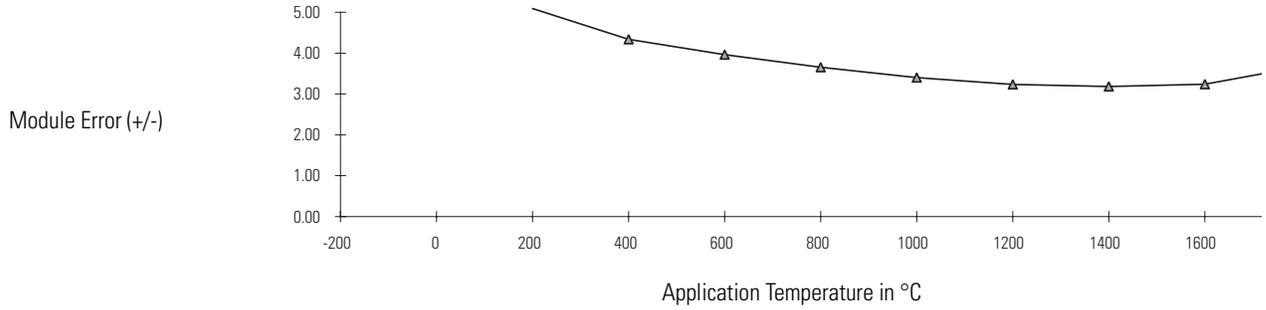


Figure E.11 Thermocouple Module Error at 25° - Type S Thermocouple Connection in a -12 to 78mV Input Range

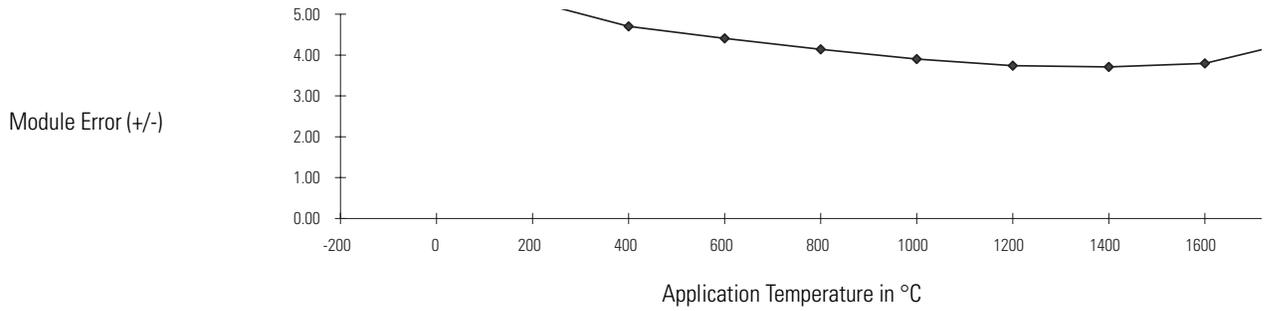


Figure E.12 Thermocouple Module Error at 25° - Type E Thermocouple Connection in a -12 to 78mV Input Range

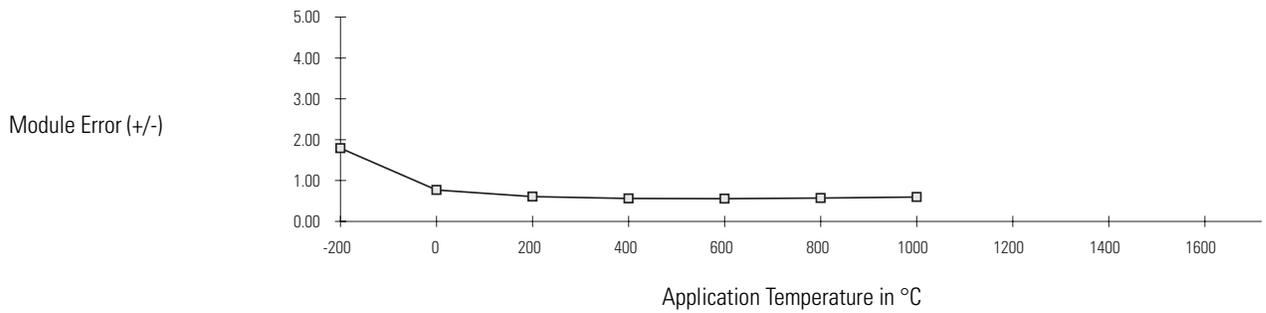


Figure E.13 Thermocouple Module Error at 25° - Type J Thermocouple Connection in a -12 to 78mV Input Range

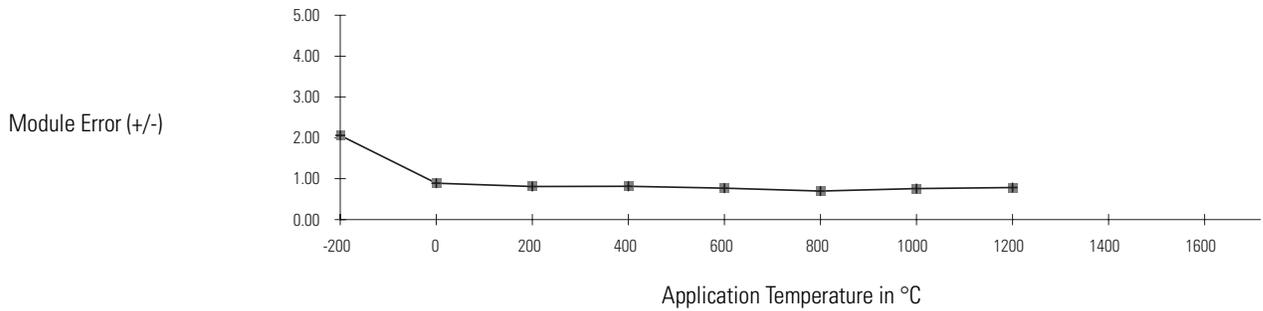


Figure E.14 Thermocouple Module Error at 25° - Type K Thermocouple Connection in a -12 to 78mV Input Range

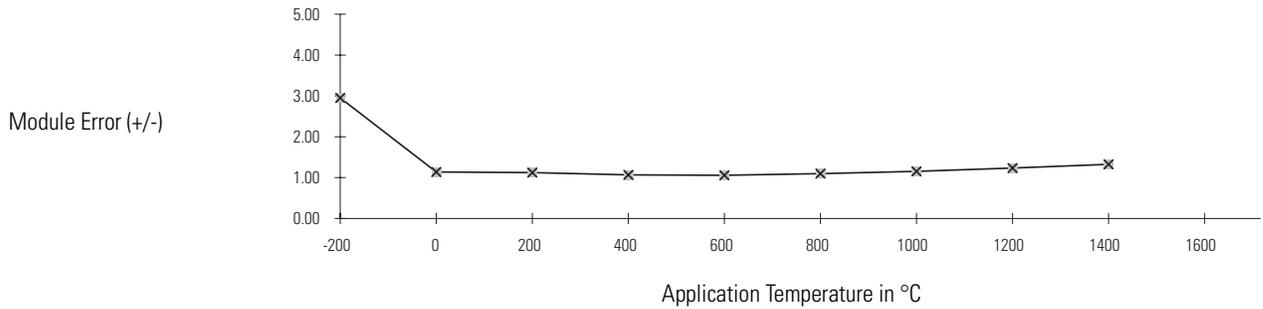


Figure E.15 Thermocouple Module Error at 25° - Type N Thermocouple Connection in a -12 to 78mV Input Range

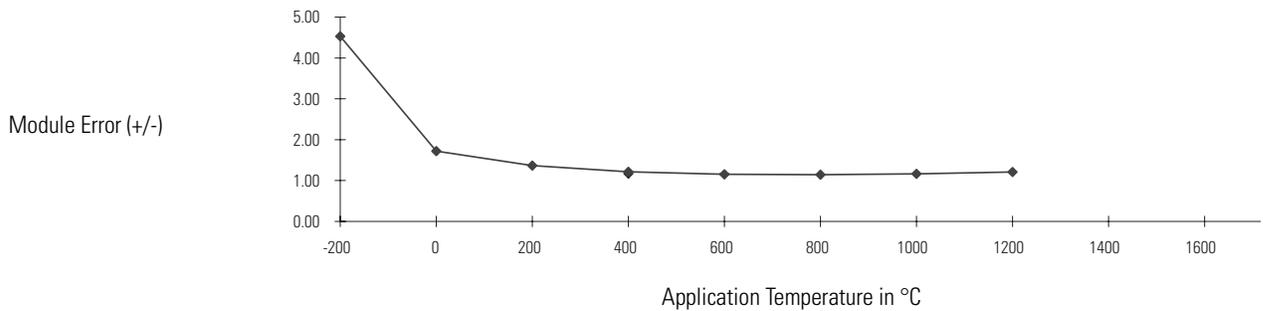
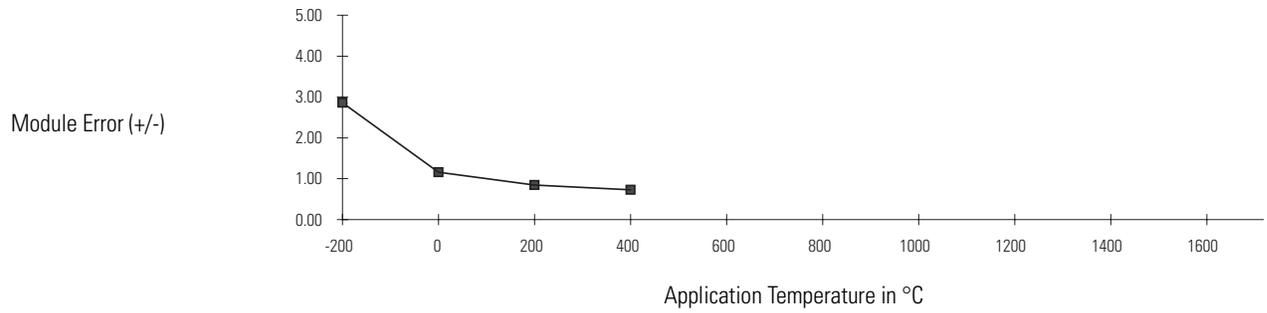


Figure E.16 Thermocouple Module Error at 25° - Type T Thermocouple Connection in a -12 to 78mV Input Range

Thermocouple Resolution

Thermocouple resolution indicates the degrees that an application temperature must change before the ControlLogix thermocouple module reports a change. Resolution varies depending on the following factors:

- Input range used, either:
 - -12 to 30mV
 - -12 to 78mV
- Thermocouple type, any of the following:
 - B, R, S, E, J, K, N, T, L and D (L and D are used on the 1756-IT6I2 module only)
- Application temperature (i.e. the temperature of the physical location where the thermocouple is being used)

EXAMPLE

For example, when the 1756-IT6I module is operating in the following conditions:

- -12 to 30mV input range
- connected to a type K thermocouple
- application temperature of 400°C

the resolution is 0.017 degrees.

In other words, the application temperature must change by 0.017 degrees or greater for the 1756-IT6I module to record a change. If the temperature stays in a range from 399.984 to 400.0169°C, the module will continue to report an application temperature of 400°C.

Module Resolution (-12 to 30mV Range)

Table E.3 lists the resolution of ControlLogix thermocouple modules when used in the -12 to 30mV input range.

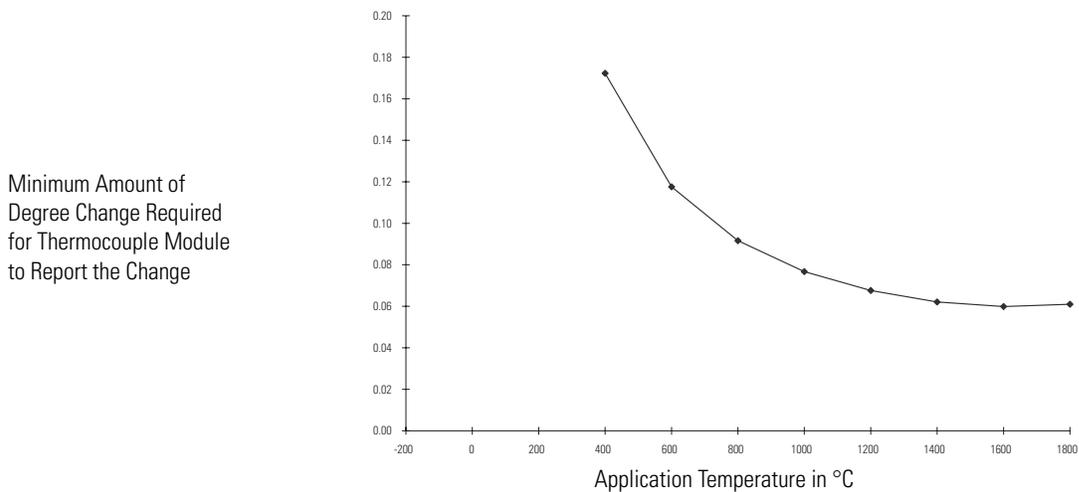
Table E.3

Application Temperature in °C:	Module Resolution (in degrees) When Connected to This Thermocouple Type:							
	B	R	S	E ⁽¹⁾	J ⁽²⁾	K ⁽³⁾	N ⁽⁴⁾	T
-200°C				0.028	0.032	0.046	0.071	0.044
0°C		0.13	0.13	0.012	0.014	0.018	0.027	0.018
200°C		0.08	0.08	0.009	0.013	0.018	0.021	0.013
400°C	0.17	0.07	0.07	0.009	0.013	0.017	0.019	0.011
600°C	0.12	0.06	0.07			0.016	0.02	
800°C	0.09	0.06	0.06				0.02	
1000°C	0.08	0.05	0.06					
1200°C	0.07	0.05	0.06					
1400°C	0.06	0.05	0.06					
1600°C	0.06	0.05	0.06					
1800°C	0.06	0.06	0.07					

- (1) Type E thermocouples can only be used in applications up to 400°C.
- (2) Type J thermocouples can only be used in applications up to 550°C.
- (3) Type K thermocouples can only be used in applications up to 700°C.
- (4) Type N thermocouples can only be used in applications up to 800°C.

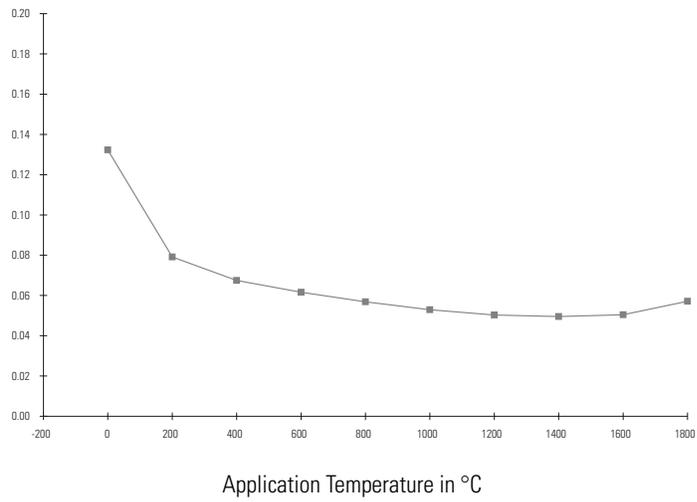
The information represented in Table E.3 is shown graphically in Figure E.17 through Figure E.24.

Figure E.17 Thermocouple Module Resolution - Type B Thermocouple Connection in a -12 to 30mV Input Range



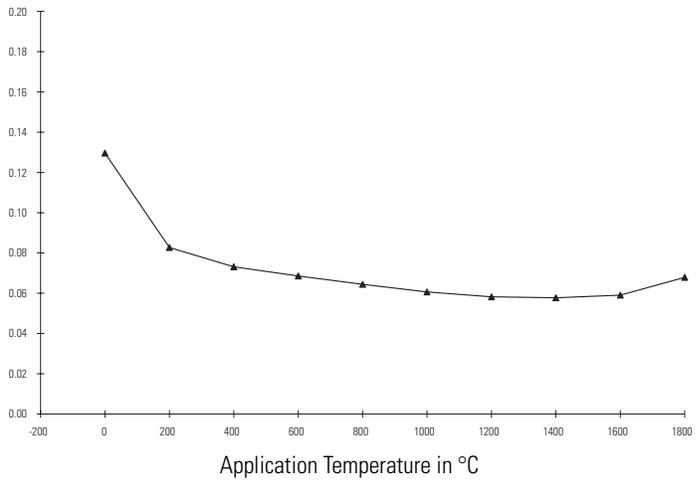
Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

Figure E.18 Thermocouple Module Resolution - Type R Thermocouple Connection in a -12 to 30mV Input Range



Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

Figure E.19 Thermocouple Module Resolution - Type S Thermocouple Connection in a -12 to 30mV Input Range



Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

Figure E.20 Thermocouple Module Resolution - Type E Thermocouple Connection in a -12 to 30mV Input Range

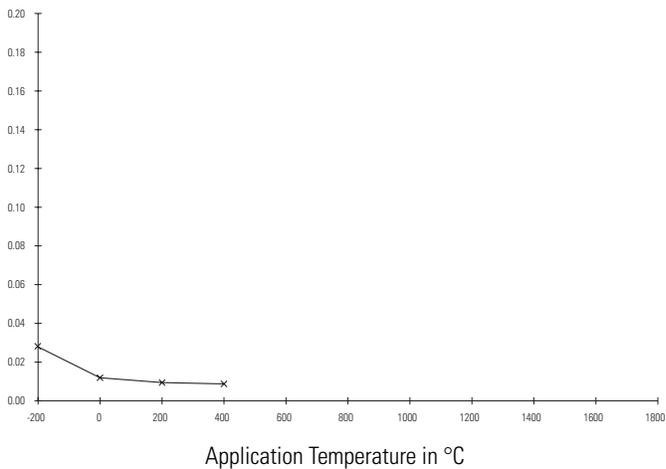


Figure E.21 Thermocouple Module Resolution - Type J Thermocouple Connection in a -12 to 30mV Input Range

Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

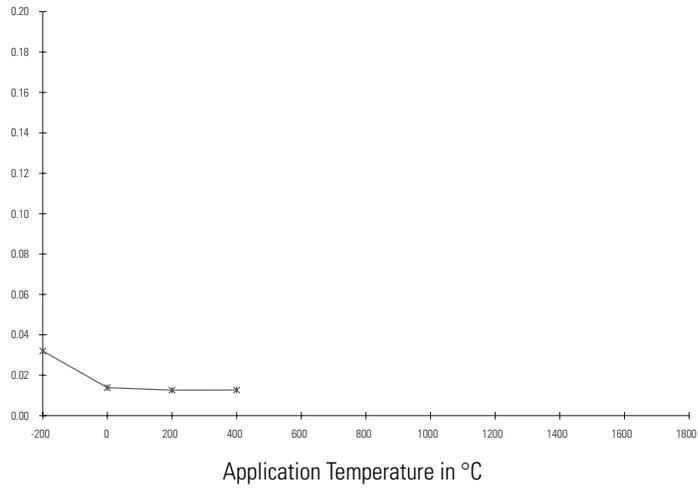


Figure E.22 Thermocouple Module Resolution - Type K Thermocouple Connection in a -12 to 30mV Input Range

Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

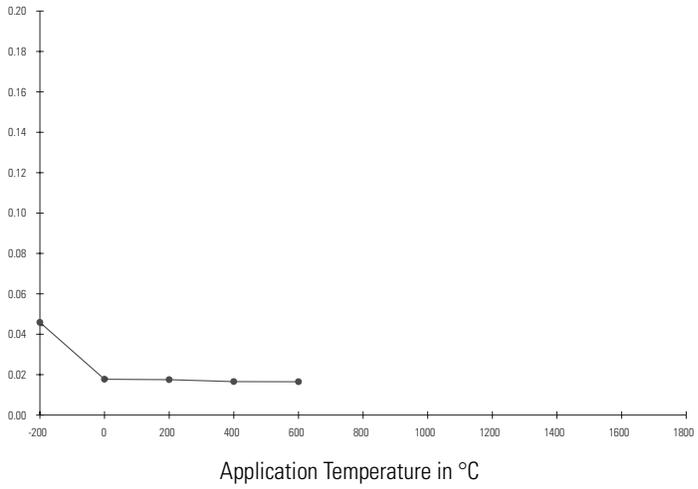


Figure E.23 Thermocouple Module Resolution - Type N Thermocouple Connection in a -12 to 30mV Input Range

Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change

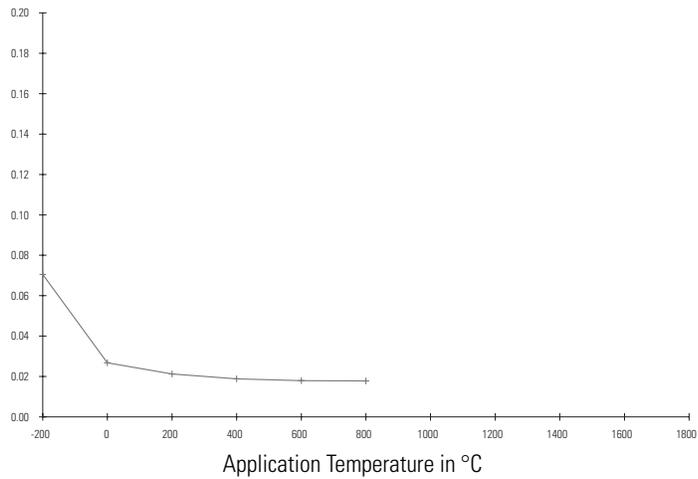
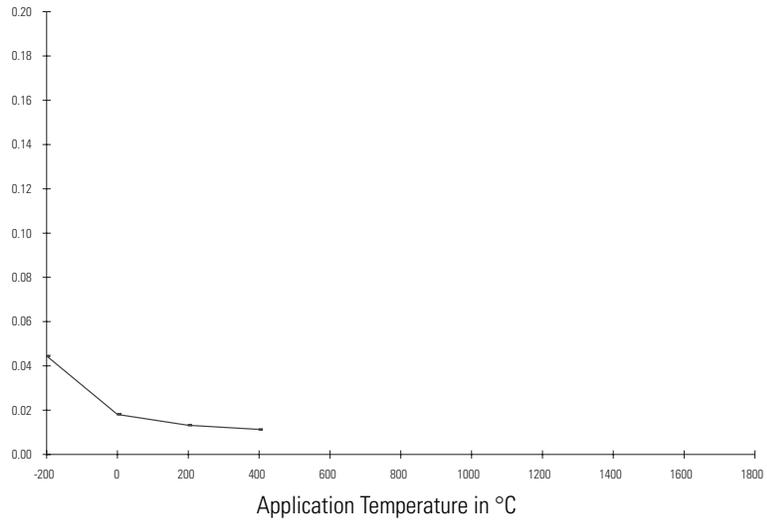


Figure E.24 Thermocouple Module Resolution - Type T Thermocouple Connection in a -12 to 30mV Input Range

Minimum Amount of Degree Change Required for Thermocouple Module to Report the Change



Module Resolution (-12 to 78mV Range)

Table E.4 lists the resolution of ControlLogix thermocouple modules when used in the -12 to 78mV input range.

Table E.4

Application Temperature in °C:	Module Resolution (in degrees) When Connected to This Thermocouple Type:							
	B	R	S	E	J	K	N	T
-200°C (-328°F)				0.056	0.064	0.046	0.141	0.089
0°C (32°F)		0.26	0.26	0.024	0.028	0.092	0.054	0.036
200°C (392°F)		0.16	0.17	0.019	0.025	0.035	0.042	0.026
400°C (752°F)	0.28	0.14	0.15	0.017	0.025	0.035	0.038	0.023
600°C (1112°F)	0.23	0.12	0.14	0.017	0.024	0.033	0.04	
800°C (1472°F)	0.18	0.11	0.13	0.018	0.022	0.033	0.04	
1000°C (1832°F)	0.15	0.11	0.12	0.019	0.024	0.034	0.04	
1200°C (2192°F)	0.14	0.10	0.12		0.024	0.036	0.04	
1400°C (2552°F)	0.12	0.10	0.12			0.038		
1600°C (2912°F)	0.12	0.10	0.12					
1800°C (3272°F)	0.12	0.11	0.14					

The information represented in Table E.2 is shown graphically in Figure E.25 through Figure E.32.

Figure E.25 Thermocouple Module Resolution - Type B Thermocouple Connection in a -12 to 78mV Input Range

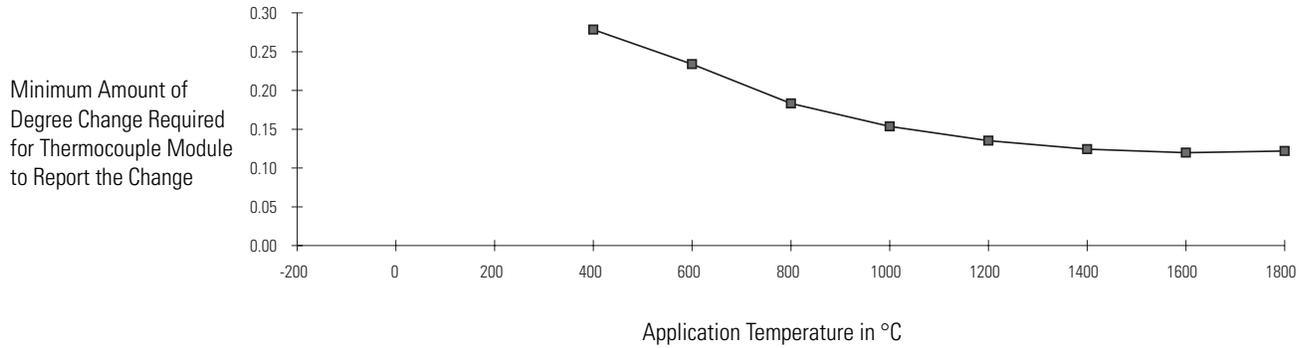


Figure E.26 Thermocouple Module Resolution - Type R Thermocouple Connection in a -12 to 78mV Input Range

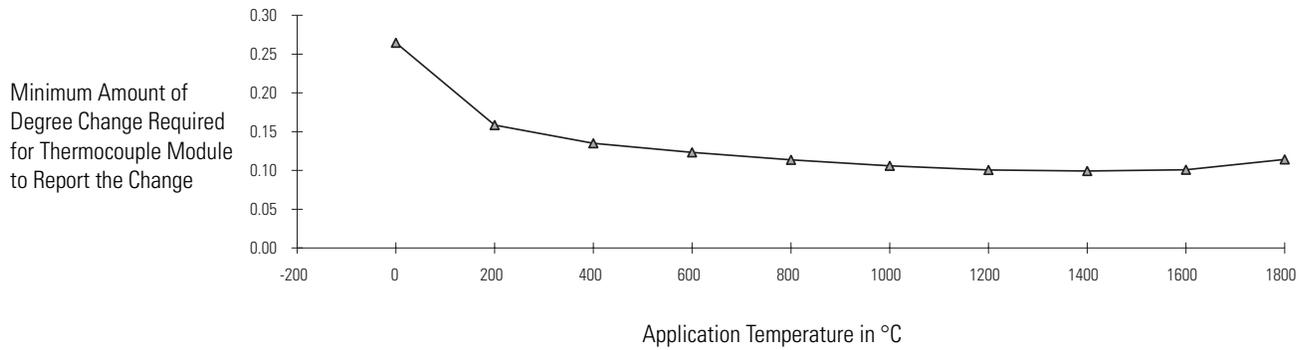


Figure E.27 Thermocouple Module Resolution - Type S Thermocouple Connection in a -12 to 78mV Input Range

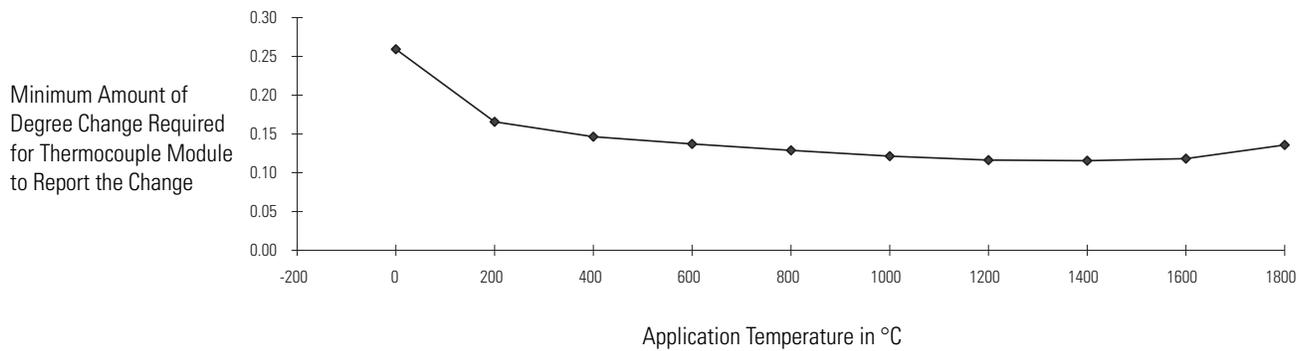


Figure E.28 Thermocouple Module Resolution - Type E Thermocouple Connection in a -12 to 78mV Input Range

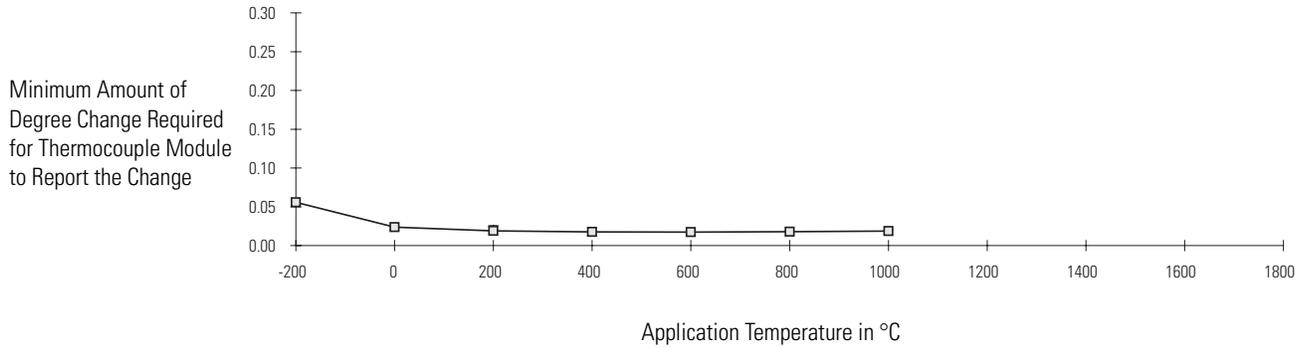


Figure E.29 Thermocouple Module Resolution - Type J Thermocouple Connection in a -12 to 78mV Input Range

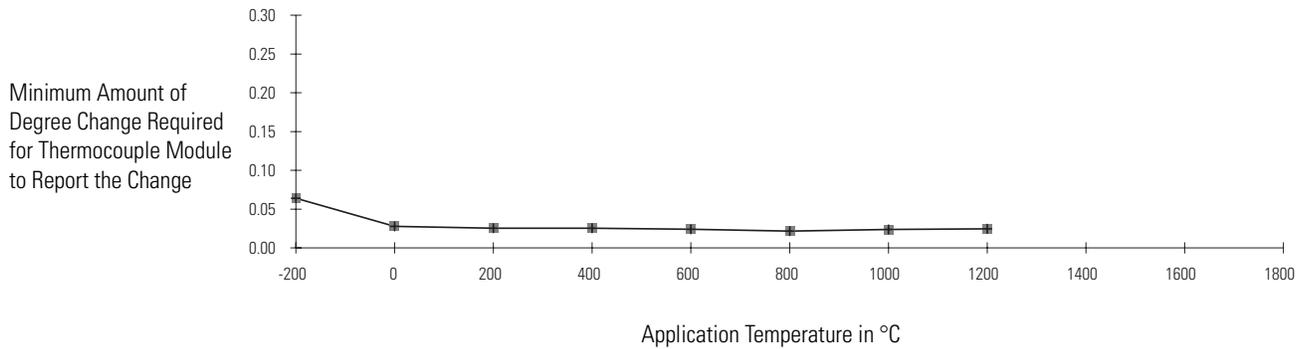


Figure E.30 Thermocouple Module Resolution - Type K Thermocouple Connection in a -12 to 78mV Input Range

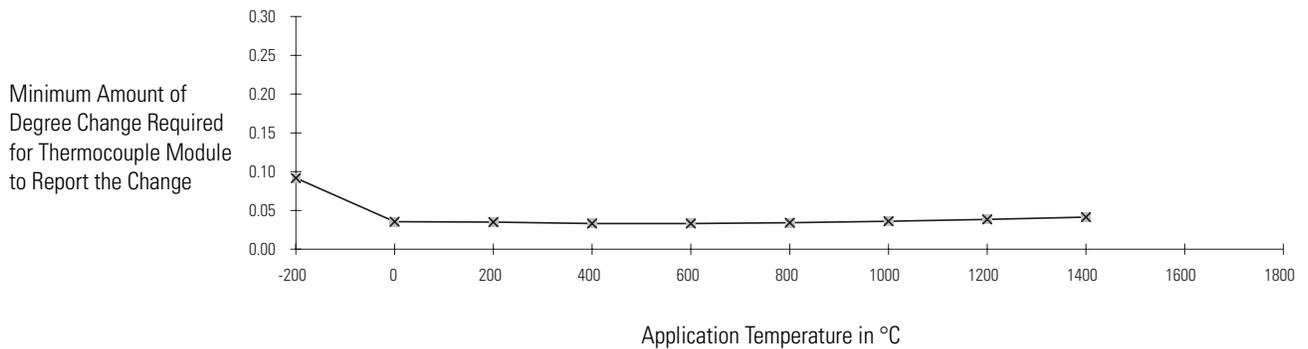


Figure E.31 Thermocouple Module Resolution - Type N Thermocouple Connection in a -12 to 78mV Input Range

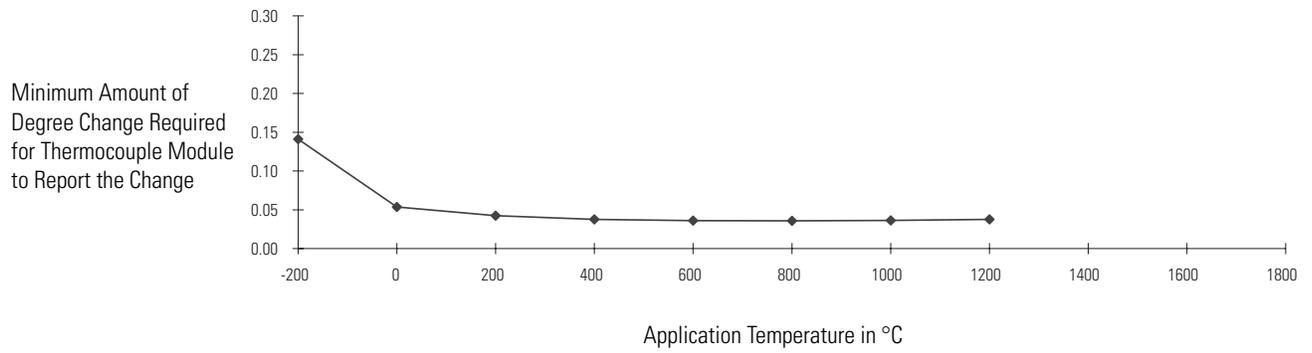
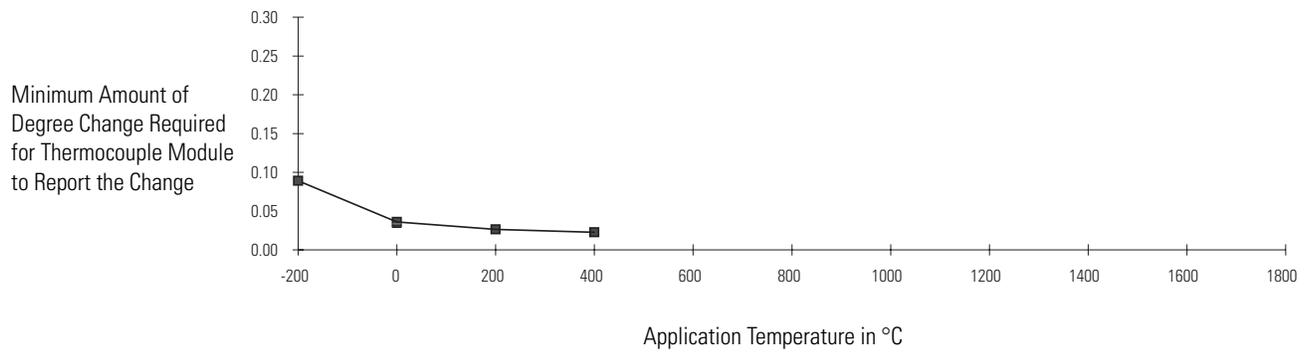


Figure E.32 Thermocouple Module Resolution - Type T Thermocouple Connection in a -12 to 78mV Input Range



Notes:

Using 1492 Wiring Systems with Your Analog I/O Module

As an alternative to buying RTBs and connecting the wires yourself, you can buy a wiring system of:

- **analog interface modules (AIFMs)** that mount on DIN rails provide the output terminal blocks for the I/O module. Use the AIFMs with the pre-wired cables that match the I/O module to the interface module.

For a complete list of the AIFMs available for use with ControlLogix analog I/O modules, see Table F.2 on page F-3.

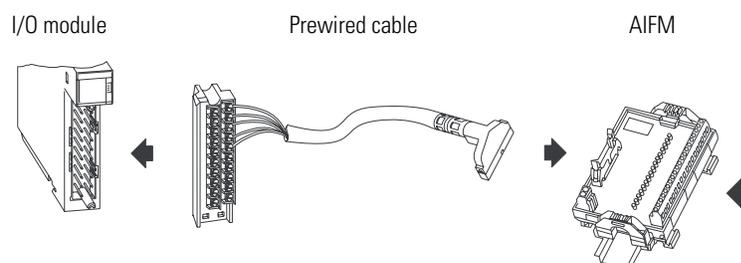
and

- **I/O-module-ready prewired cables.** One end of the cable assembly is an RTB that plugs into the front of the I/O module. The other end has individually color-coded conductors that connect to a standard terminal block.

For a complete list of the prewired cables available for use with ControlLogix analog I/O modules, see Table F.3 on page F-3.

Figure F.1 shows the AIFM and prewired cables.

Figure F.1



IMPORTANT

The 1492 IFMs may not be used in any application that requires agency certification of the ControlLogix system. Use of the IFM violates the UL, CSA and FM certifications of these products.

Table F.1 lists the AIFMs and prewired cables that can be used with specific ControlLogix analog I/O modules.

Table F.1

For this module:		Use this AIFM(s):⁽¹⁾	With this prewired cable:
1756-IF6CIS		1492-AIFM6S-3	1492-ACABLExX
1756-IF6I	in current mode	1492-AIFM6S-3	1492-ACABLExX
	in voltage mode	1492-AIFM6S-3	1492-ACABLExY
1756-IF8	in single-ended current mode	1492-AIFM8-3	1492-ACABLExTB
		1492-AIFM8-F-5	
	in single-ended voltage mode	1492-AIFM8-3	1492-ACABLExTA
		1492-AIFM8-F-5	
in differential current mode	1492-AIFM8-3 1492-AIFM8-F-5	1492-ACABLExTD	
in differential voltage mode	1492-AIFM8-3 1492-AIFM8-F-5	1492-ACABLExTC	
1756-IF16	in single-ended current mode	1492-AIFM8-3	1492-ACABLExUB
		1492-AIFM16-F-3	
		1492-AIFM16-F-5	
	in single-ended voltage mode	1492-AIFM8-3	1492-ACABLExUA
1492-AIFM16-F-3 1492-AIFM16-F-5			
in differential current mode	1492-AIFM8-3	1492-ACABLExUD	
	1492-AIFM16-F-3 1492-AIFM16-F-5		
in differential voltage mode	1492-AIFM8-3 1492-AIFM16-F-3 1492-AIFM16-F-5	1492-ACABLExUC	
1756-IR6I		1492-AIFM6S-3	1492-ACABLExZ
1756-IT6I		1492-AIFM6TC-3	1492-ACABLExY
1756-IT6I2		1492-AIFM6TC-3	1492-ACABLExYT
1756-OF4	in current mode	1492-AIFM4-3	1492-ACABLExVB
	in voltage mode	1492-AIFM4-3	1492-ACABLExVA
1756-OF6CI		1492-AIFM6S-3	1492-ACABLExY
1756-OF6VI		1492-AIFM6S-3	1492-ACABLExY
1756-OF8	in current mode	1492-AIFM8-3	1492-ACABLExWB
	in voltage mode	1492-AIFM8-3	1492-ACABLExWA

⁽¹⁾ When multiple AIFMs are listed for a catalog number, both fit the application listed. For example, when using the 1756-IF8 in single-ended current mode, you can use either the 1492-AIFM8-3 or 1492-AIFM8-F-5.

Table F.2 describes the AIFMs available for use with your ControlLogix analog I/O modules.

Table F.2

Catalog Number	Type of AIFM:	Description:
1492-AIFM4-3	feed through	4 channels with 3 terminals per channel
1492-AIFM6S-3	feed through	6 channels isolated with 3-4 terminals per channel
1492-AIFM8-3	feed through	8 channels with 3 terminals per channel
1492-AIFM6TC-3	thermocouple	6 channels with 3 terminals per channel
1492-AIFM8-F-5	fusible	8 channels with 5 terminals per channel
1492-AIFM16-F-3	fusible	16 channels with 3 terminals per channel
1492-AIFM16-F-5	fusible	16 channels with 5 terminals per channel

Table F.3 describes the I/O module-ready prewired cables available for use with your ControlLogix analog I/O modules.

Table F.3 t

Catalog Number:⁽¹⁾	Number of Conductors:⁽²⁾	Conductor Size:	Nominal Outer Diameter:	RTB at the I/O Module End:
1492-ACABLExM	11 twisted pairs	22 AWG	11.5 mm (0.45 in)	1757-PIM
1492-ACABLExX	9 twisted pairs ⁽³⁾	22 AWG	6.8 mm (0.27 in)	1756-TBNH
1492-ACABLExY	9 twisted pairs ⁽⁴⁾	22 AWG	6.8 mm (0.27 in)	1756-TBNH
1492-ACABLExZ	20 conductors ⁽⁵⁾	22 AWG	8.4 mm (0.33 in)	1756-TBNH
1492-ACABLExTA	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExTB	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExTC	5 twisted pairs	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExTD	5 twisted pairs	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExUA	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExUB	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBCH
1492-ACABLExUC	9 twisted pairs	22 AWG	6.8 mm (0.27 in)	1756-TBCH
1492-ACABLExUD	9 twisted pairs	22 AWG	6.8 mm (0.27 in)	1756-TBCH
1492-ACABLExVA	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBNH
1492-ACABLExVB	20 conductors	22 AWG	8.4 mm (0.33 in)	1756-TBNH
1492-ACABLExWA	9 twisted pairs	22 AWG	6.8 mm (0.27 in)	1756-TBNH
1492-ACABLExWB	9 twisted pairs	22 AWG	6.8 mm (0.27 in)	1756-TBNH

⁽¹⁾ Cables are available in lengths of 0.5m, 1.0m, 2.5m, and 5.0m. To order, insert the code for the desired cable length into the catalog number in place of the x: 005=0.5m, 010=1.0m, 25=2.5m, 050=5m. Build-to-order cable lengths are also available.

⁽²⁾ Each cable for analog I/O has an overall shield with a ring lug on a 200mm (8.87 in) exposed drain wire at the I/O module end of the cable.

⁽³⁾ One pair is not connected to the I/O module connector; two additional pairs are not used.

⁽⁴⁾ Two pairs are not used.

⁽⁵⁾ One conductor is not connected to the I/O module connector; one additional conductor is not used.

■ Notes:

Broadcast

Data transmissions to all addresses

Communications format

Format that defines the type of information transferred between an I/O module and its owner-controller. This format also defines the tags created for each I/O module.

On the 1756-IF16 and 1756-IF8 modules, the communications format must match module wiring.

Compatible match

An electronic keying protection mode that requires the physical module and the module configured in the software to match according to vendor, catalog number and major revision. In this case, the minor revision of the module must be greater than or equal to that of the configured slot.

Connection

The continuous communication mechanism from the controller to an I/O module in the control system

ControlBus

The backplane used by the 1756 chassis

Coordinated System Time (CST)

Timer value which is kept synchronized for all modules within a single ControlBus chassis. The CST is a 64-bit number with microsecond resolution.

Direct Connection

An I/O connection where the controller establishes an individual connection with I/O modules

Disable keying

An option that turns off all electronic keying to the module. Requires no attributes of the physical module and the module configured in the software to match.

Download

The process of transferring the contents of a project on the workstation into the controller

Electronic keying

A system feature which makes sure that the physical module attributes are consistent with what was configured in the software

Exact match

An electronic keying protection mode that requires the physical module and the module configured in the software to match identically, according to vendor, catalog number, major revision and minor revision

Field side

Interface between user field wiring and I/O module

Inhibit

A ControlLogix process that allows you to configure an I/O module but prevent it from communicating with the owner-controller. In this case, the controller does not establish a connection

Interface module (IFM)

A prewired removable terminal block (RTB)

Listen-only connection

An I/O connection that allows a controller to monitor I/O module data without owning the module

Major revision

A module revision that is updated any time there is a functional change to the module resulting in an interface change with software

Minor revision

A module revision that is updated any time there is a change to the module that does not affect its function or software user interface (e.g. bug fix)

Multicast

Data transmissions which reach a specific group of one or more destinations

Multiple owners

A configuration set-up where multiple owner-controllers use exactly the same configuration information to simultaneously own an input module

Network update time (NUT)

The smallest repetitive time interval in which the data can be sent on a ControlNet network. The NUT may be configured over the range from 2ms to 100ms using RSNetWorx

Owner-controller

The controller that creates and stores the primary configuration and communication connection to a module

Program mode

In this mode, the controller program is not executing. Inputs are actively producing data. Outputs are not actively controlled and go to their configured program mode state.

Remote connection

An I/O connection where the controller establishes an individual connection with I/O modules in a remote chassis

Removable terminal block (RTB)

Field wiring connector for I/O modules

Removal and insertion under power (RIUP)

ControlLogix feature that allows a user to install or remove a module or RTB while power is applied

Requested packet interval (RPI)

A configurable parameter which defines when the module will multicast data

Run mode

In this mode, the controller program is executing. Inputs are actively producing data. Outputs are actively controlled.

Service

A system feature that is performed on user demand

System side

Backplane side of the interface to the I/O module

Tag

A named area of the controller's memory where data is stored like a variable

Timestamping

ControlLogix process that stamps a change in input, output, or diagnostic data with a time reference indicating when that change occurred

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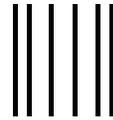
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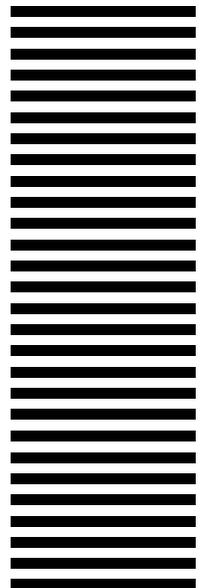
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